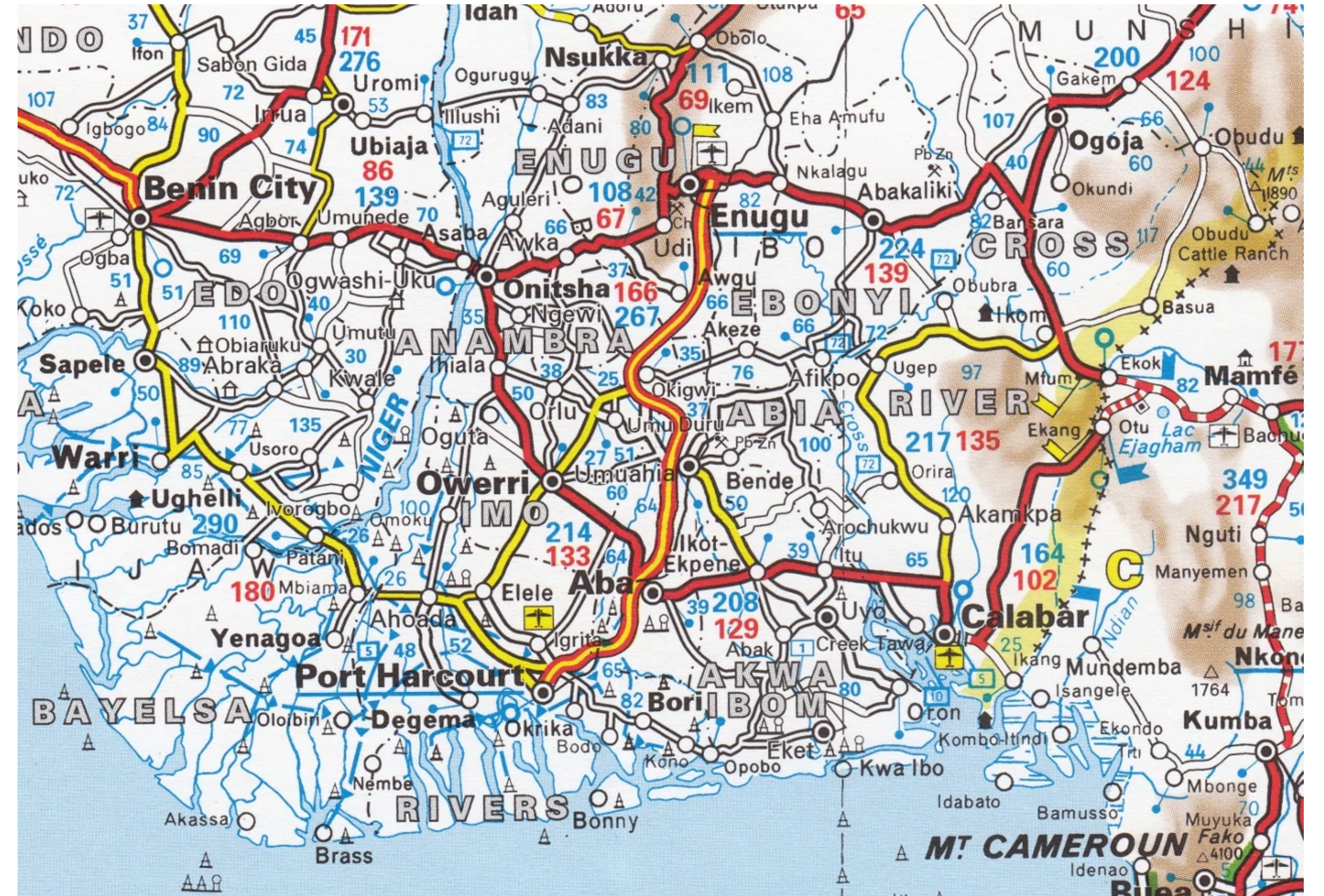




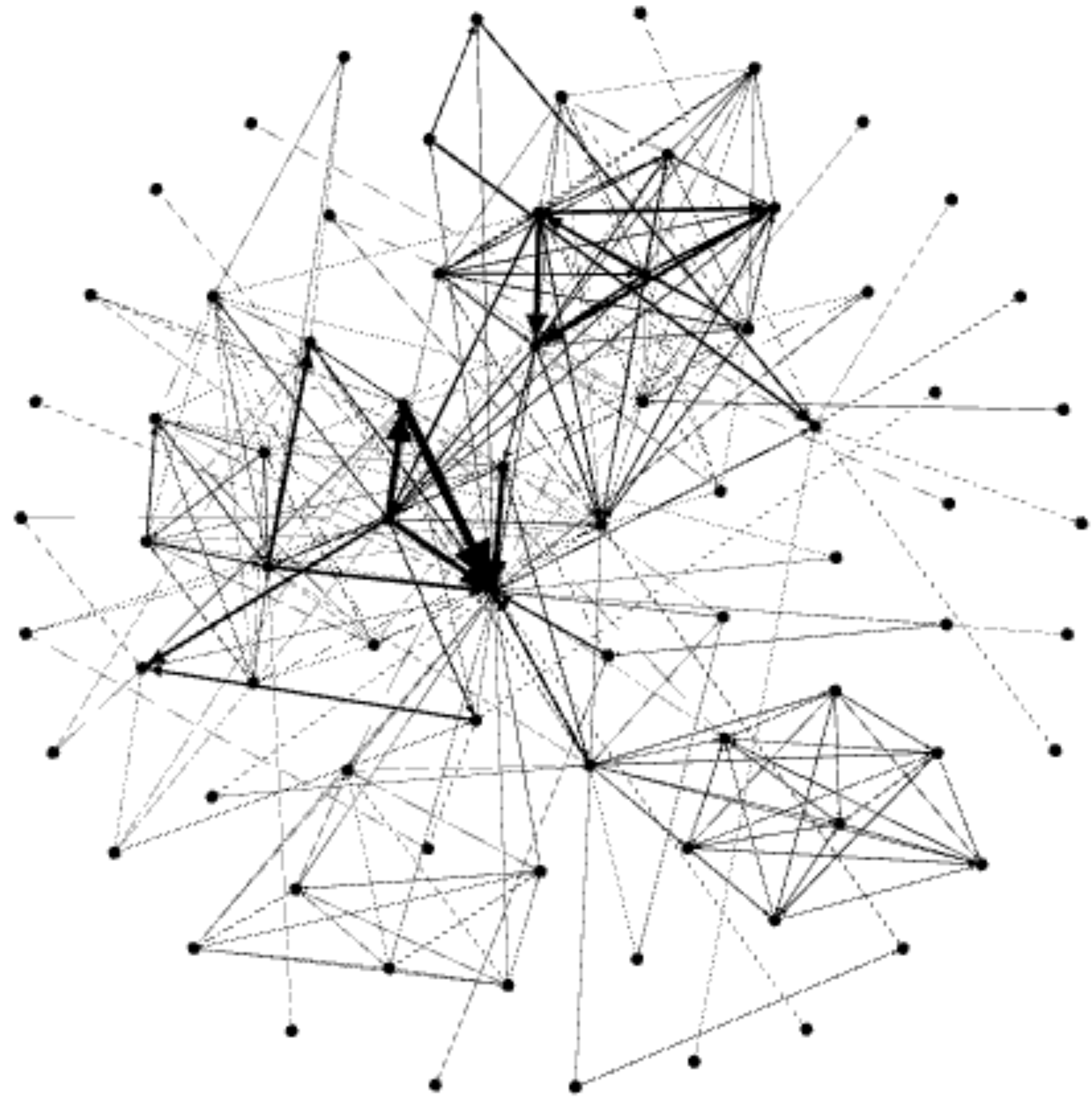
THE UNIVERSITY OF VERMONT  
COLLEGE OF ENGINEERING &  
MATHEMATICAL SCIENCES

# Shortest Path



# Shortest path

- Vehicle routing
- Network design
- Telecommunications
- Optimization

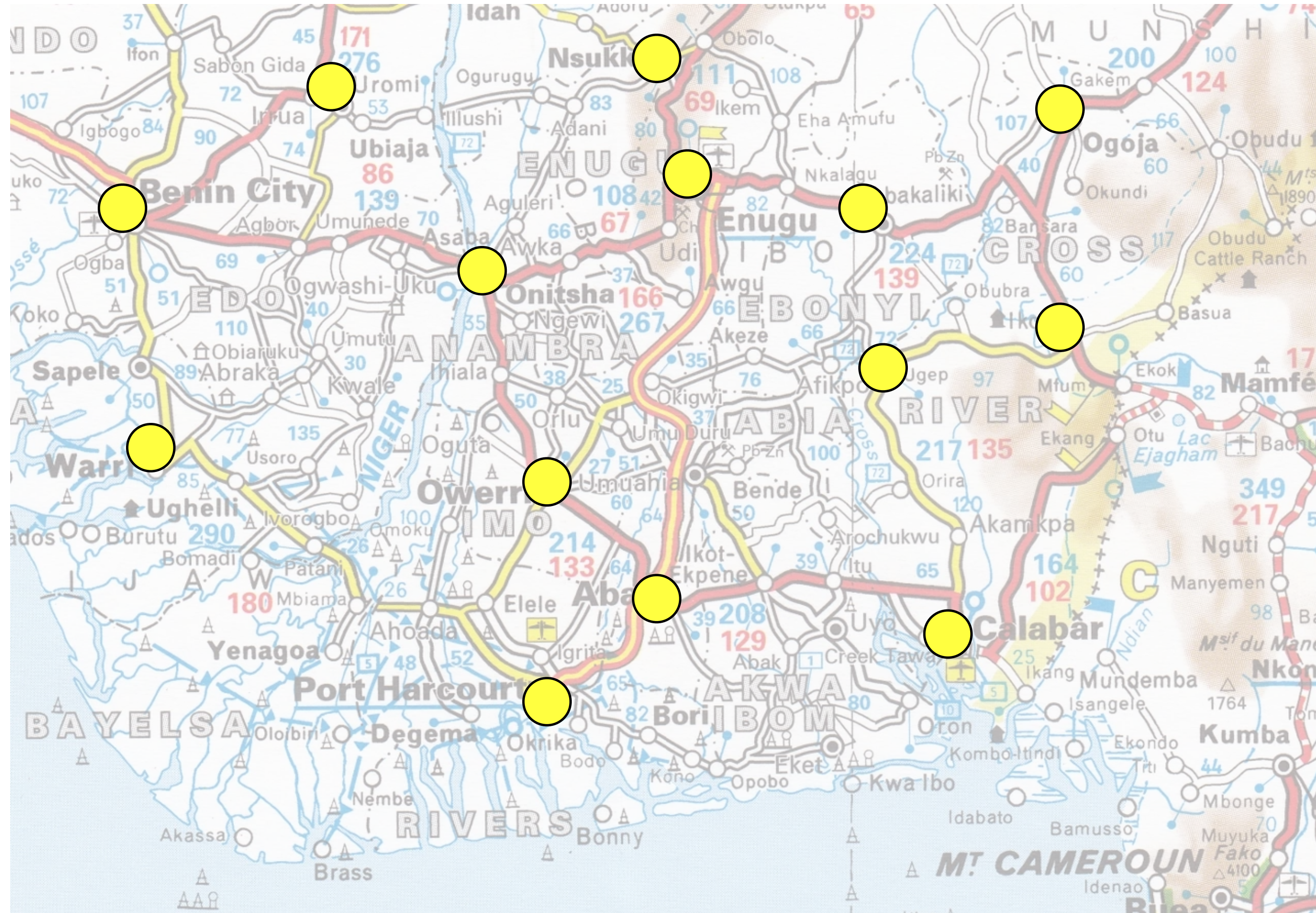


Weighted network of characters in Victor Hugo's *Les Misérables*, from the Stanford GraphBase, Knuth, 1993. Image generated with Gephi.

