

Matrices to Simplify Regression Notation

$$\begin{array}{l}
 Y_1 = \beta_0 + \beta_1 x_1 + \varepsilon_1 \\
 Y_2 = \beta_0 + \beta_1 x_2 + \varepsilon_2 \\
 \vdots \\
 Y_n = \beta_0 + \beta_1 x_n + \varepsilon_n
 \end{array}
 \quad
 \begin{array}{l}
 \begin{pmatrix} Y_1 \\ Y_2 \\ \vdots \\ Y_n \end{pmatrix} \\
 \underline{Y}
 \end{array}
 =
 \begin{array}{l}
 \begin{pmatrix} 1 & X_1 \\ 1 & X_2 \\ \vdots & \vdots \\ 1 & X_n \end{pmatrix} \\
 \underline{X}
 \end{array}
 \begin{array}{l}
 \begin{pmatrix} \beta_0 \\ \beta_1 \end{pmatrix} \\
 \underline{\beta}
 \end{array}
 +
 \begin{array}{l}
 \begin{pmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_n \end{pmatrix} \\
 \underline{\varepsilon}
 \end{array}$$

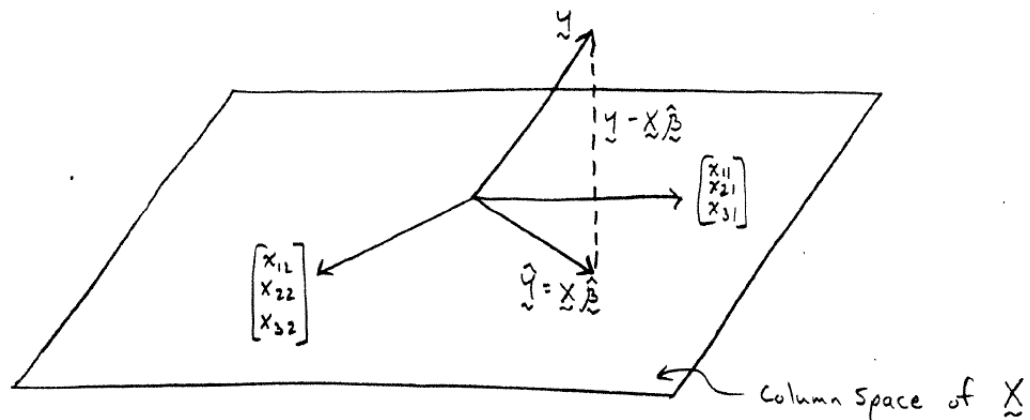
- Least Squares Estimates: $\hat{\underline{\beta}} = (\hat{\beta}_0, \hat{\beta}_1)'$ chosen to minimize SSE

$$\circ \underline{Y} = \underline{X} \underline{\beta} + \underline{\varepsilon} \rightarrow \underline{\varepsilon} = \underline{Y} - \hat{\underline{Y}} = \underline{Y} - \underline{X} \hat{\underline{\beta}} \rightarrow \underline{\varepsilon}' \underline{\varepsilon} = \varepsilon_1^2 + \varepsilon_2^2 + \dots + \varepsilon_n^2 = SSE$$

$$\circ \hat{\underline{\beta}} = (\hat{\beta}_0, \hat{\beta}_1)' = (\underline{X}' \underline{X})^{-1} \underline{X}' \underline{Y}$$

- Geometry of LSEs:

$$\text{Let } \underline{X}_{3 \times 2} = \begin{bmatrix} x_{11} & x_{12} \\ x_{21} & x_{22} \\ x_{31} & x_{32} \end{bmatrix} \quad \text{and} \quad \underline{y} = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}$$



Properties of Residuals

1. $\sum e_i = 0$

2. $\frac{\sum e_i^2}{n-(p+1)} = \text{MSE} = s^2 = \hat{\sigma}^2$

3. Same scale as the y_i observations

4. Normalized residuals are scale independent

Normalized Residuals

$$r_i = \frac{e_i - 0}{s \sqrt{1-h_{ii}}}$$

Text
"Standardized"

R
`rstandard()`

AKA.
internally studentized

$$r_{(-i)} = \frac{e_i - 0}{s_{(-i)} \sqrt{1-h_{ii}}}$$

"jackknife"

`rstudent()`

externally studentized

- $s_{(-i)}$ is the MSE computed if we leave out the i^{th} observation

Testing for outliers (in the y -direction)

- $r_{(-i)}$ is better modeled by a T -distribution than r_i
- H_0 : $r_{(-i)}$ is not from an outlier

Cook's Distance

- Measures the average standardized distance between $\hat{\beta}$ and $\hat{\beta}_{(-i)}$
- Measures influence in both the X and Y direction

$$D_i = \left(\frac{r_i^2}{p+1} \right) \left(\frac{h_{ii}}{1-h_{ii}} \right)$$

- If the model is correct then $D_i \sim F_{p, n-(p+1)}$

Transformations and Tukey's "Rule of the Bulge"

- Observe which way the curve bulges as suggested by a scatterplot of the data
- Transform y or x (or both) according to the signs of the corresponding quadrant:
up → powers >1
down → powers <1 (including logarithm)

