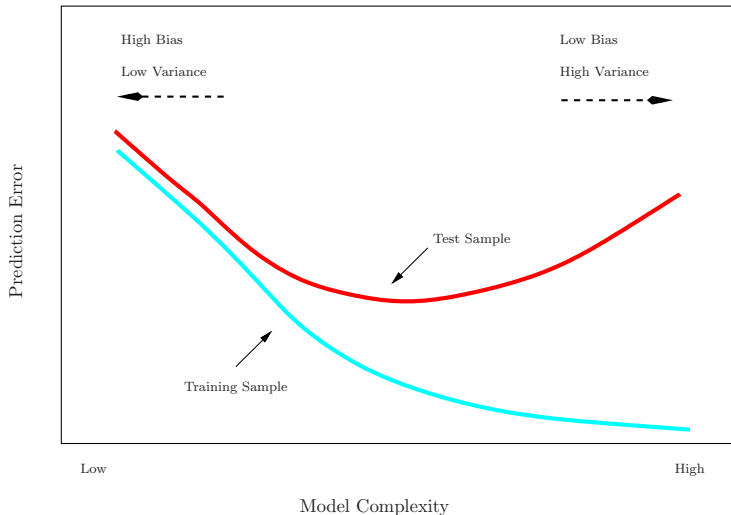


Training- versus Test-Set Performance



More on prediction-error estimates

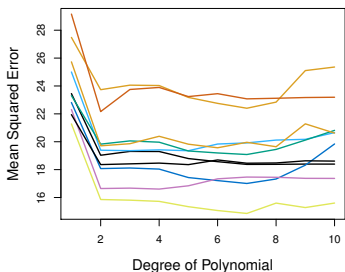
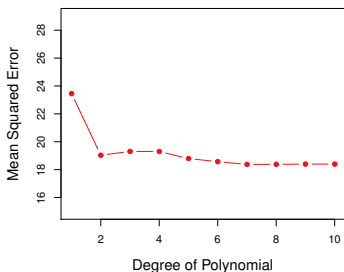
- Best solution: a large designated test set. Often not available
- Some methods make a *mathematical adjustment* to the training error rate in order to estimate the test error rate. These include the *C_p statistic*, *AIC* and *BIC*. They are discussed elsewhere in this course
- Here we instead consider a class of methods that estimate the test error by *holding out* a subset of the training observations from the fitting process, and then applying the statistical learning method to those held out observations

Validation-set approach

- Here we randomly divide the available set of samples into two parts: a *training set* and a *validation* or *hold-out set*.
- The model is fit on the training set, and the fitted model is used to predict the responses for the observations in the validation set.
- The resulting validation-set error provides an estimate of the test error. This is typically assessed using MSE in the case of a quantitative response and misclassification rate in the case of a qualitative (discrete) response.

Example: automobile data

- Want to compare linear vs higher-order polynomial terms in a linear regression
- We randomly split the 392 observations into two sets, a training set containing 196 of the data points, and a validation set containing the remaining 196 observations.



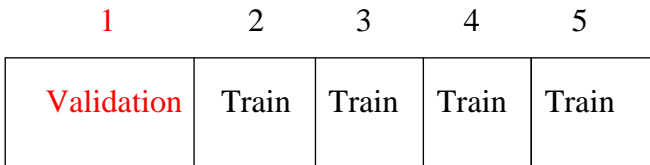
Left panel shows single split; right panel shows multiple splits

K -fold Cross-validation

- *Widely used approach* for estimating test error.
- Estimates can be used to select best model, and to give an idea of the test error of the final chosen model.
- Idea is to randomly divide the data into K equal-sized parts. We leave out part k , fit the model to the other $K - 1$ parts (combined), and then obtain predictions for the left-out k th part.
- This is done in turn for each part $k = 1, 2, \dots, K$, and then the results are combined.

K -fold Cross-validation in detail

Divide data into K roughly equal-sized parts ($K = 5$ here)



The details

- Let the K parts be C_1, C_2, \dots, C_K , where C_k denotes the indices of the observations in part k . There are n_k observations in part k : if N is a multiple of K , then $n_k = n/K$.

- Compute

$$CV_{(K)} = \sum_{k=1}^K \frac{n_k}{n} \text{MSE}_k$$

where $\text{MSE}_k = \sum_{i \in C_k} (y_i - \hat{y}_i)^2 / n_k$, and \hat{y}_i is the fit for observation i , obtained from the data with part k removed.

- Setting $K = n$ yields n -fold or *leave-one out cross-validation* (LOOCV).

A nice special case!