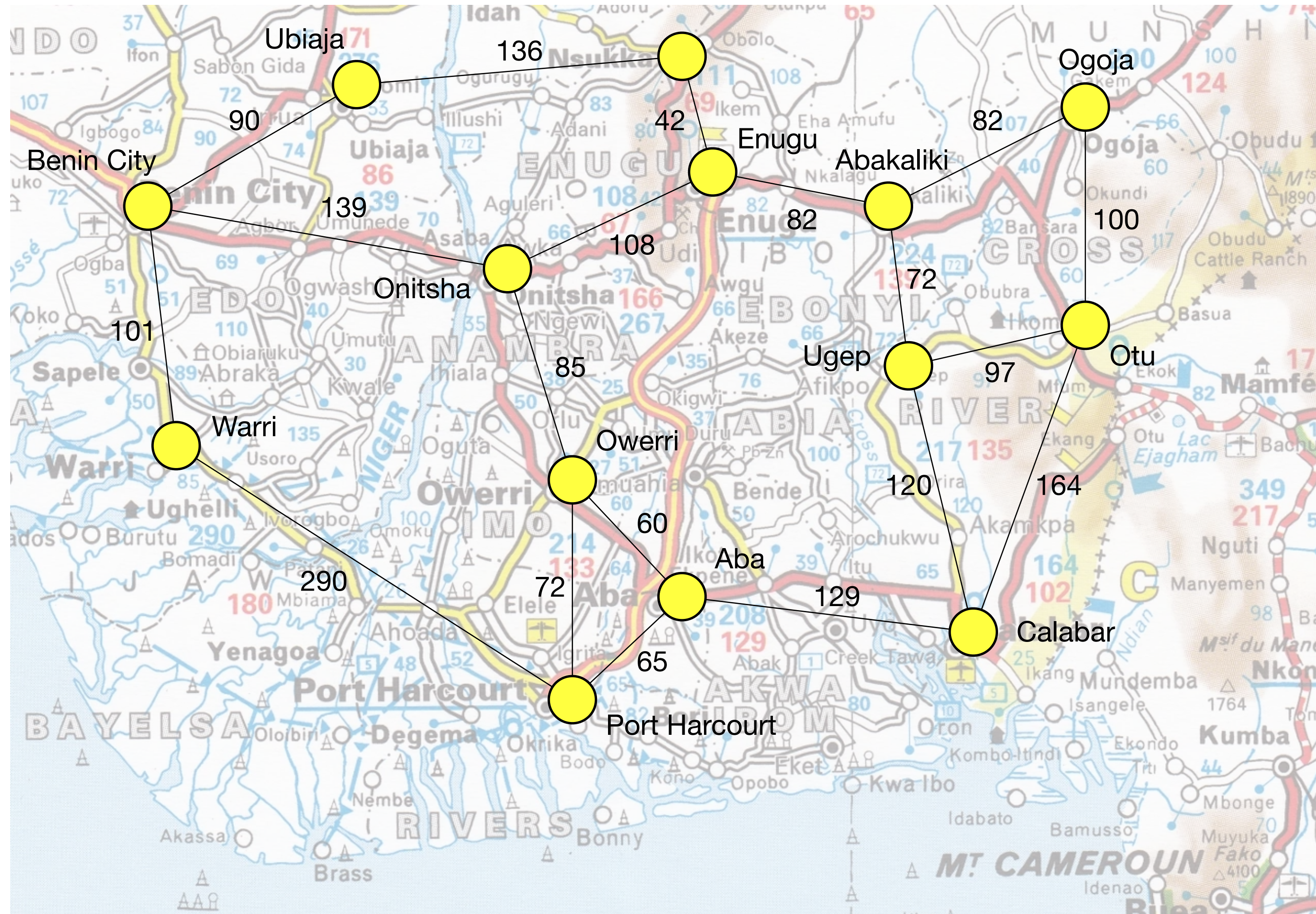
# Shortest path



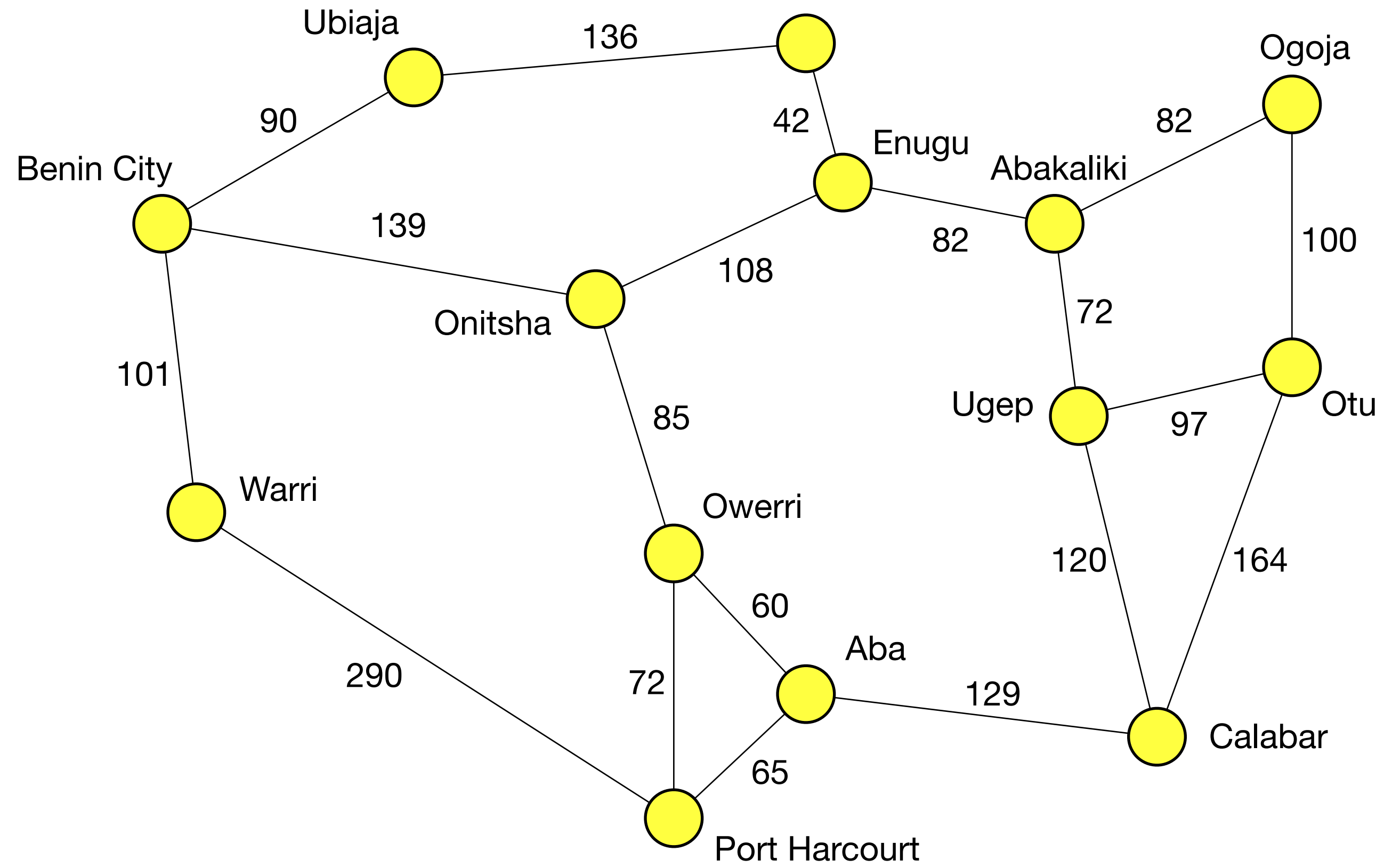
# Shortest path



# Shortest path



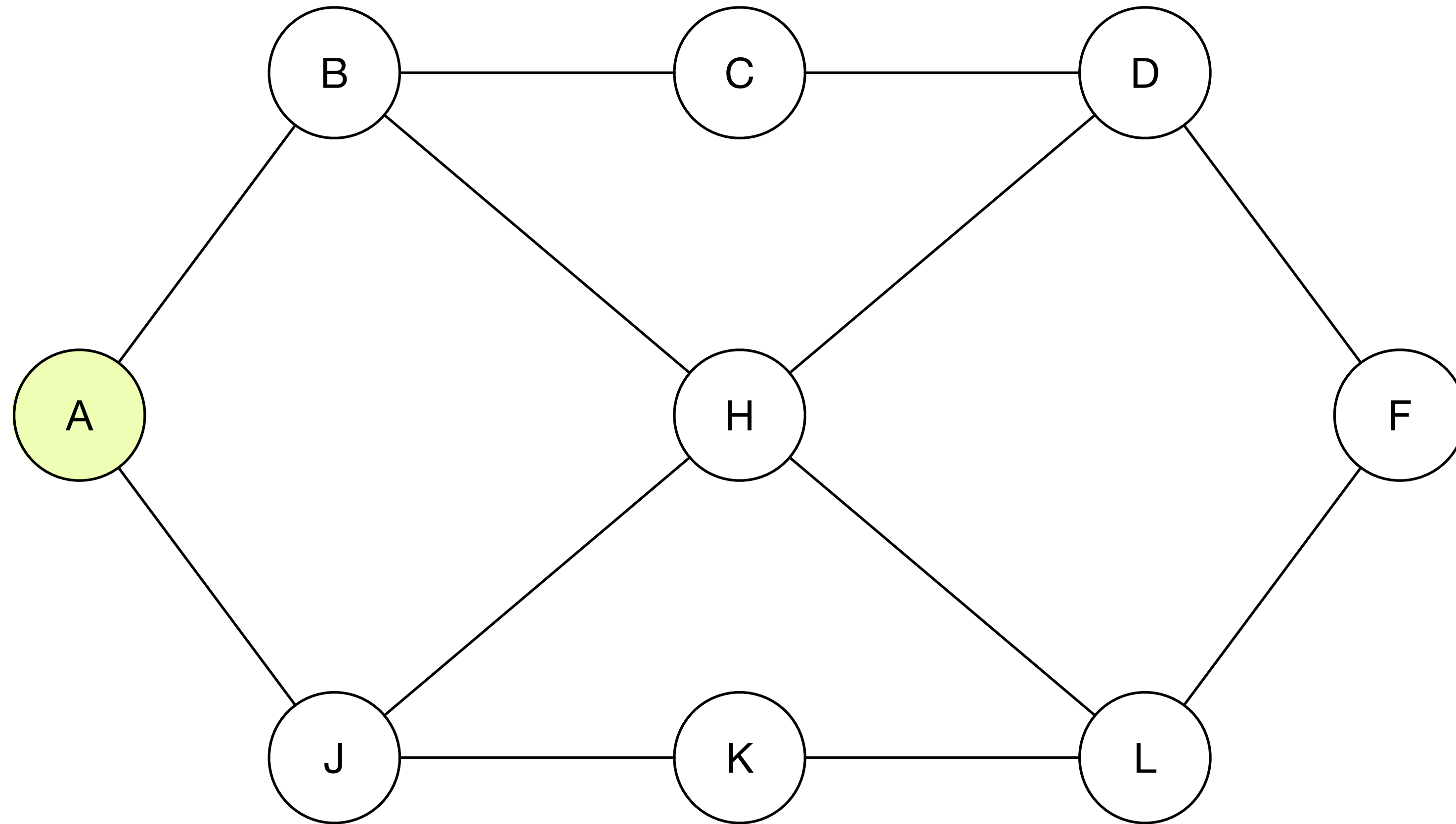
# Shortest path



# Shortest path

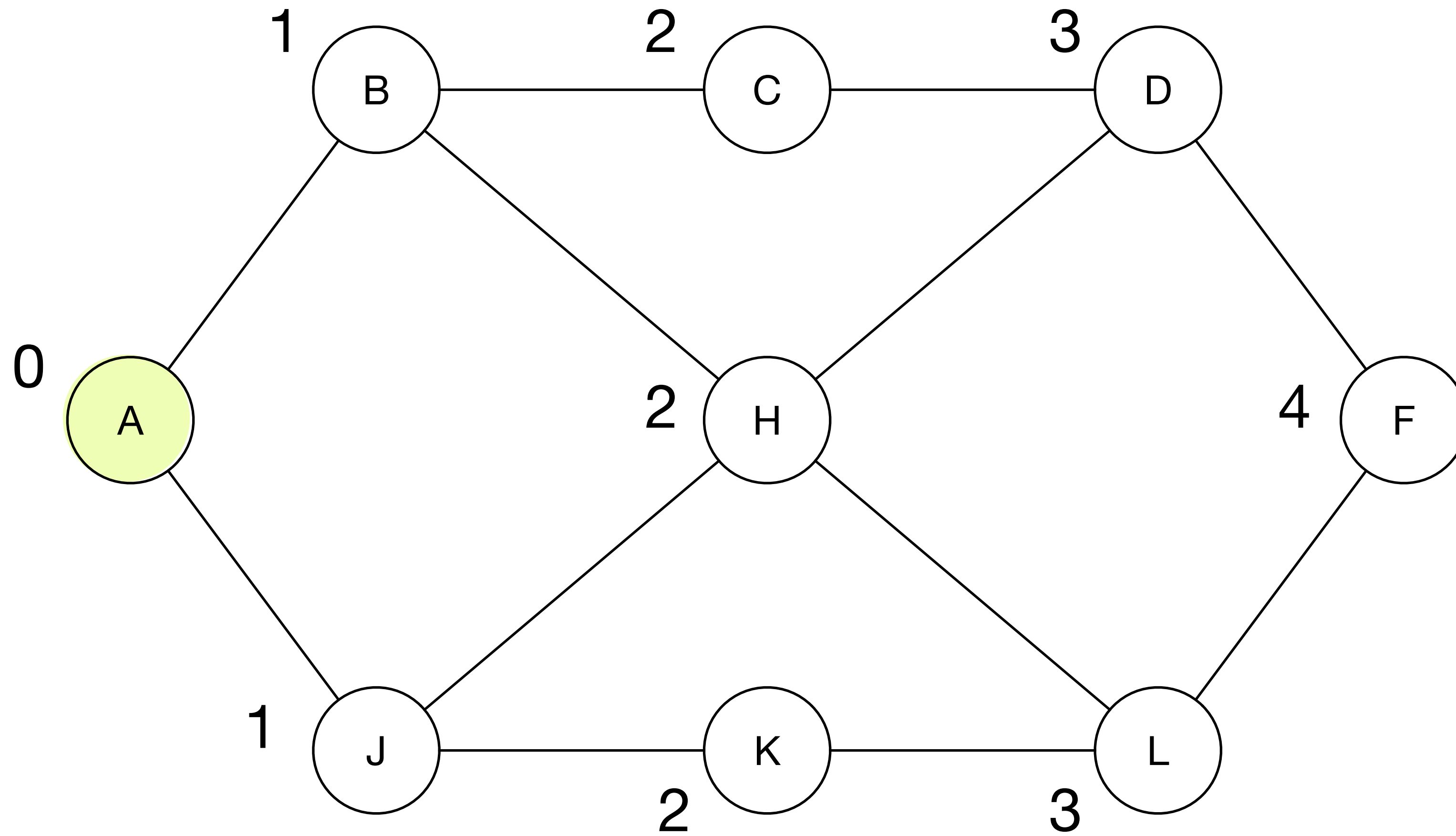
- Shortest paths from some node  $V_0$  to all other nodes
- Shortest path from some node  $V_0$  to one other node,  $V_1$

# Shortest path, undirected, unweighted

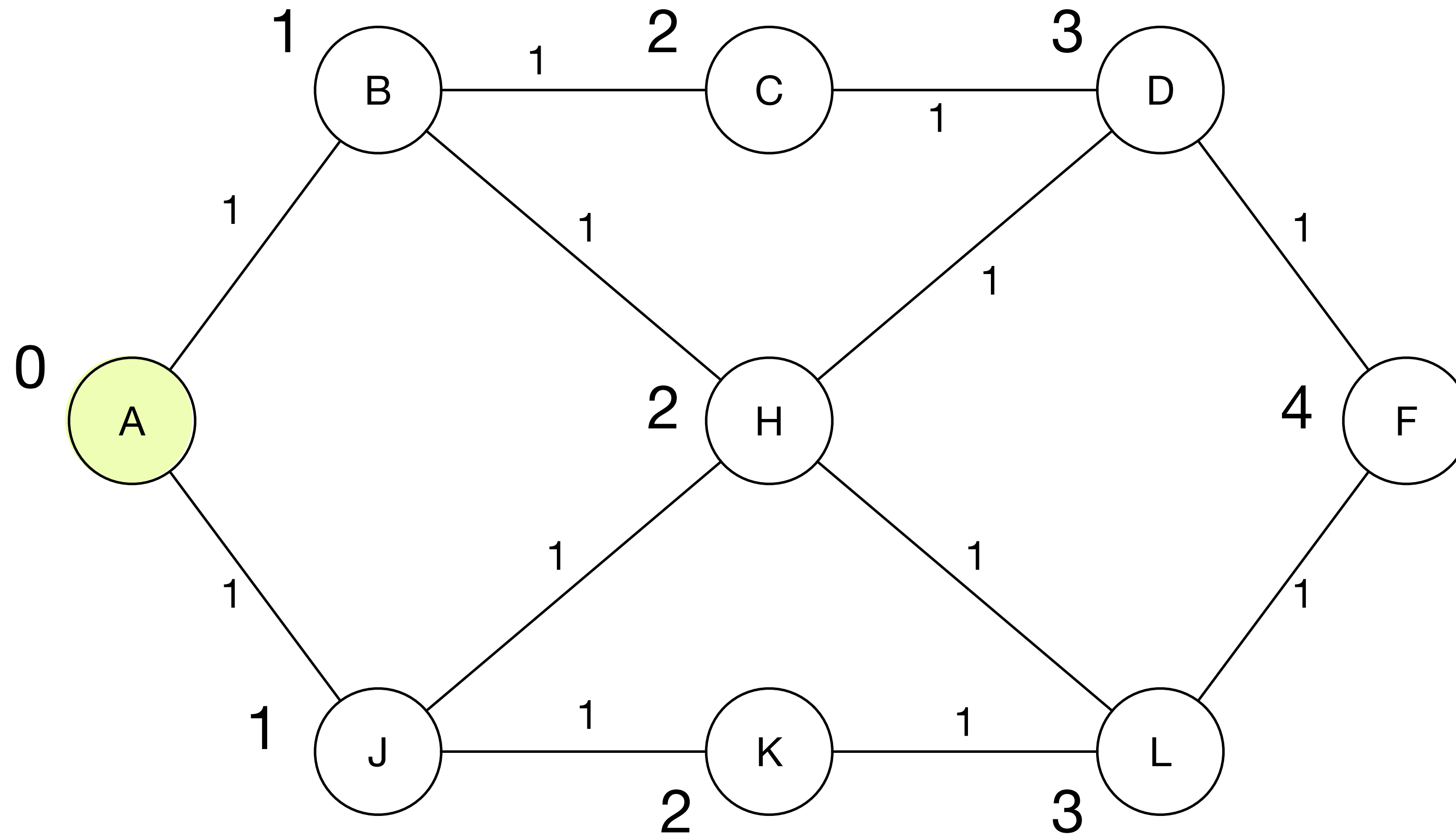




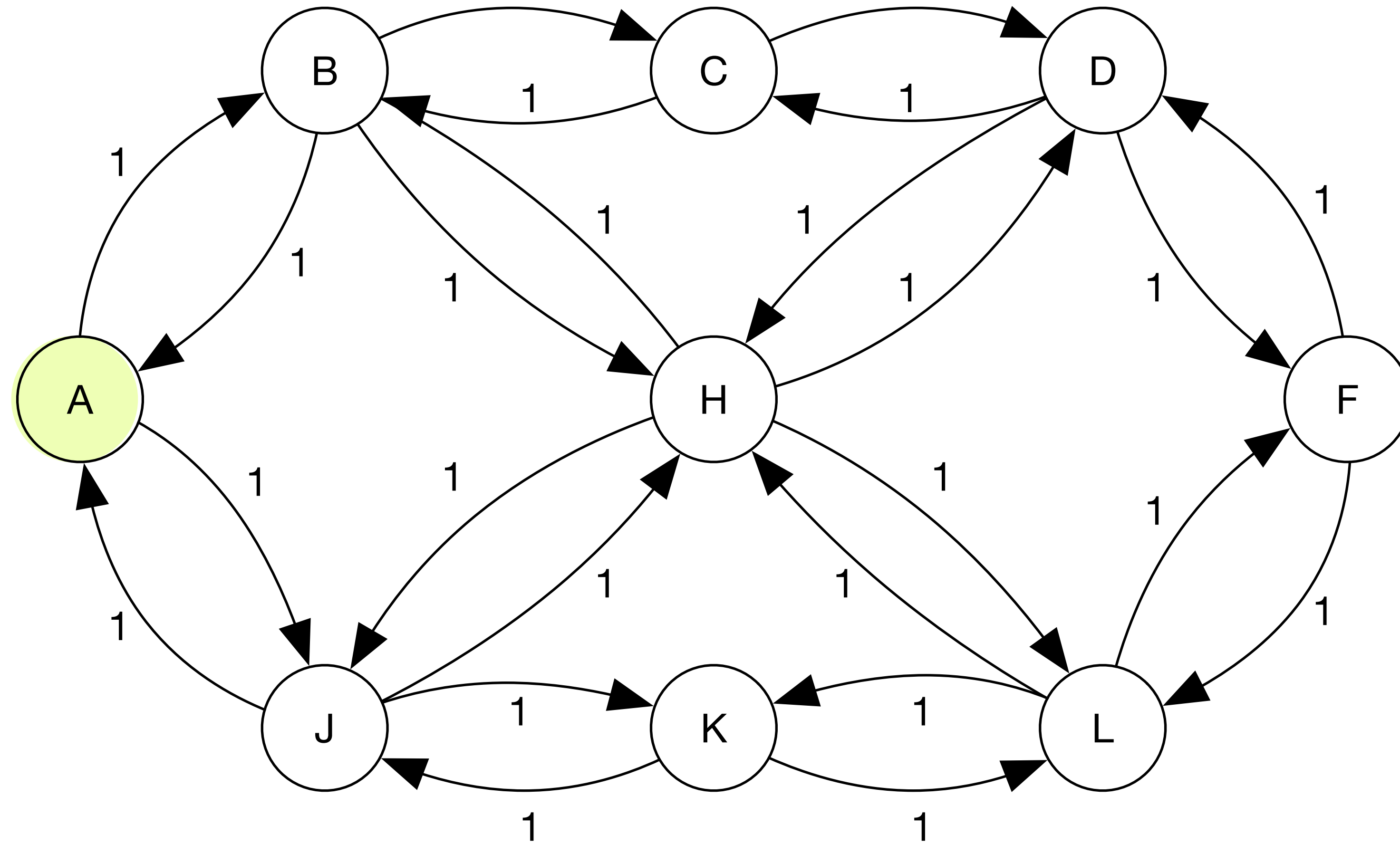
# Shortest path, undirected, unweighted



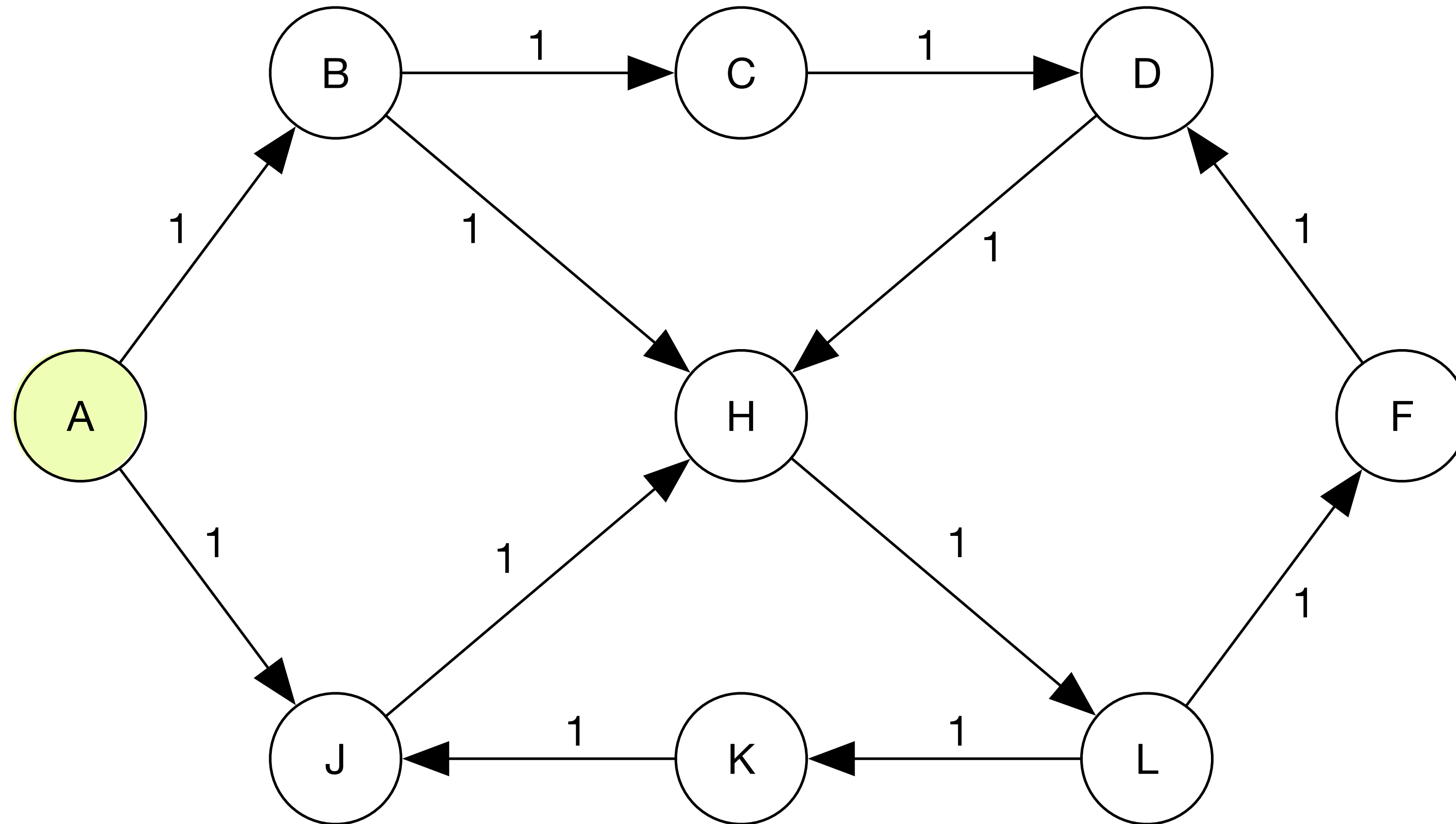
# Shortest path, undirected



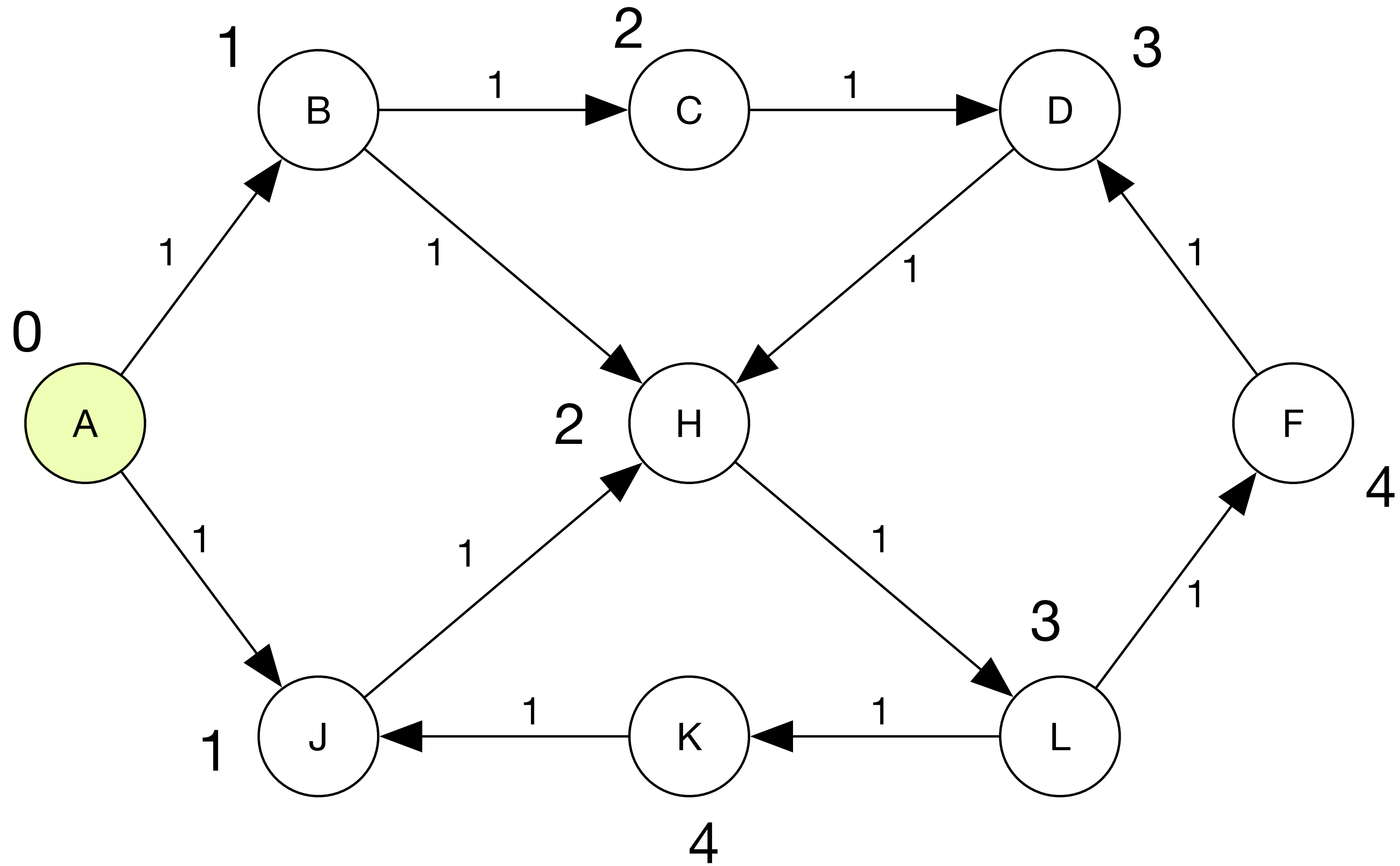
# Shortest path



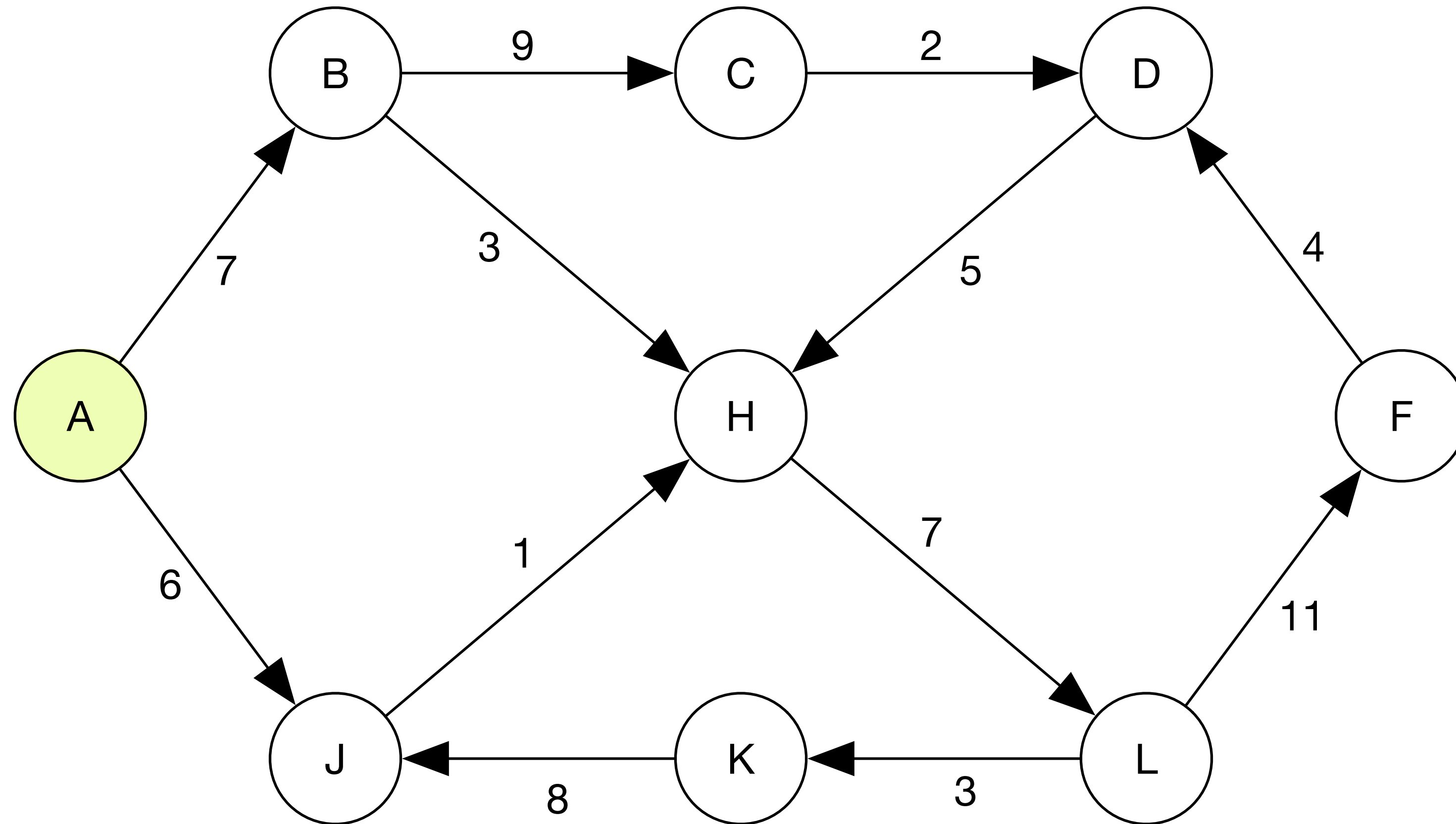
# Shortest path



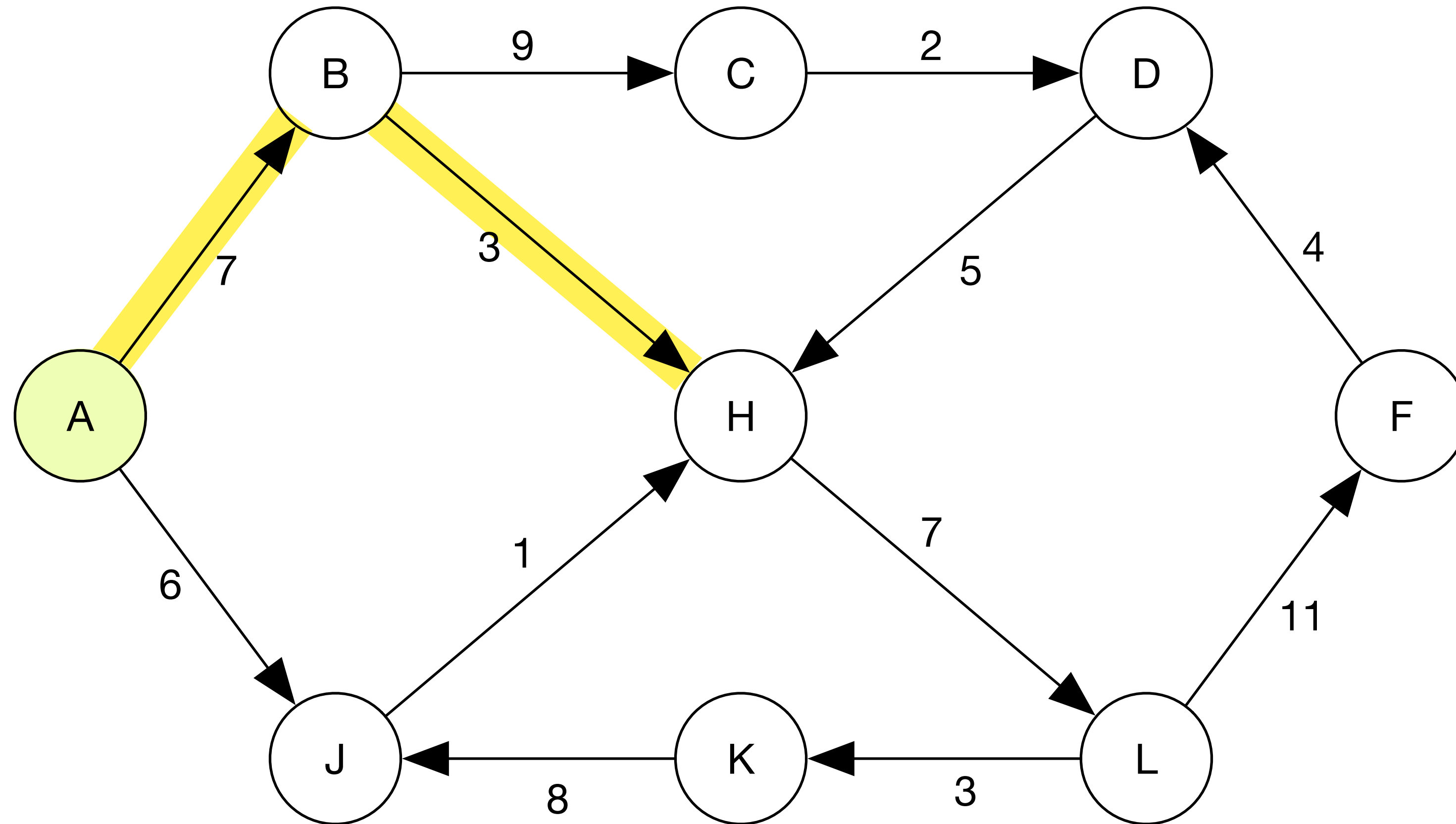
# Shortest path



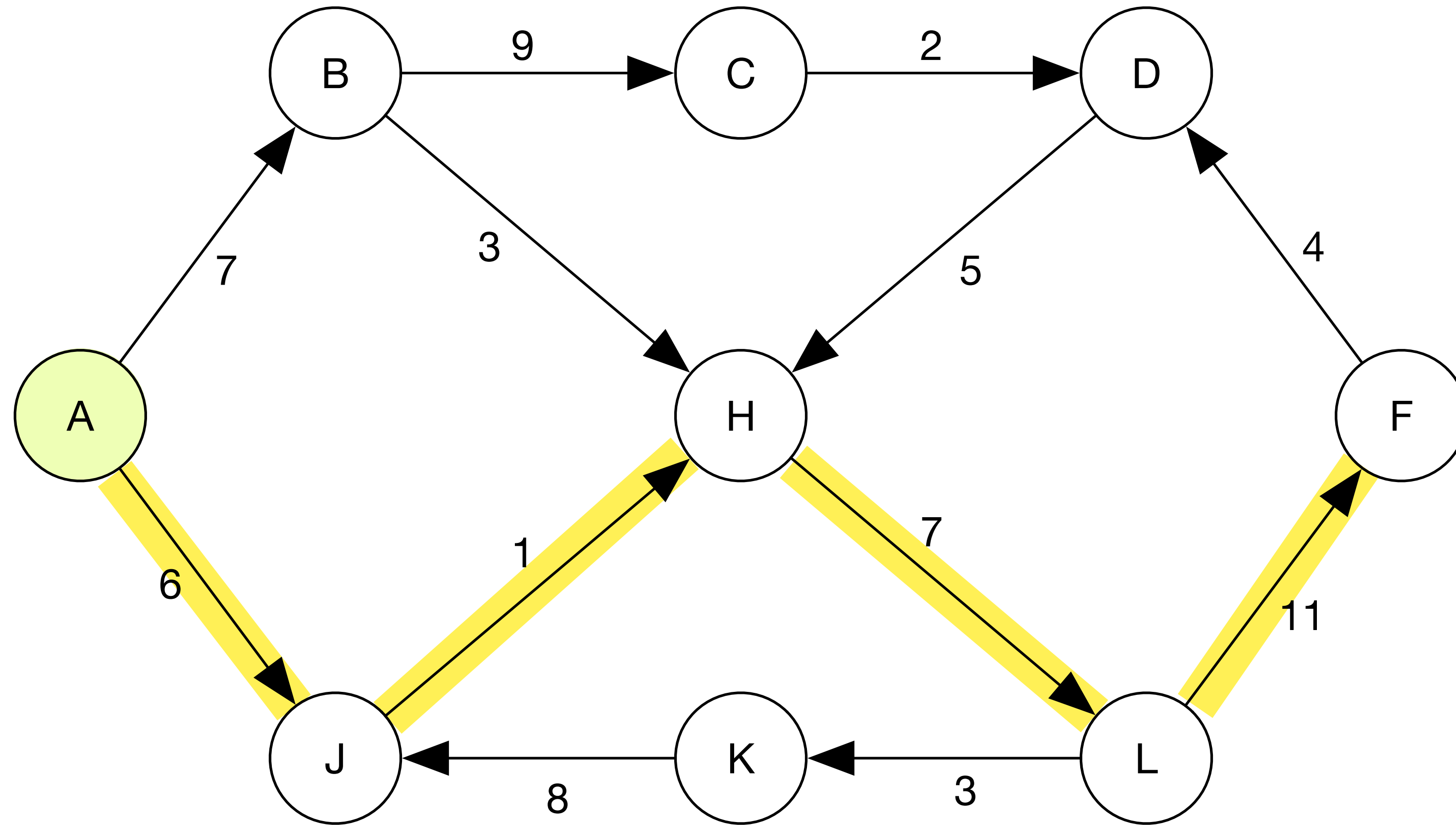