- With least-squares linear or polynomial regression, an amazing shortcut makes the cost of LOOCV the same as that of a single model fit! The following formula holds:

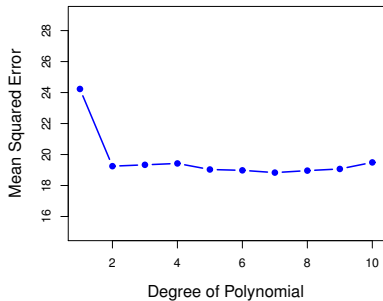
$$CV_{(n)} = \frac{1}{n} \sum_{i=1}^n \left(\frac{y_i - \hat{y}_i}{1 - h_i} \right)^2,$$

where \hat{y}_i is the i th fitted value from the original least squares fit, and h_i is the leverage (diagonal of the “hat” matrix; see book for details.) This is like the ordinary MSE, except the i th residual is divided by $1 - h_i$.

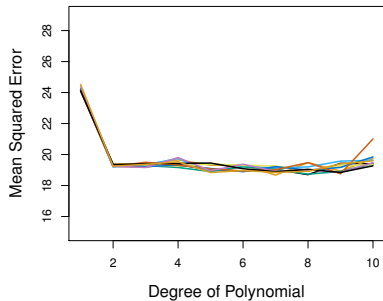
- LOOCV sometimes useful, but typically doesn't *shake up* the data enough. The estimates from each fold are highly correlated and hence their average can have high variance.
- a better choice is $K = 5$ or 10 .

Auto data revisited

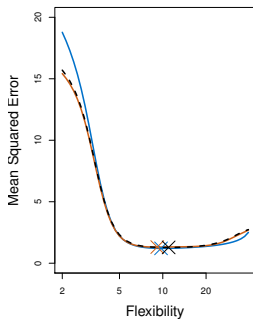
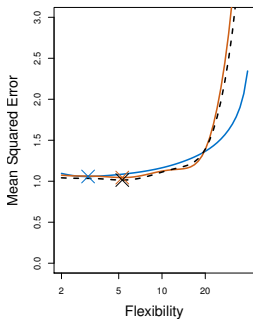
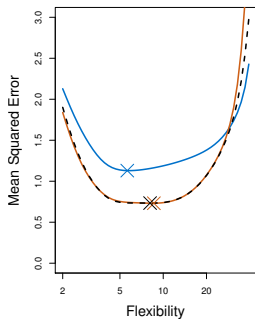
LOOCV



10-fold CV



True and estimated test MSE for the simulated data



Other issues with Cross-validation

- Since each training set is only $(K - 1)/K$ as big as the original training set, the estimates of prediction error will typically be biased upward. *Why?*
- This bias is minimized when $K = n$ (LOOCV), but this estimate has high variance, as noted earlier.
- $K = 5$ or 10 provides a good compromise for this bias-variance tradeoff.

Cross-Validation for Classification Problems

- We divide the data into K roughly equal-sized parts C_1, C_2, \dots, C_K . C_k denotes the indices of the observations in part k . There are n_k observations in part k : if n is a multiple of K , then $n_k = n/K$.
- Compute

$$\text{CV}_K = \sum_{k=1}^K \frac{n_k}{n} \text{Err}_k$$

where $\text{Err}_k = \sum_{i \in C_k} I(y_i \neq \hat{y}_i) / n_k$.

- The estimated standard deviation of CV_K is

$$\widehat{\text{SE}}(\text{CV}_K) = \sqrt{\sum_{k=1}^K (\text{Err}_k - \overline{\text{Err}_k})^2 / (K - 1)}$$

- This is a useful estimate, but strictly speaking, not quite valid.

The Bootstrap

- The *bootstrap* is a flexible and powerful statistical tool that can be used to quantify the uncertainty associated with a given estimator or statistical learning method.
- For example, it can provide an estimate of the standard error of a coefficient, or a confidence interval for that coefficient.

A simple example

- Suppose that we wish to invest a fixed sum of money in two financial assets that yield returns of X and Y , respectively, where X and Y are random quantities.
- We will invest a fraction α of our money in X , and will invest the remaining $1 - \alpha$ in Y .
- We wish to choose α to minimize the total risk, or variance, of our investment. In other words, we want to minimize $\text{Var}(\alpha X + (1 - \alpha)Y)$.
- One can show that the value that minimizes the risk is given by

$$\alpha = \frac{\sigma_Y^2 - \sigma_{XY}}{\sigma_X^2 + \sigma_Y^2 - 2\sigma_{XY}},$$

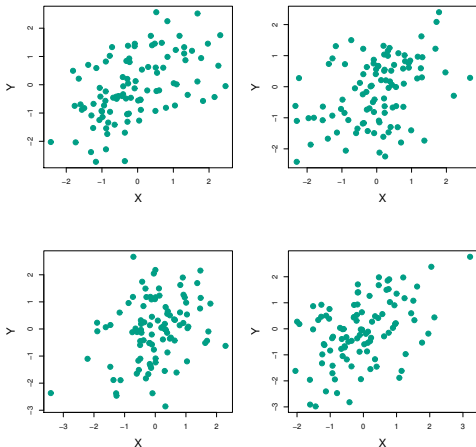
where $\sigma_X^2 = \text{Var}(X)$, $\sigma_Y^2 = \text{Var}(Y)$, and $\sigma_{XY} = \text{Cov}(X, Y)$.