# Shortest path



# Shortest path

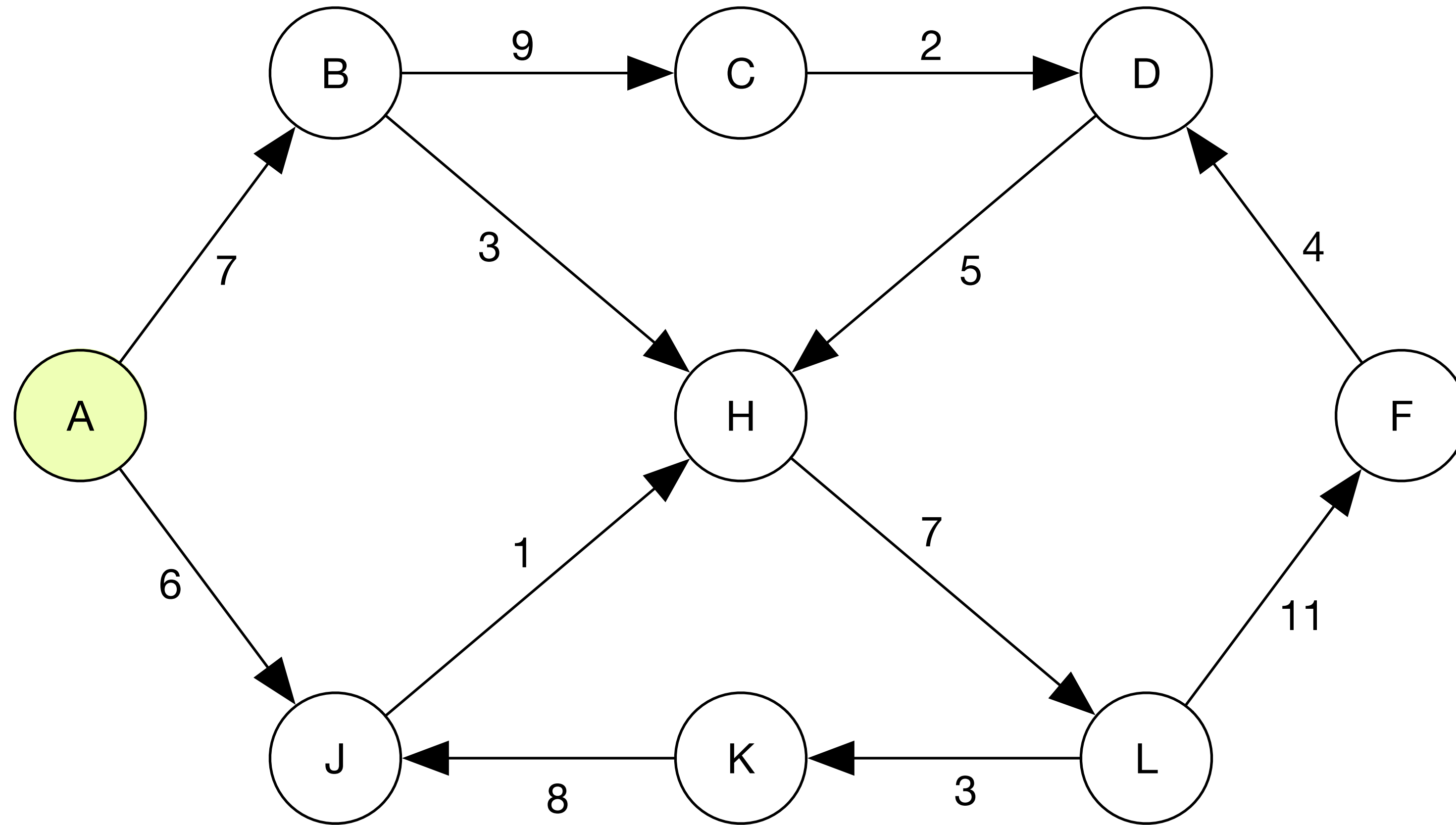


# Shortest path





# Shortest path



# Shortest path: Dijkstra's algorithm



# Dijkstra's algorithm

Given some graph,  $G = (V, E)$ , and some starting node  $S \in V$ , Dijkstra's algorithm will find the shortest paths (or paths with minimum weight) from  $S$  to all other nodes in  $V$ .

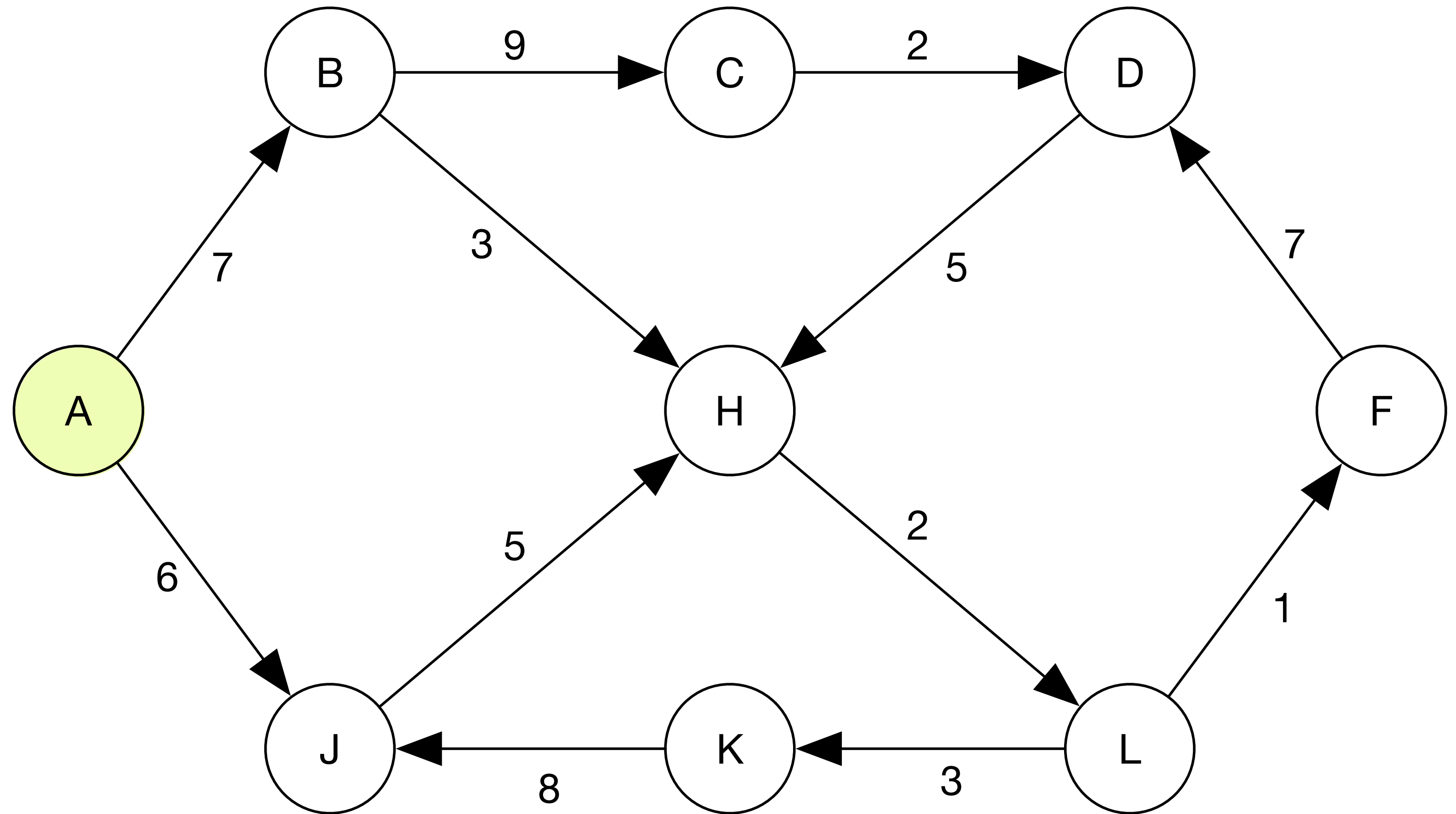
Note that  $G$  must not contain any negative weight edges.

# Dijkstra

Mark all nodes as unvisited (add to set U)

Unvisited set

$U = \{A, B, C, D, F, H, J, K, L\}$

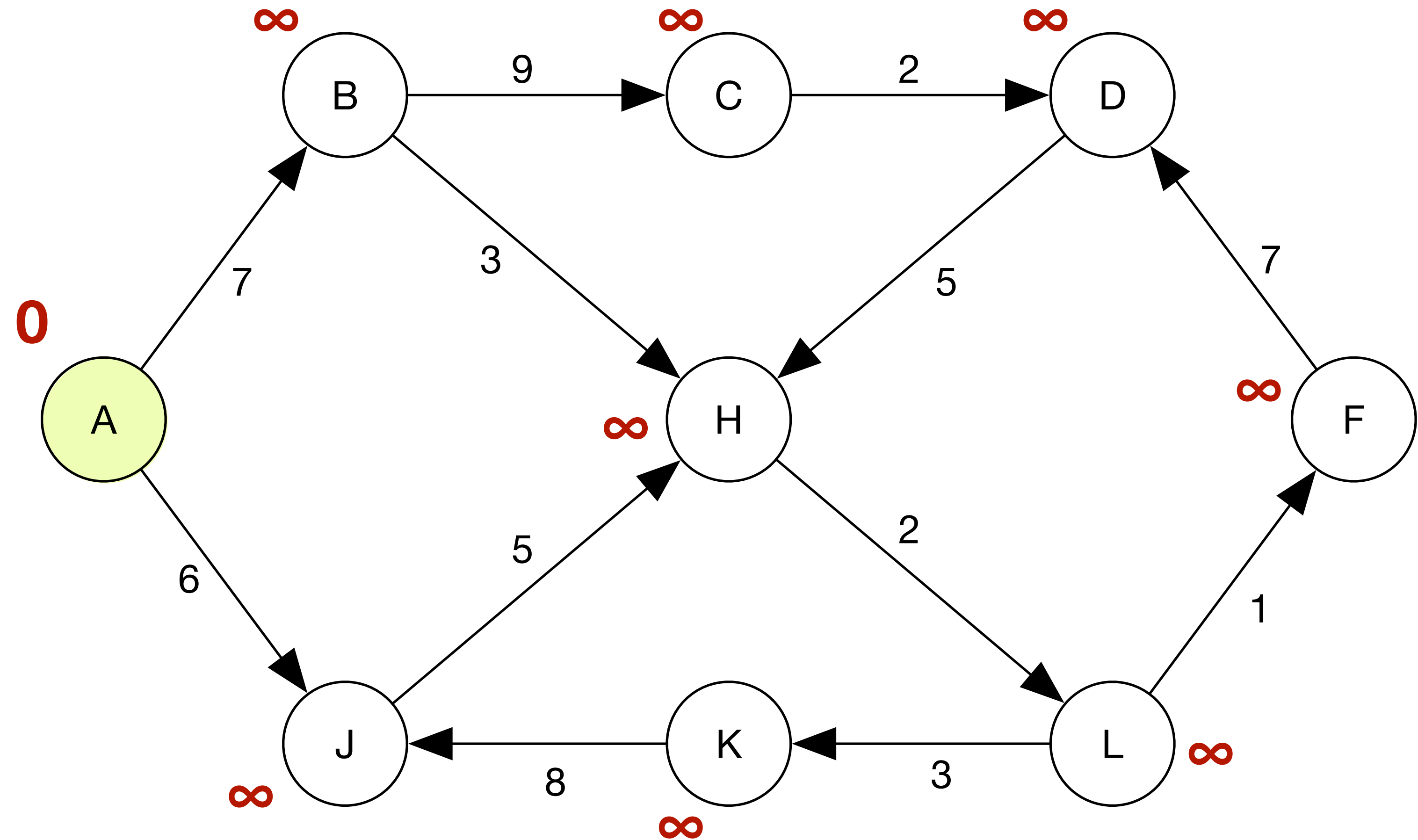


# Dijkstra

Initialize distances

Unvisited set

$U = \{A, B, C, D, F, H, J, K, L\}$

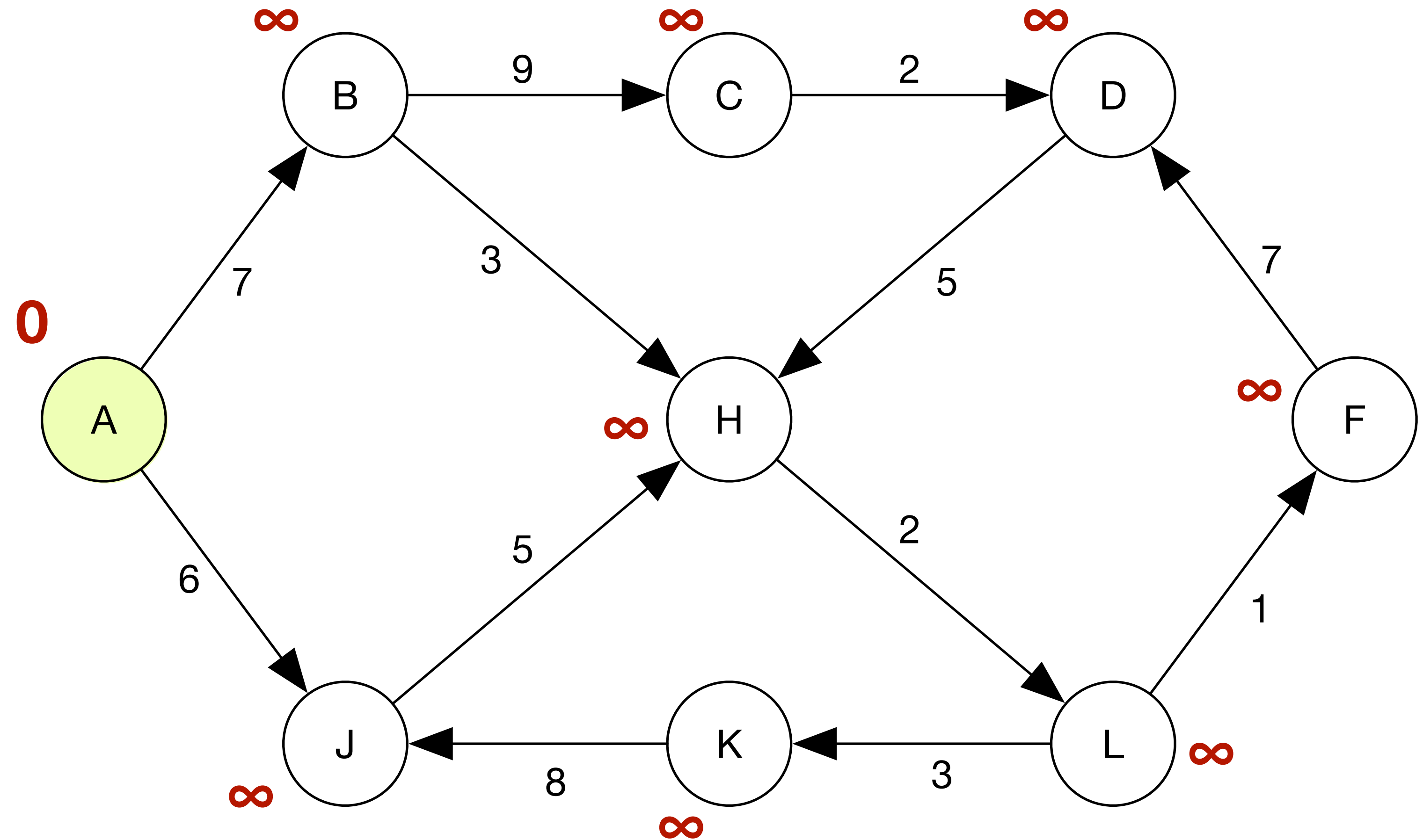


# Dijkstra

Calculate distances to unvisited neighbors

Unvisited set

$U = \{A, B, C, D, F, H, J, K, L\}$

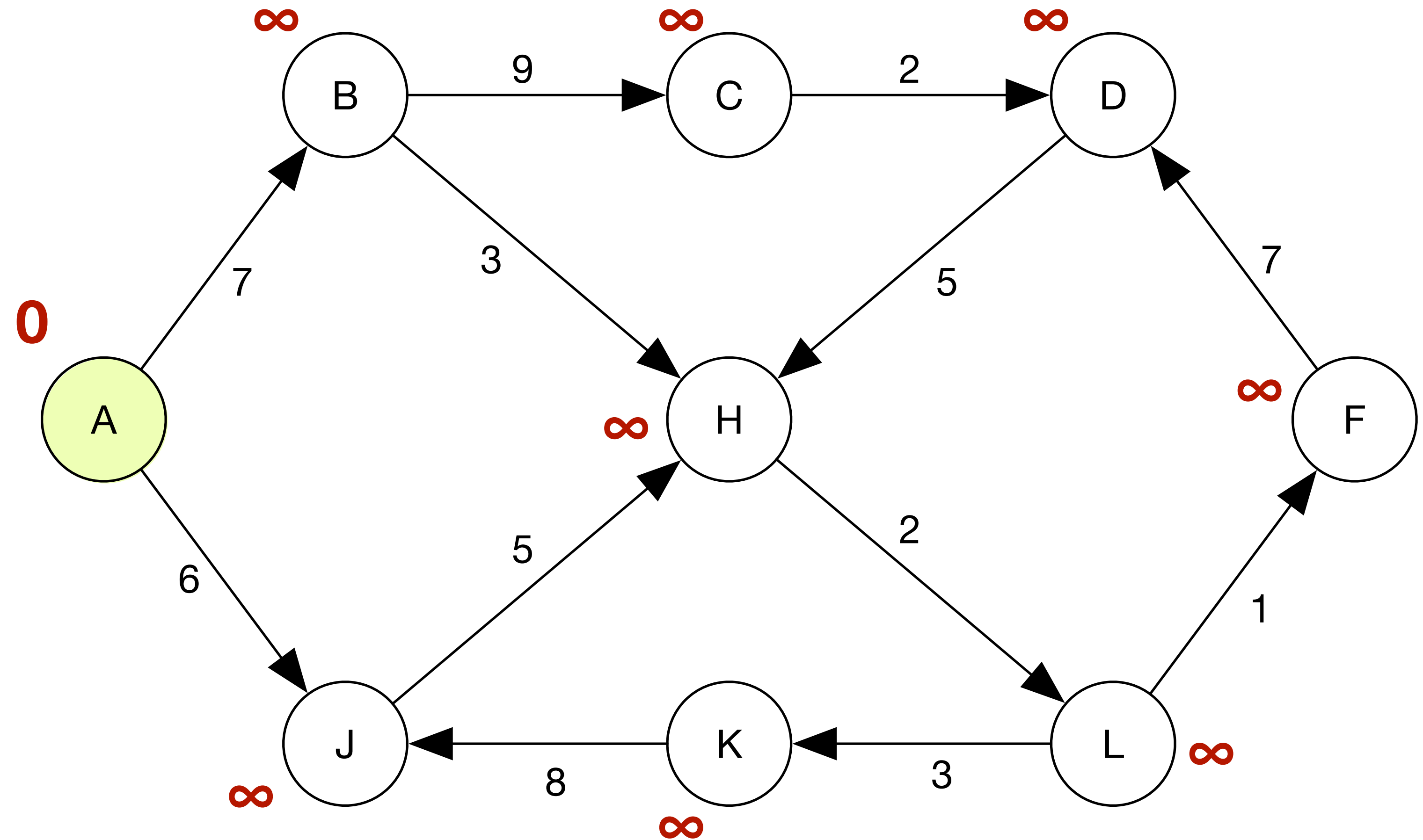


# Dijkstra

Calculate distances to unvisited neighbors

Unvisited set

$U = \{A, B, C, D, F, H, J, K, L\}$

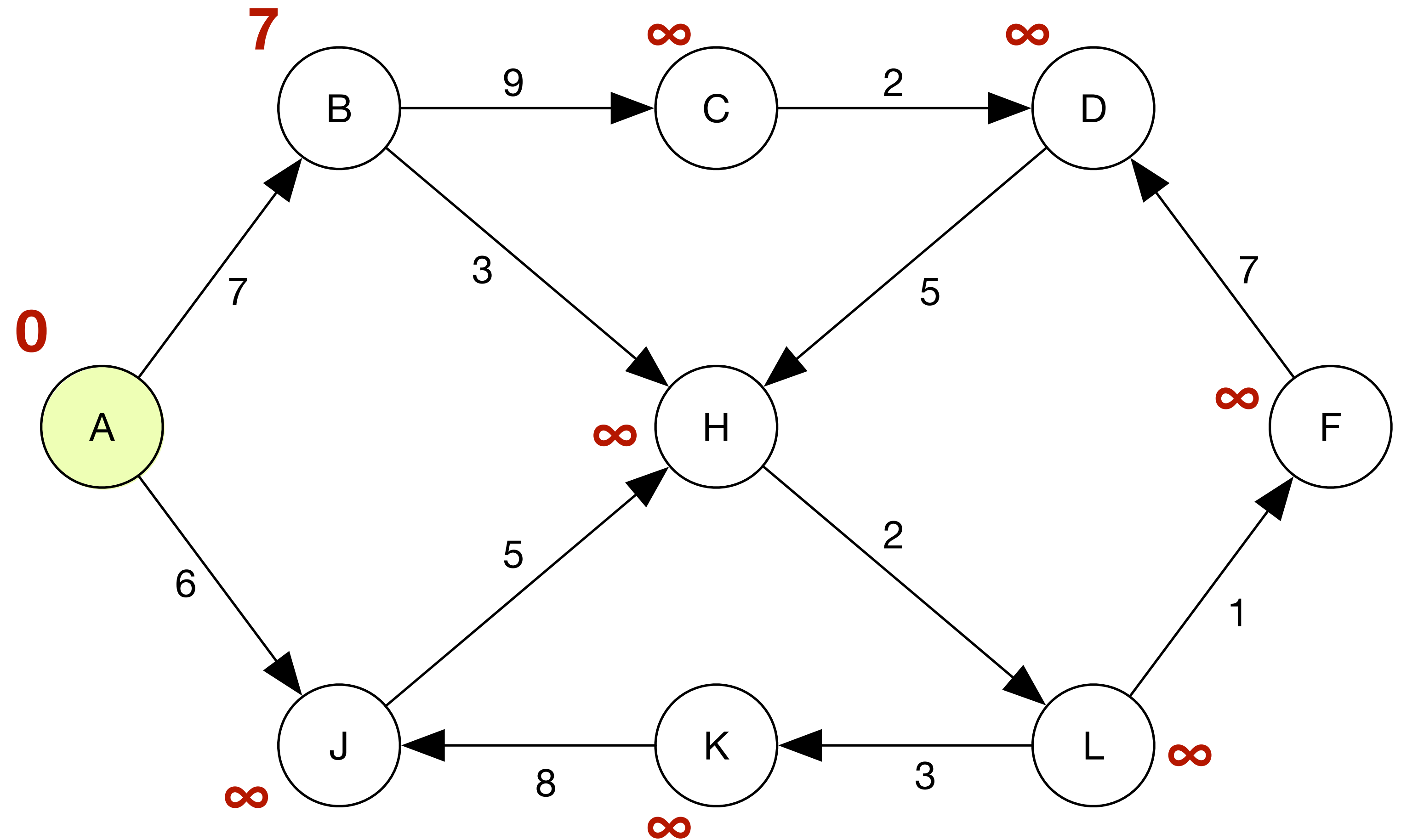


# Dijkstra

Calculate distances to unvisited neighbors

Unvisited set

$U = \{A, B, C, D, F, H, J, K, L\}$



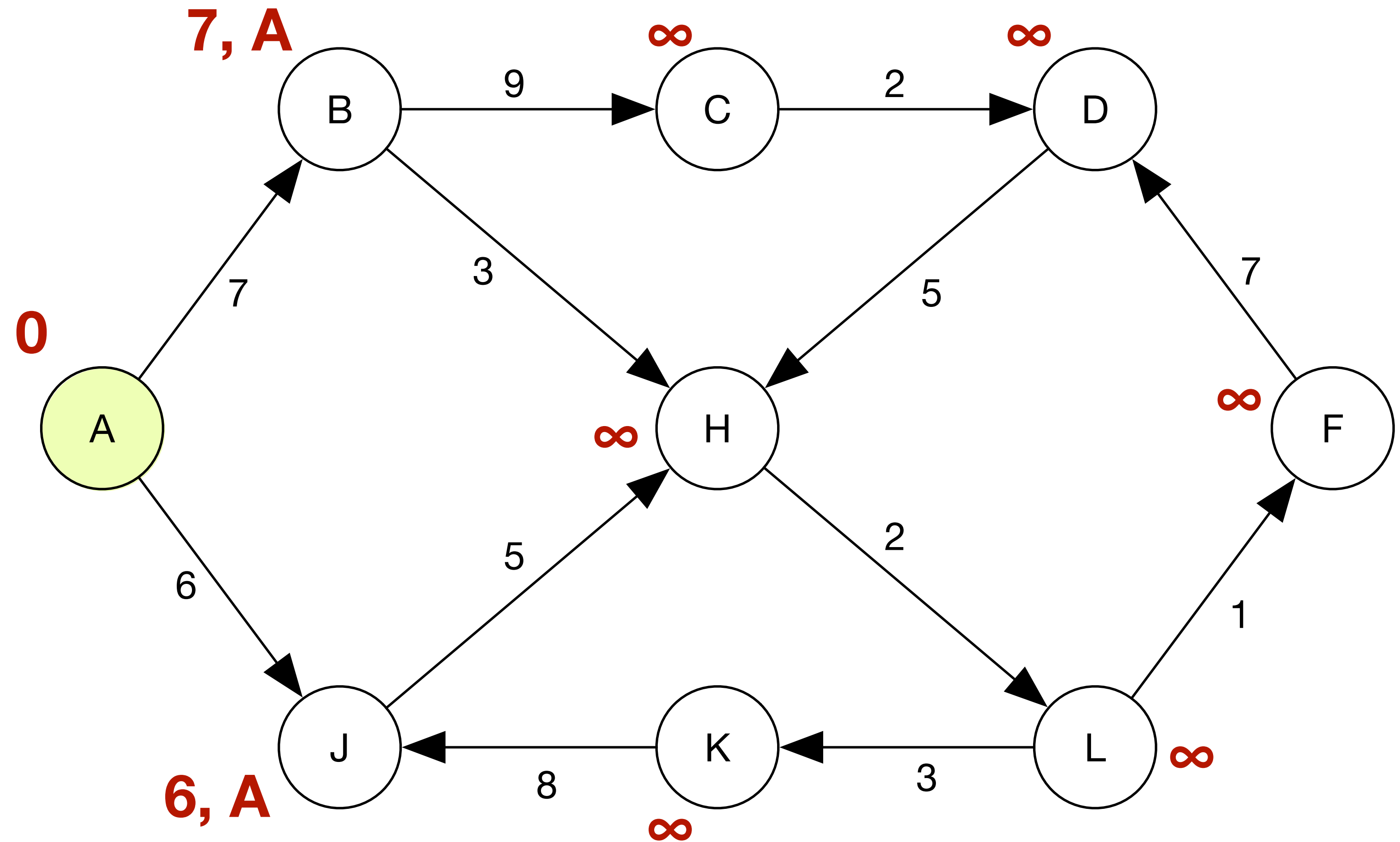


# Dijkstra

Calculate distances to unvisited neighbors

Unvisited set

$U = \{A, B, C, D, F, H, J, K, L\}$

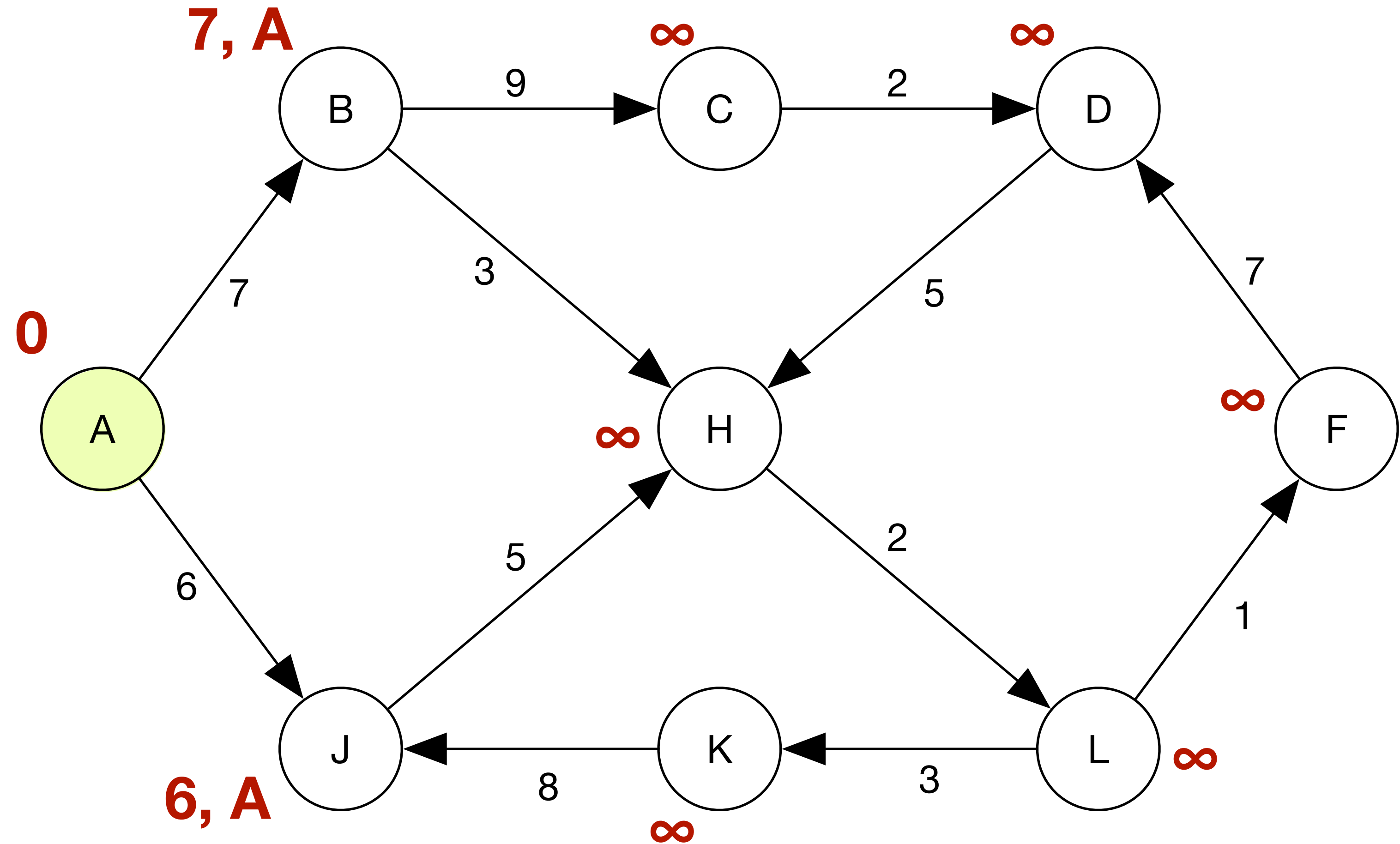


# Dijkstra

Mark A as visited (remove from U)