Example continued

- But the values of σ_X^2 , σ_Y^2 , and σ_{XY} are unknown.
- We can compute estimates for these quantities, $\hat{\sigma}_X^2$, $\hat{\sigma}_Y^2$, and $\hat{\sigma}_{XY}$, using a data set that contains measurements for X and Y .
- We can then estimate the value of α that minimizes the variance of our investment using

$$\hat{\alpha} = \frac{\hat{\sigma}_Y^2 - \hat{\sigma}_{XY}}{\hat{\sigma}_X^2 + \hat{\sigma}_Y^2 - 2\hat{\sigma}_{XY}}.$$

Example continued



Each panel displays 100 simulated returns for investments X and Y . From left to right and top to bottom, the resulting estimates for α are 0.576, 0.532, 0.657, and 0.651.

Example continued

- To estimate the standard deviation of $\hat{\alpha}$, we repeated the process of simulating 100 paired observations of X and Y , and estimating α 1,000 times.
- We thereby obtained 1,000 estimates for α , which we can call $\hat{\alpha}_1, \hat{\alpha}_2, \dots, \hat{\alpha}_{1000}$.

Example continued

- The mean over all 1,000 estimates for α is

$$\bar{\alpha} = \frac{1}{1000} \sum_{r=1}^{1000} \hat{\alpha}_r = 0.5996,$$

very close to $\alpha = 0.6$, and the standard deviation of the estimates is

$$\sqrt{\frac{1}{1000 - 1} \sum_{r=1}^{1000} (\hat{\alpha}_r - \bar{\alpha})^2} = 0.083.$$

- This gives us a very good idea of the accuracy of $\hat{\alpha}$: $\text{SE}(\hat{\alpha}) \approx 0.083$.
- So roughly speaking, for a random sample from the population, we would expect $\hat{\alpha}$ to differ from α by approximately 0.08, on average.

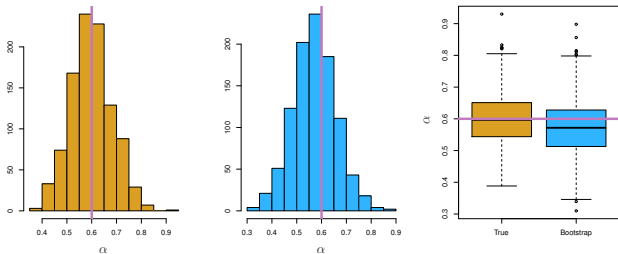
Now back to the real world

- the bootstrap approach allows us to use a computer to mimic the process of obtaining new data sets, so that we can estimate the variability of our estimate without generating additional samples.
- Rather than repeatedly obtaining independent data sets from the population, we instead obtain distinct data sets by repeatedly sampling observations from the original data set *with replacement*.

- Denoting the first bootstrap data set by Z^{*1} , we use Z^{*1} to produce a new bootstrap estimate for α , which we call $\hat{\alpha}^{*1}$
- This procedure is repeated B times for some large value of B (say 100 or 1000), in order to produce B different bootstrap data sets
- We estimate the standard error of these bootstrap estimates using the formula

$$\text{SE}_B(\hat{\alpha}) = \sqrt{\frac{1}{B-1} \sum_{r=1}^B (\hat{\alpha}^{*r} - \bar{\hat{\alpha}}^*)^2}.$$

Results



Left: A histogram of the estimates of α obtained by generating 1,000 simulated data sets from the true population. *Center:* A histogram of the estimates of α obtained from 1,000 bootstrap samples from a single data set. *Right:* The estimates of α displayed in the left and center panels are shown as boxplots. In each panel, the pink line indicates the true value of α .

The bootstrap in general

- In more complex data situations, figuring out the appropriate way to generate bootstrap samples can require some thought.
- For example, if the data is a time series, we can't simply sample the observations with replacement (*why not?*).
- We can instead create blocks of consecutive observations, and sample those with replacements. Then we paste together sampled blocks to obtain a bootstrap dataset.

Other uses of the bootstrap

- Primarily used to obtain standard errors of an estimate.
- Also provides approximate confidence intervals for a population parameter. For example, looking at the histogram in the middle panel of the Figure on slide 29, the 5% and 95% quantiles of the 1000 values is (.43, .72).
- This represents an approximate 90% confidence interval for the true α . *How do we interpret this confidence interval?*
- The above interval is called a *Bootstrap Percentile* confidence interval. It is the simplest method (among many approaches) for obtaining a confidence interval from the bootstrap.