Unvisited set

$U = \{B, C, D, F, H, J, K, L\}$

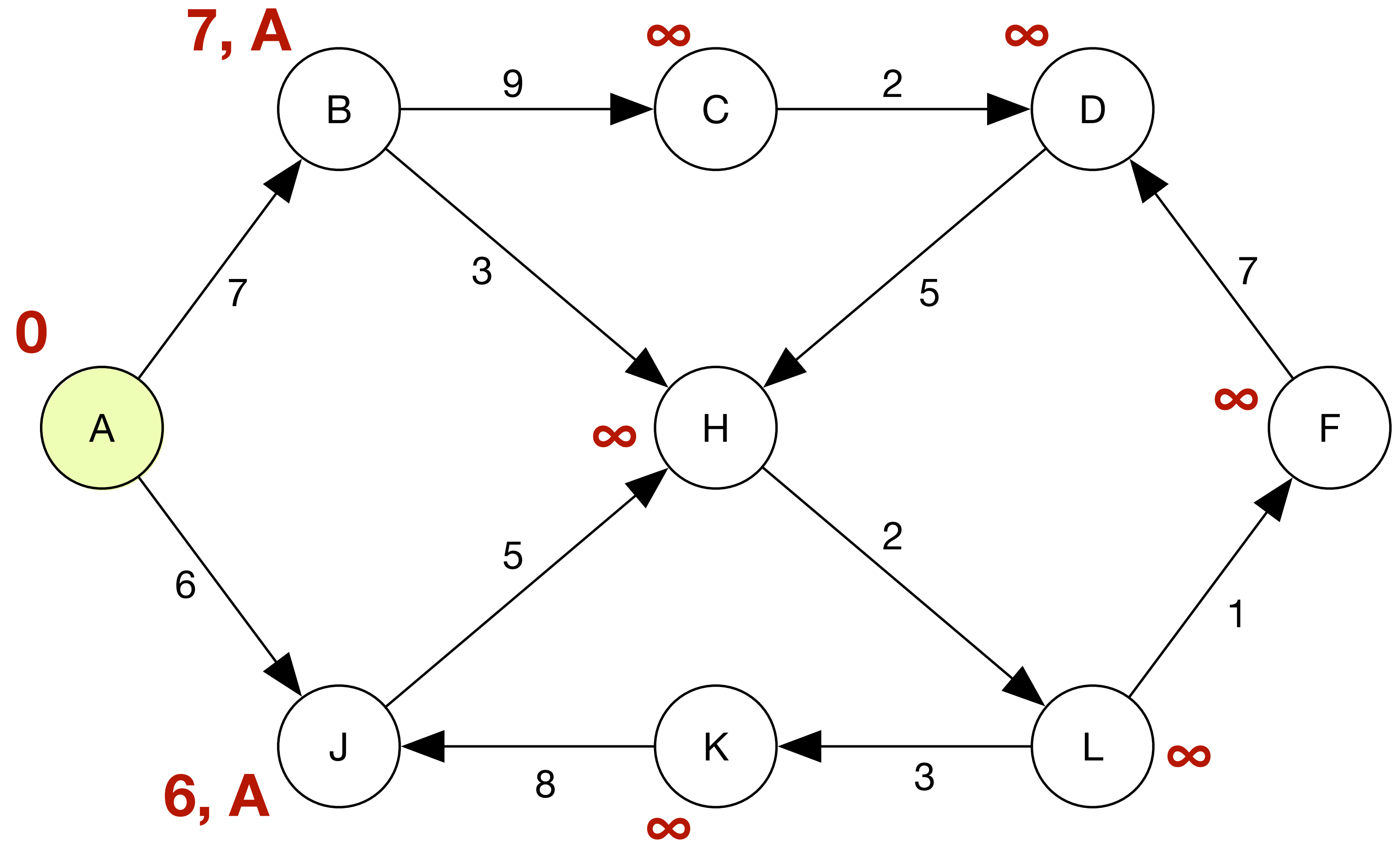


# Dijkstra

Choose next node from which to explore

Unvisited set

$U = \{B, C, D, F, H, J, K, L\}$

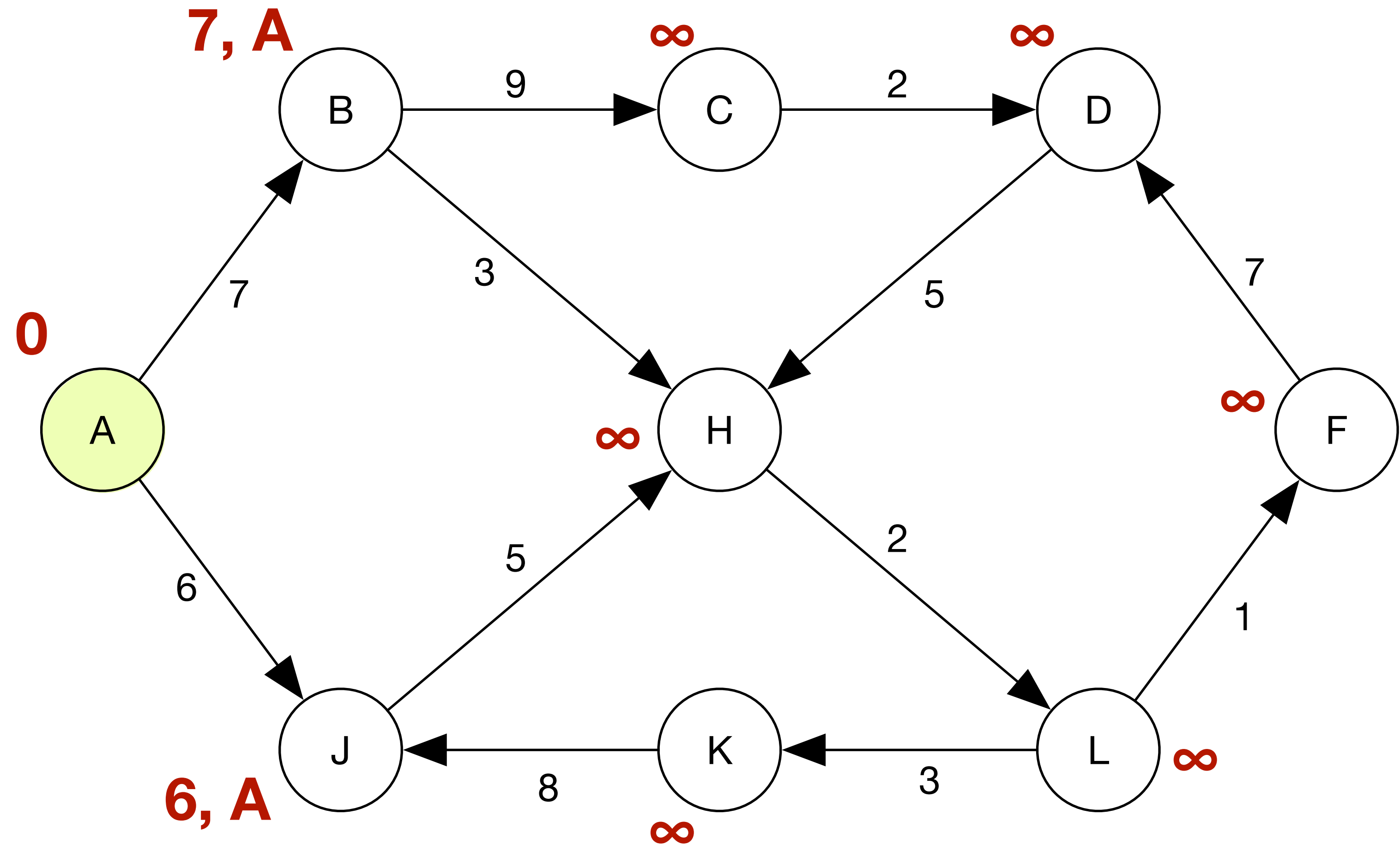


# Dijkstra

Explore from J, and calculate distances

Unvisited set

$U = \{B, C, D, F, H, J, K, L\}$

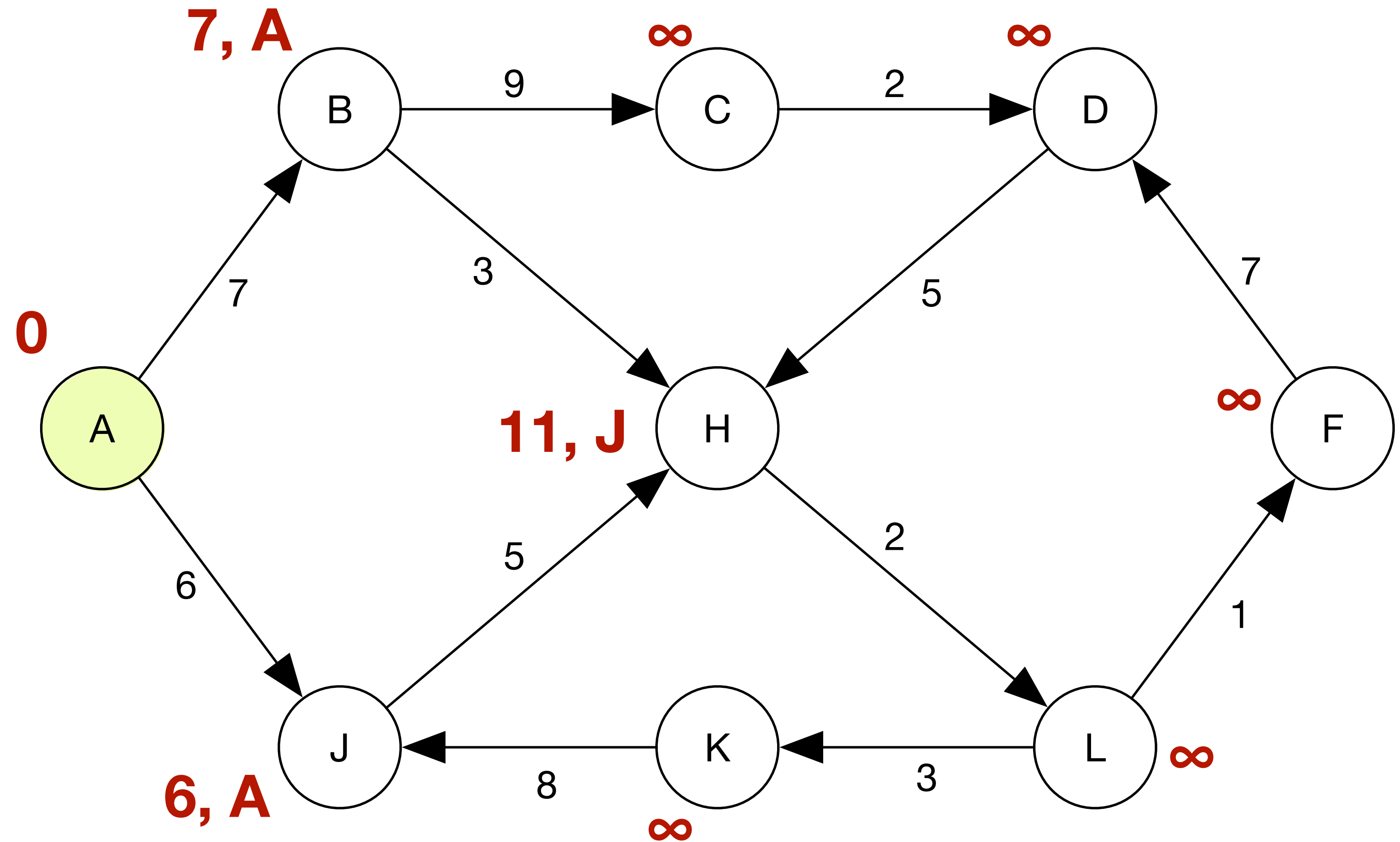


# Dijkstra

Explore from J, and calculate distances

Unvisited set

$U = \{B, C, D, F, H, J, K, L\}$

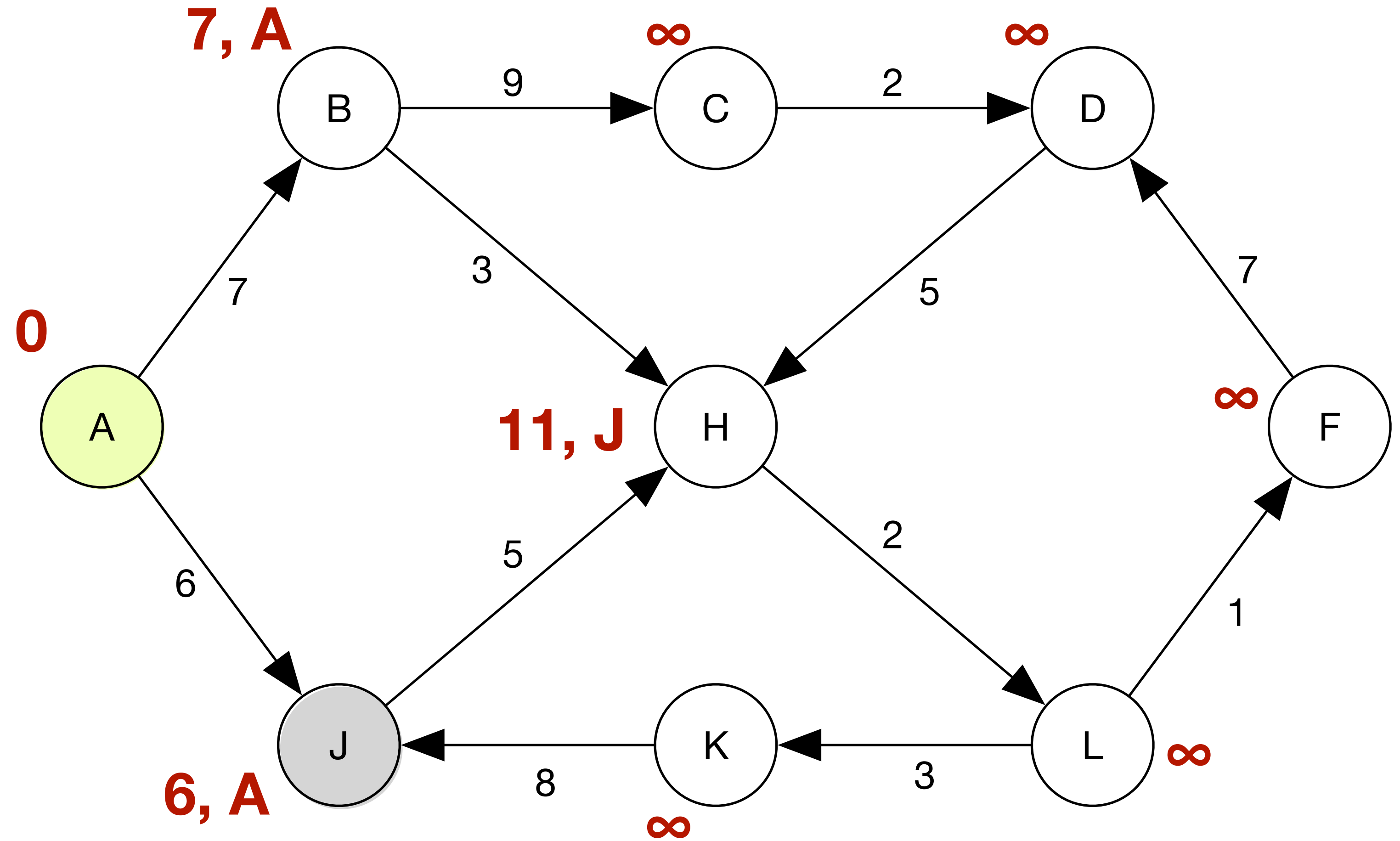


# Dijkstra

Mark J as visited (remove from set U)

Unvisited set

$U = \{B, C, D, F, H, K, L\}$

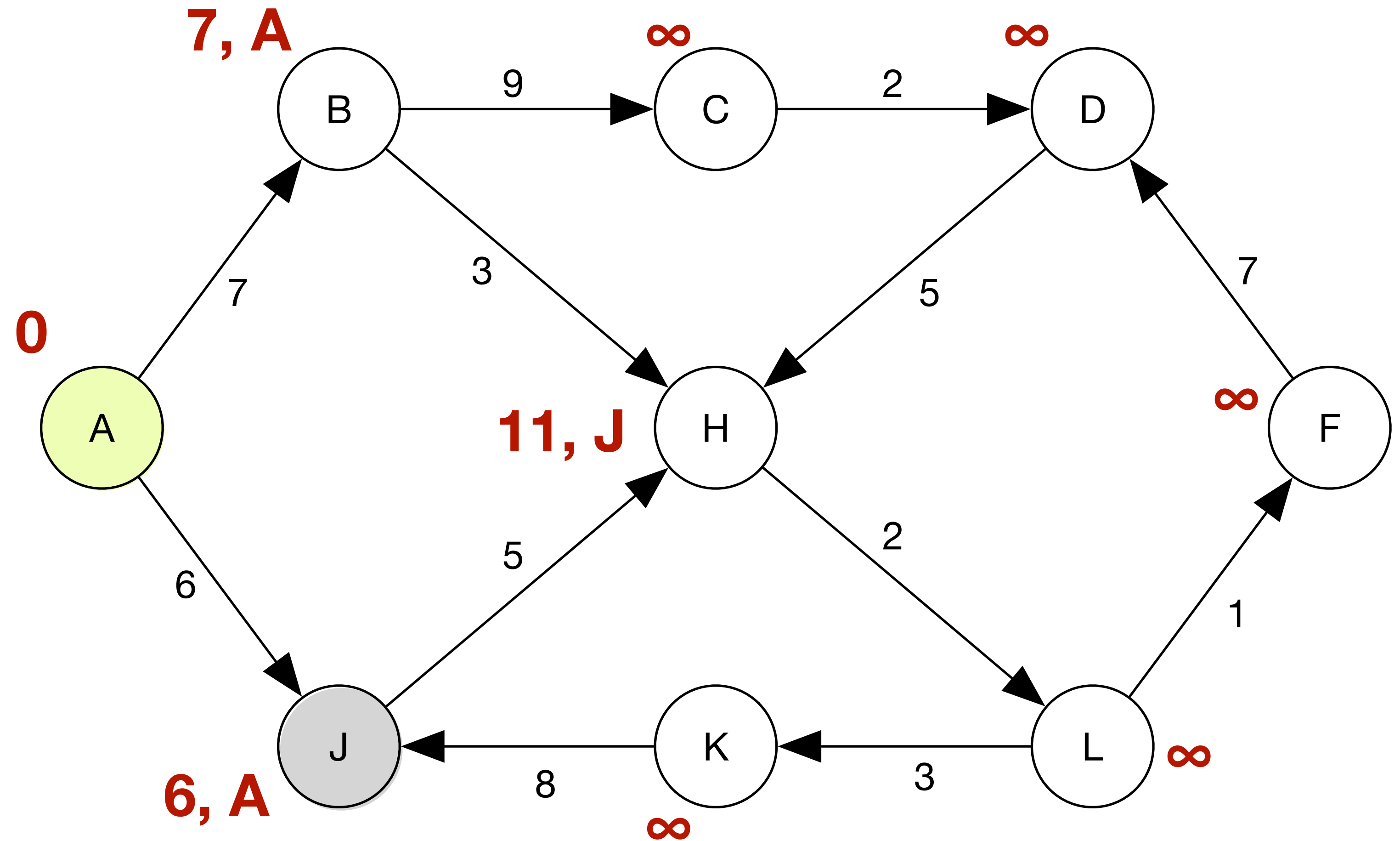


# Dijkstra

Choose next node from which to explore

Unvisited set

$U = \{B, C, D, F, H, K, L\}$

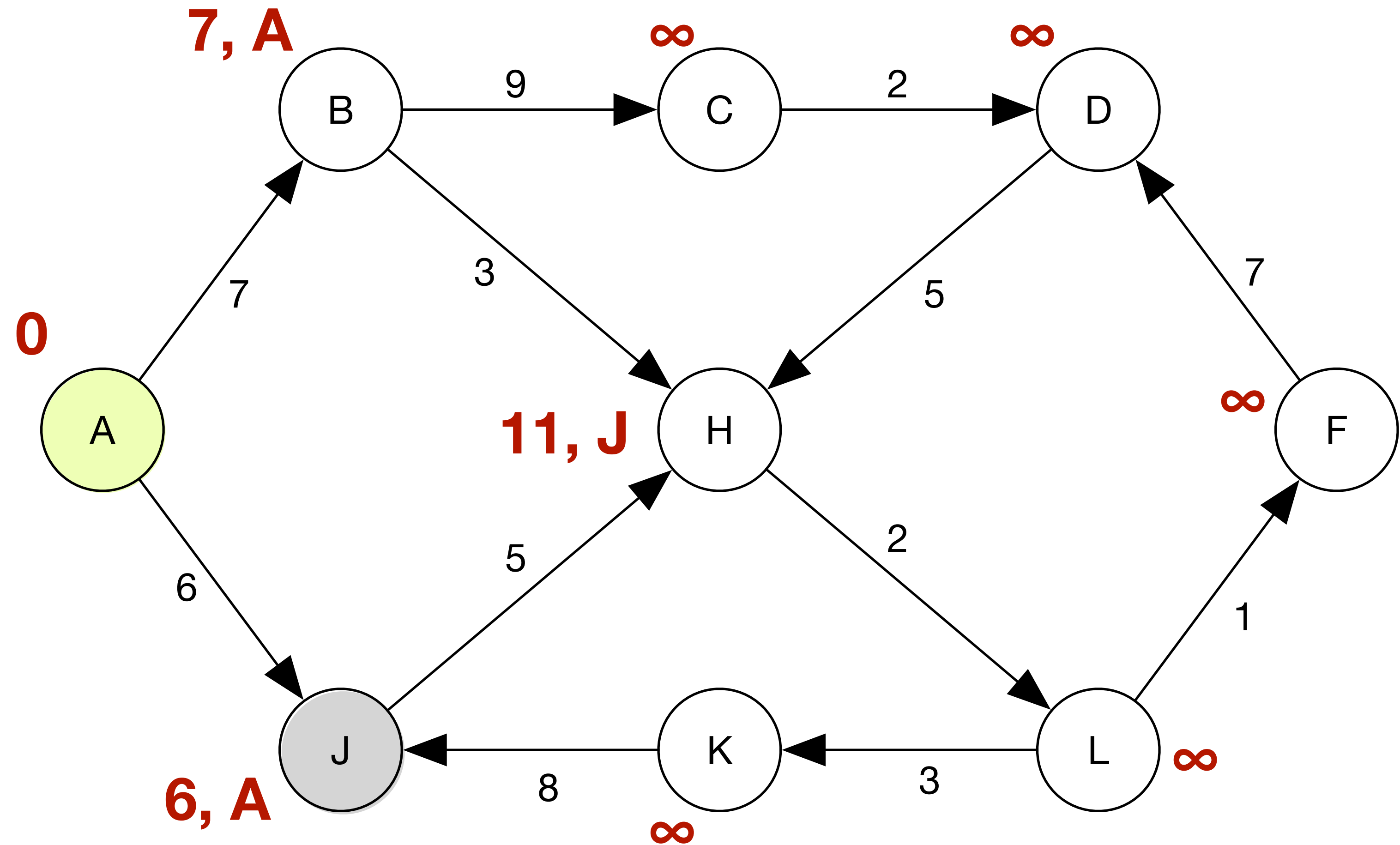


# Dijkstra

Explore from B and calculate distances

Unvisited set

$U = \{B, C, D, F, H, K, L\}$



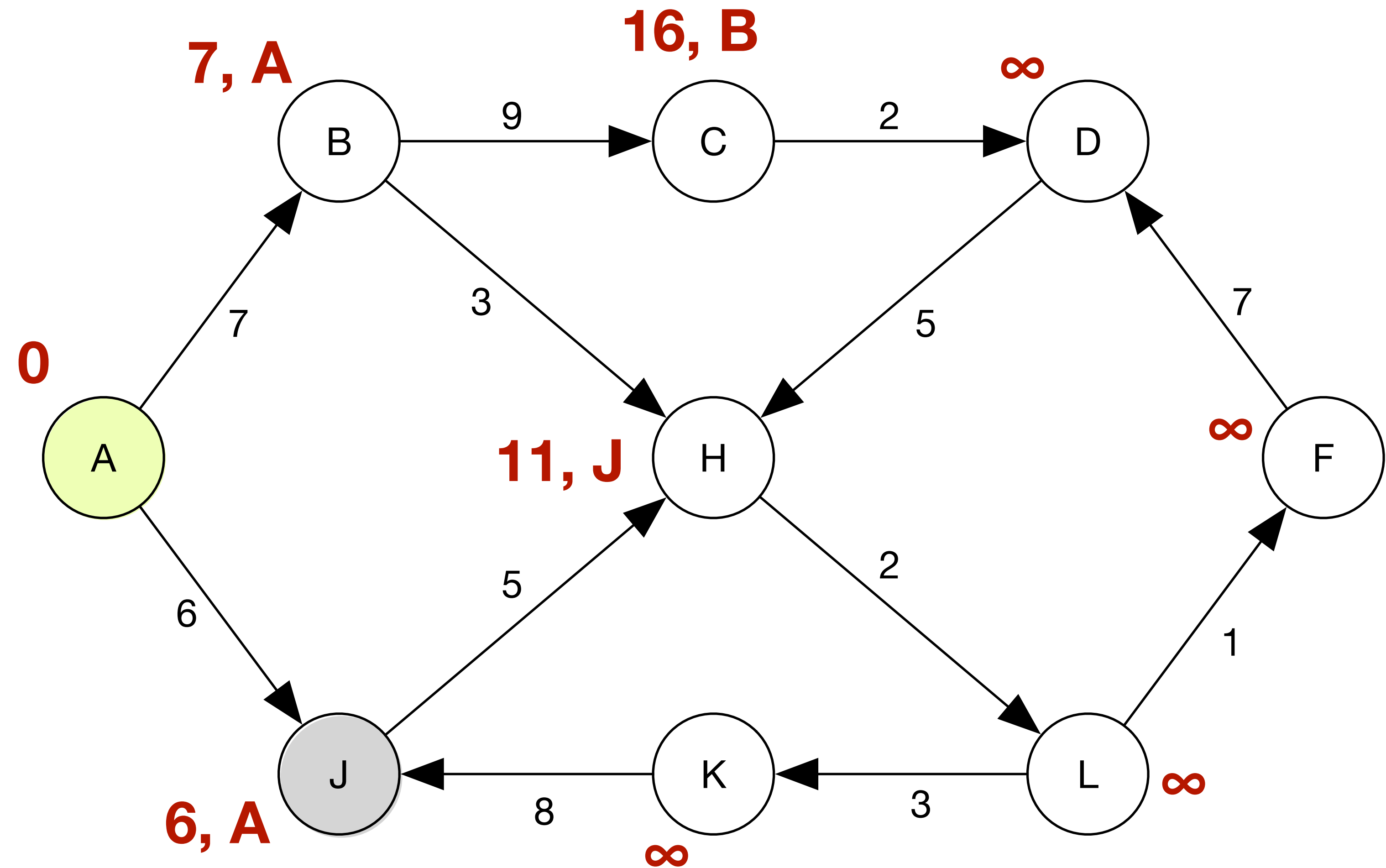


# Dijkstra

Explore from B and calculate distances

Unvisited set

$U = \{B, C, D, F, H, K, L\}$

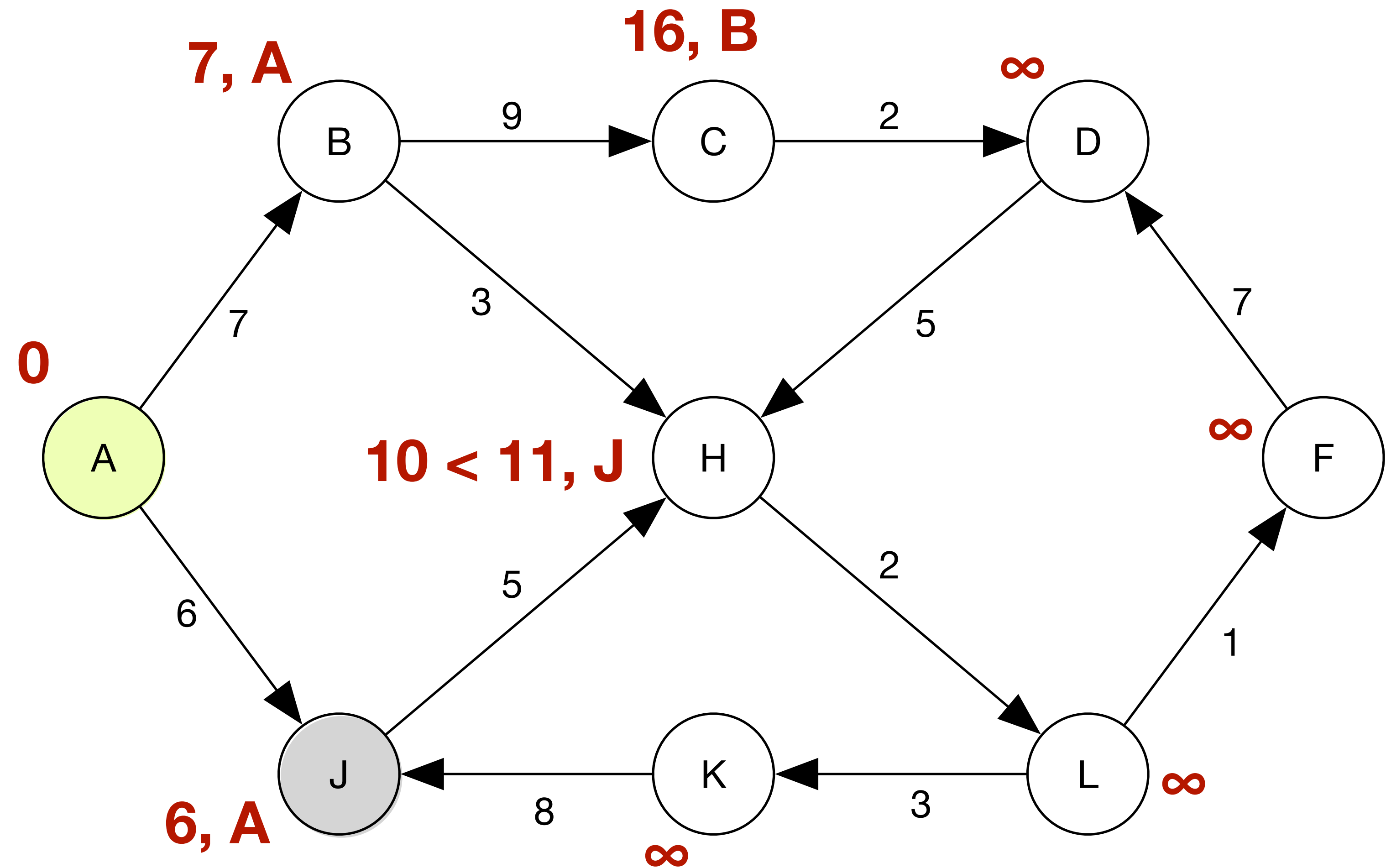


# Dijkstra

Explore from B and calculate distances

Unvisited set

$U = \{B, C, D, F, H, K, L\}$

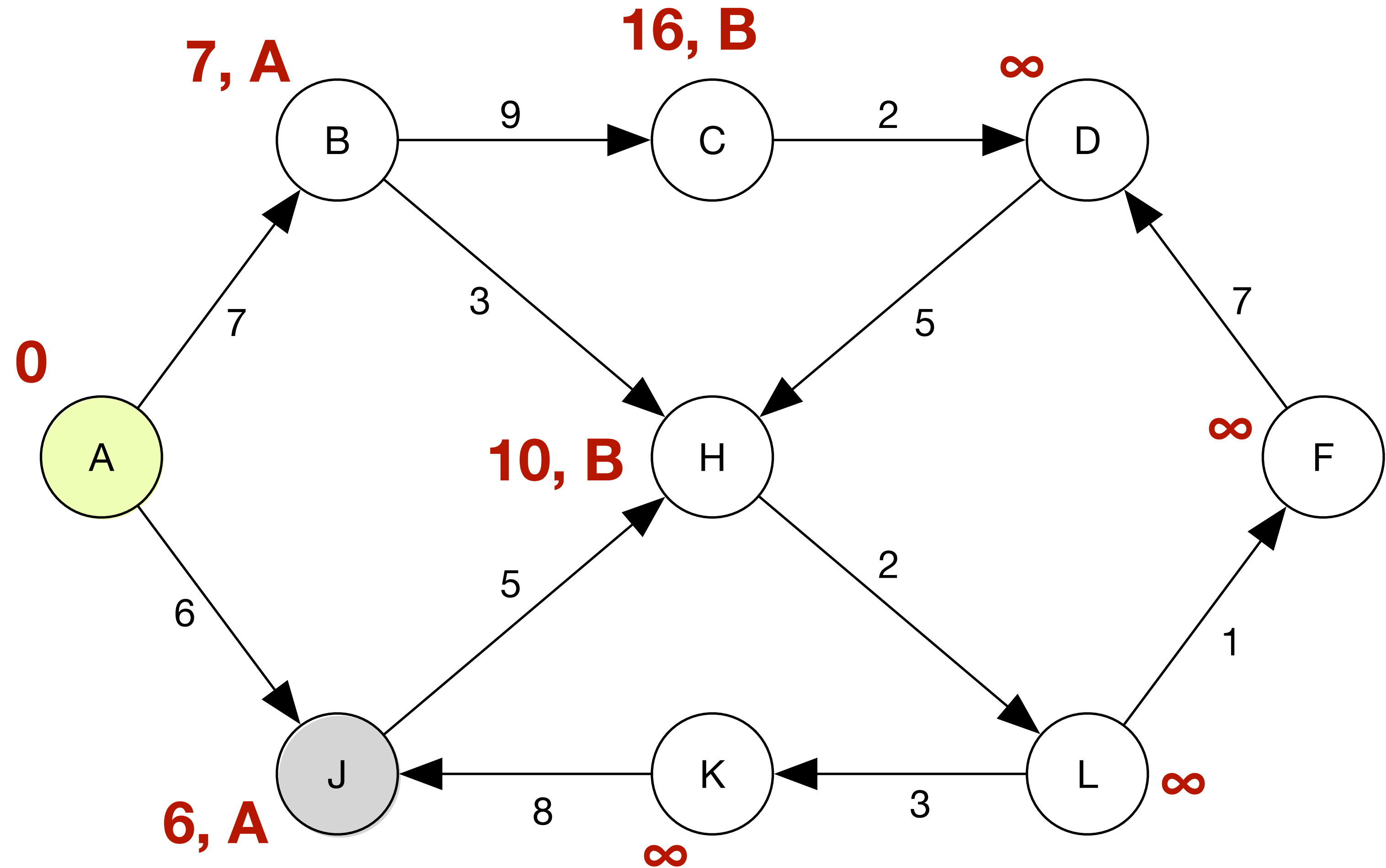


# Dijkstra

Explore from B and calculate distances

Unvisited set

$U = \{B, C, D, F, H, K, L\}$

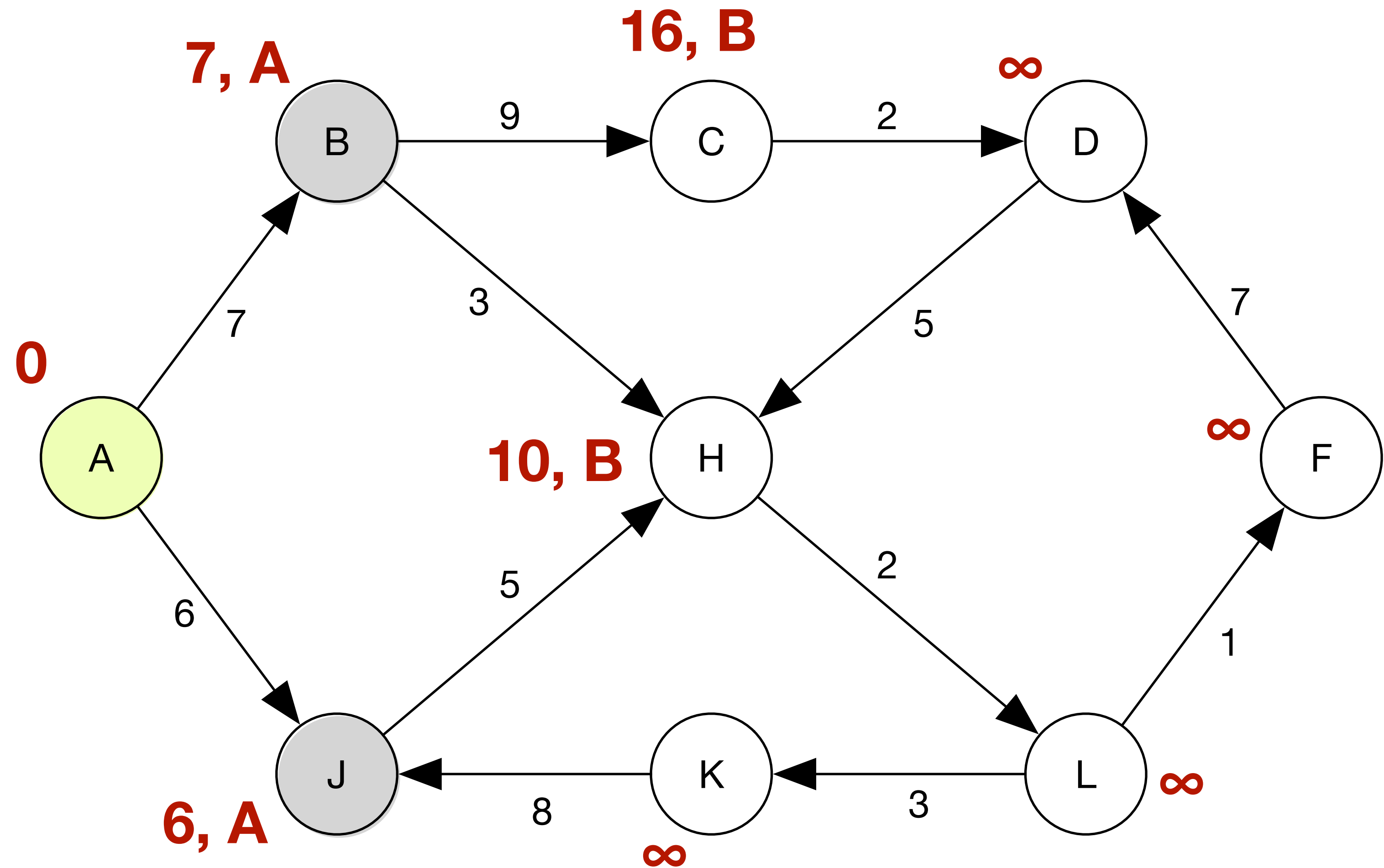


# Dijkstra

Mark B as visited (remove from set U)

Unvisited set

$U = \{C, D, F, H, K, L\}$

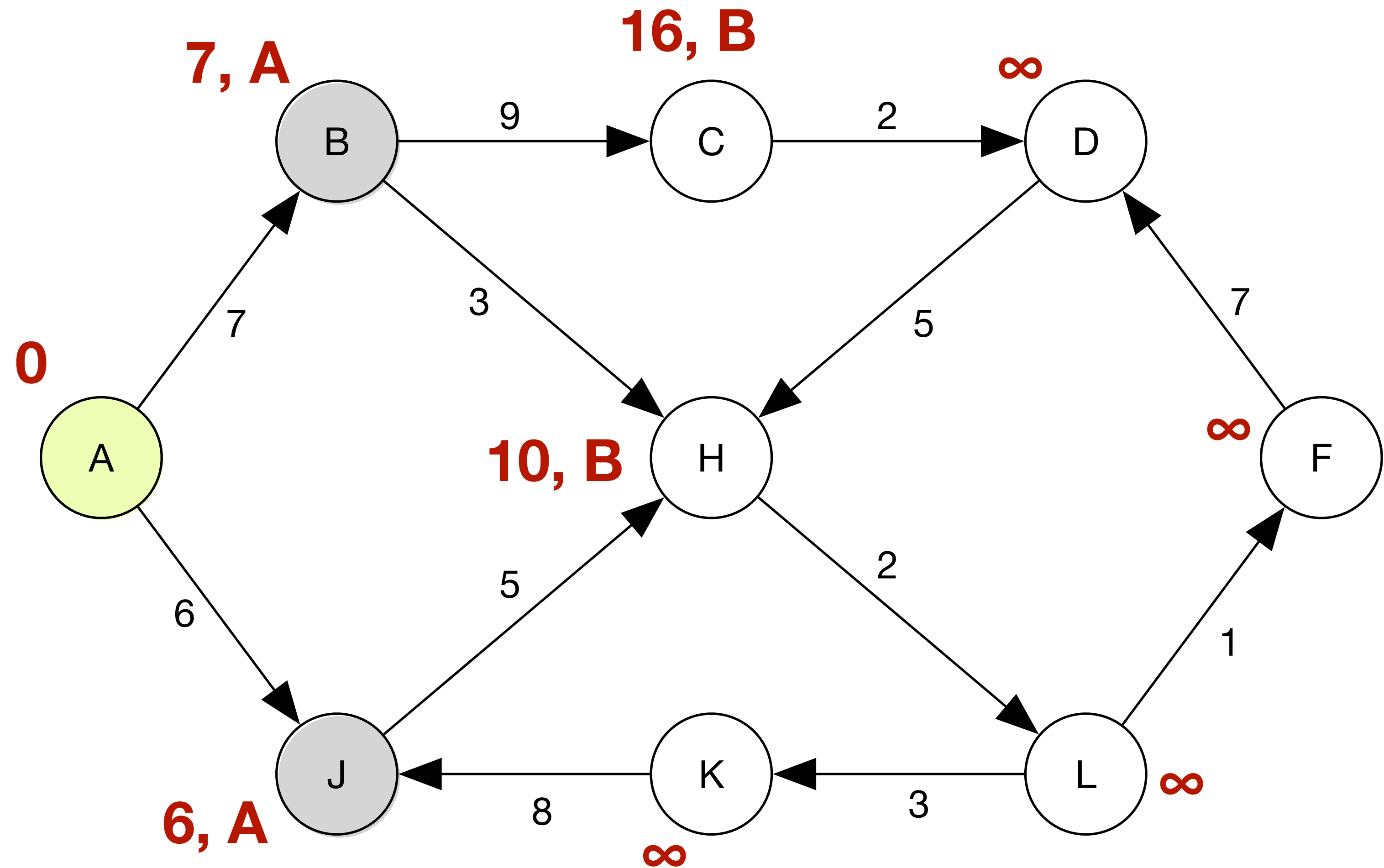


# Dijkstra

Choose the next node from which to explore

Unvisited set

$U = \{C, D, F, H, K, L\}$

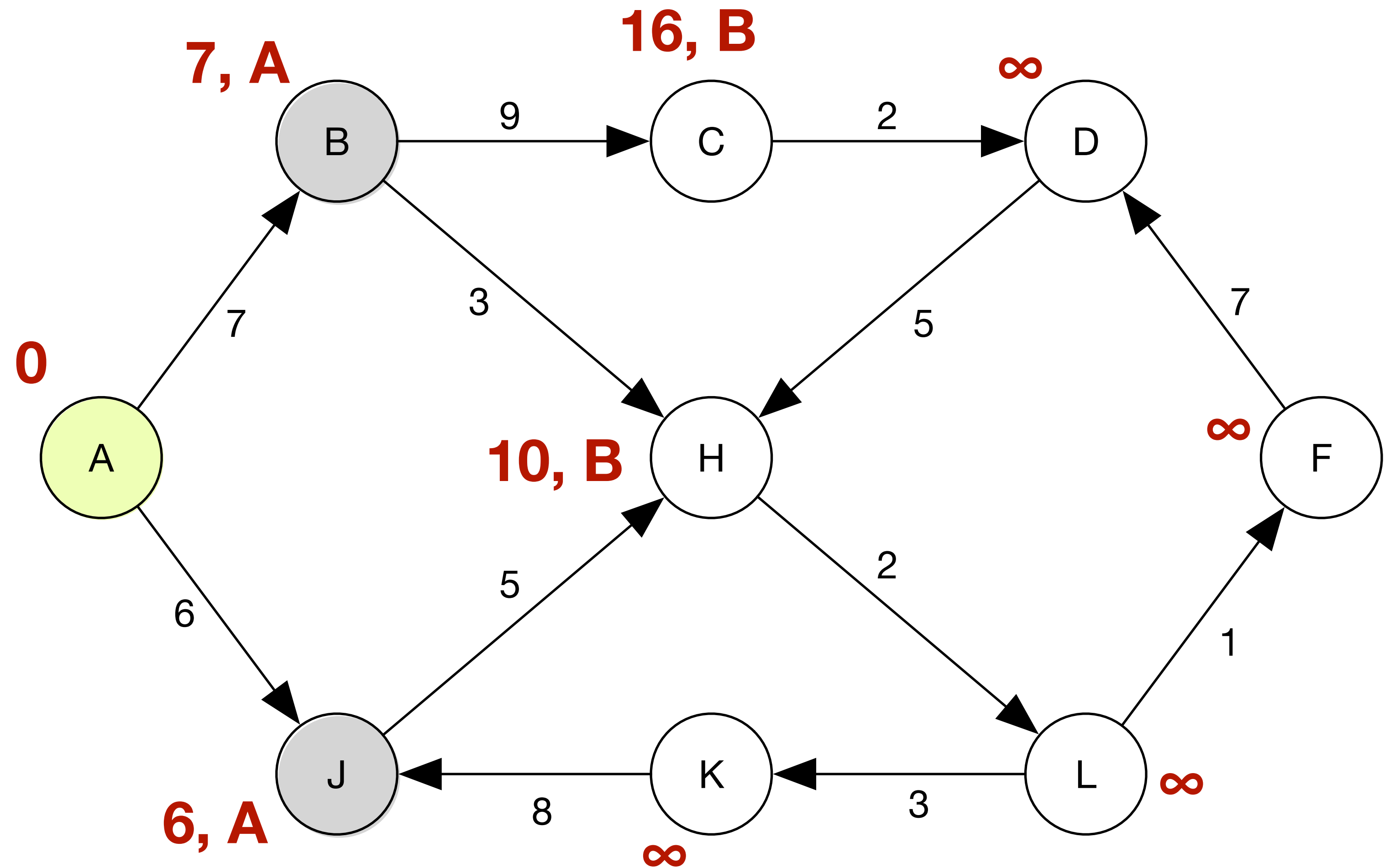


# Dijkstra

Explore from H and calculate distances

Unvisited set

$U = \{C, D, F, H, K, L\}$

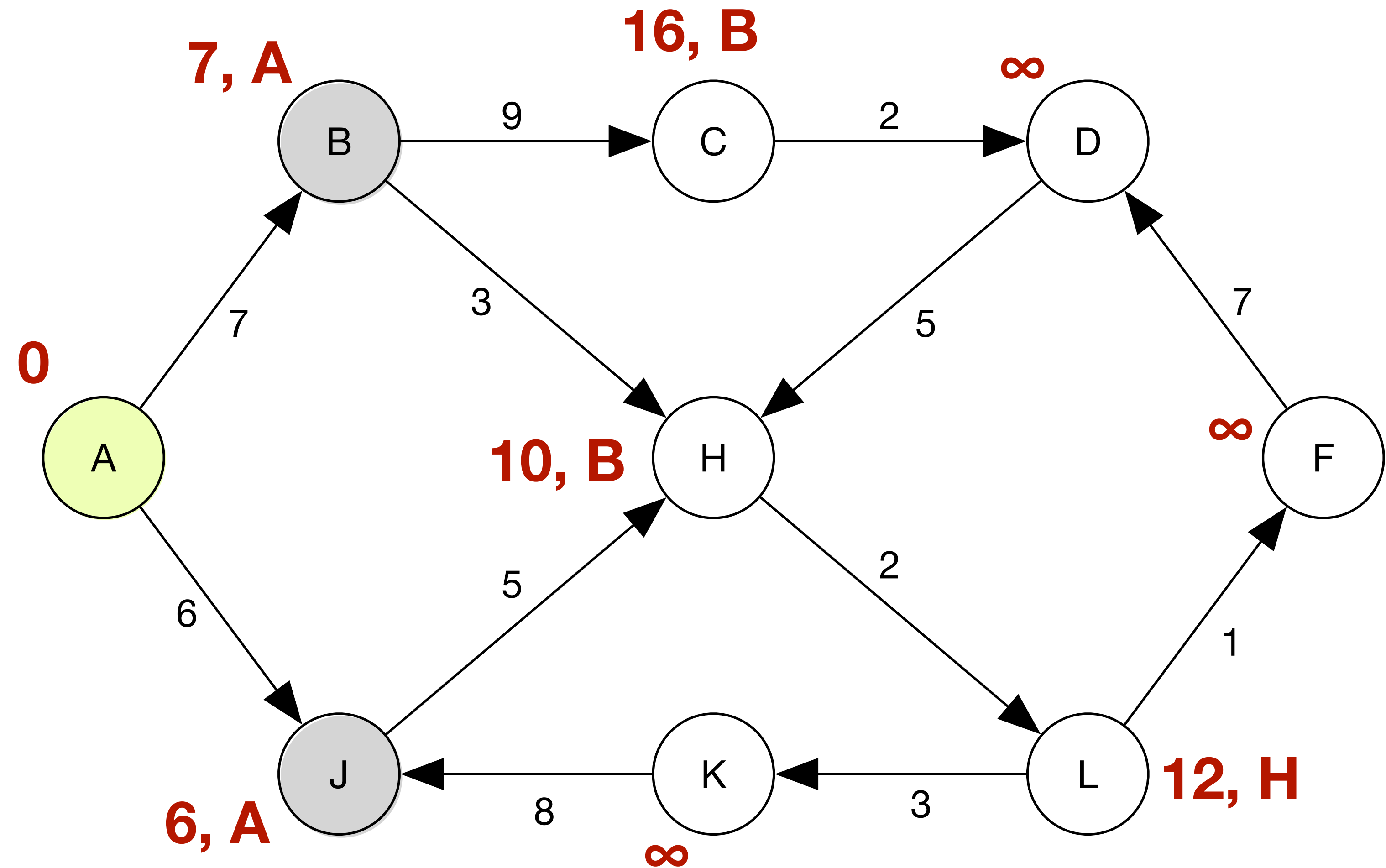


# Dijkstra

Explore from H and calculate distances

Unvisited set

$U = \{C, D, F, H, K, L\}$

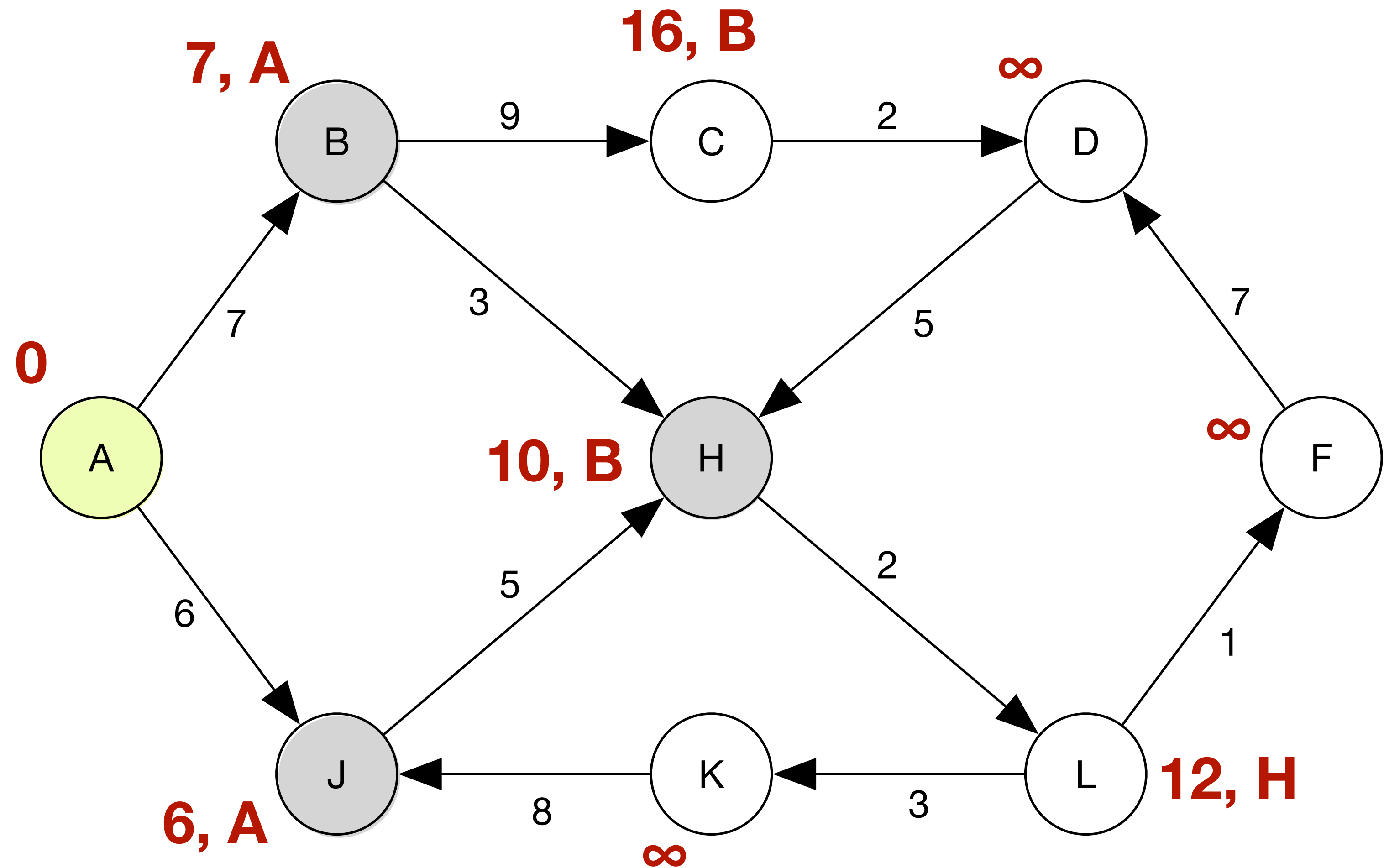


# Dijkstra

Mark H as visited (remove from set U)

Unvisited set

$U = \{C, D, F, K, L\}$



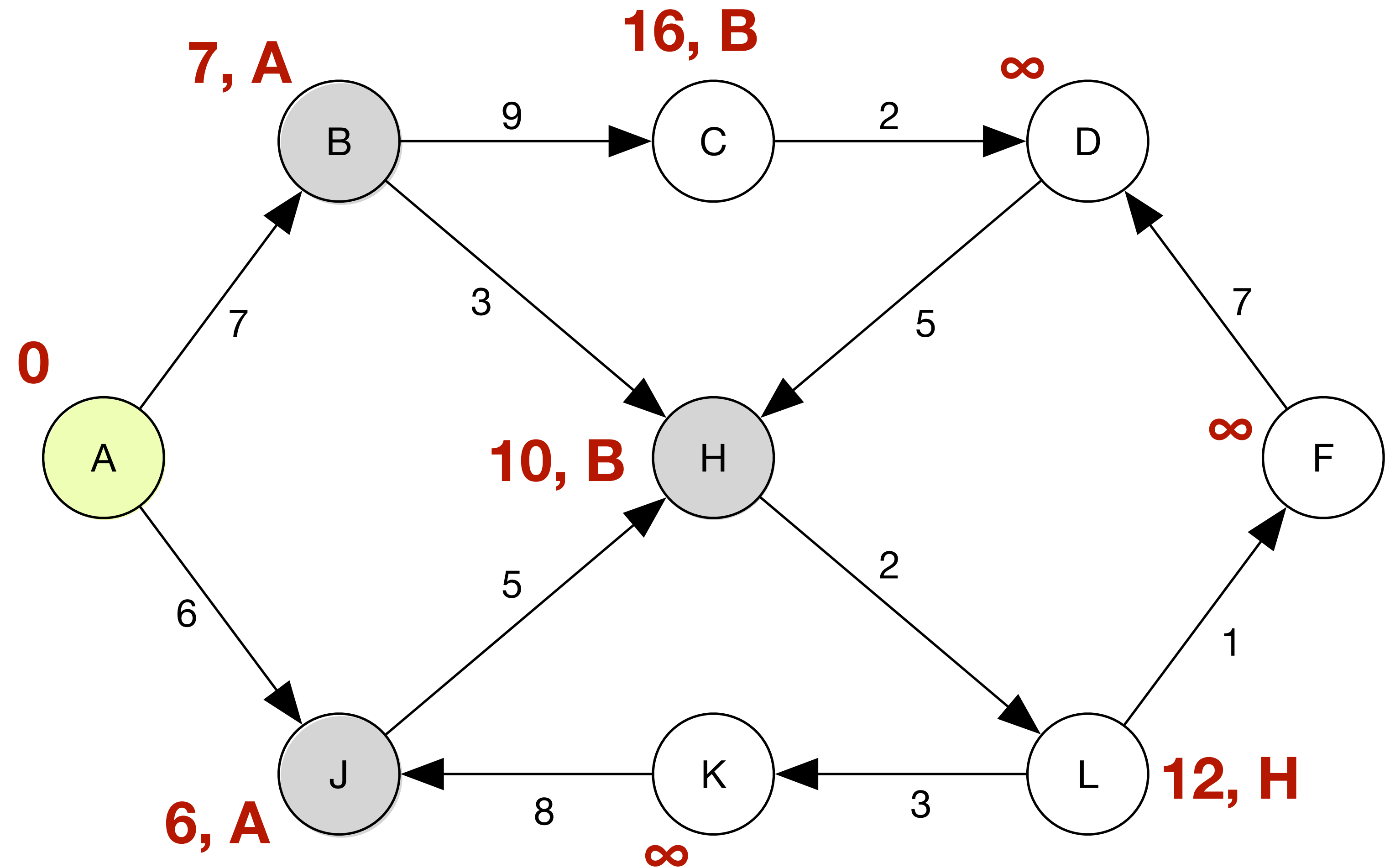


# Dijkstra

Choose next node from which to explore

Unvisited set

$U = \{C, D, F, K, L\}$

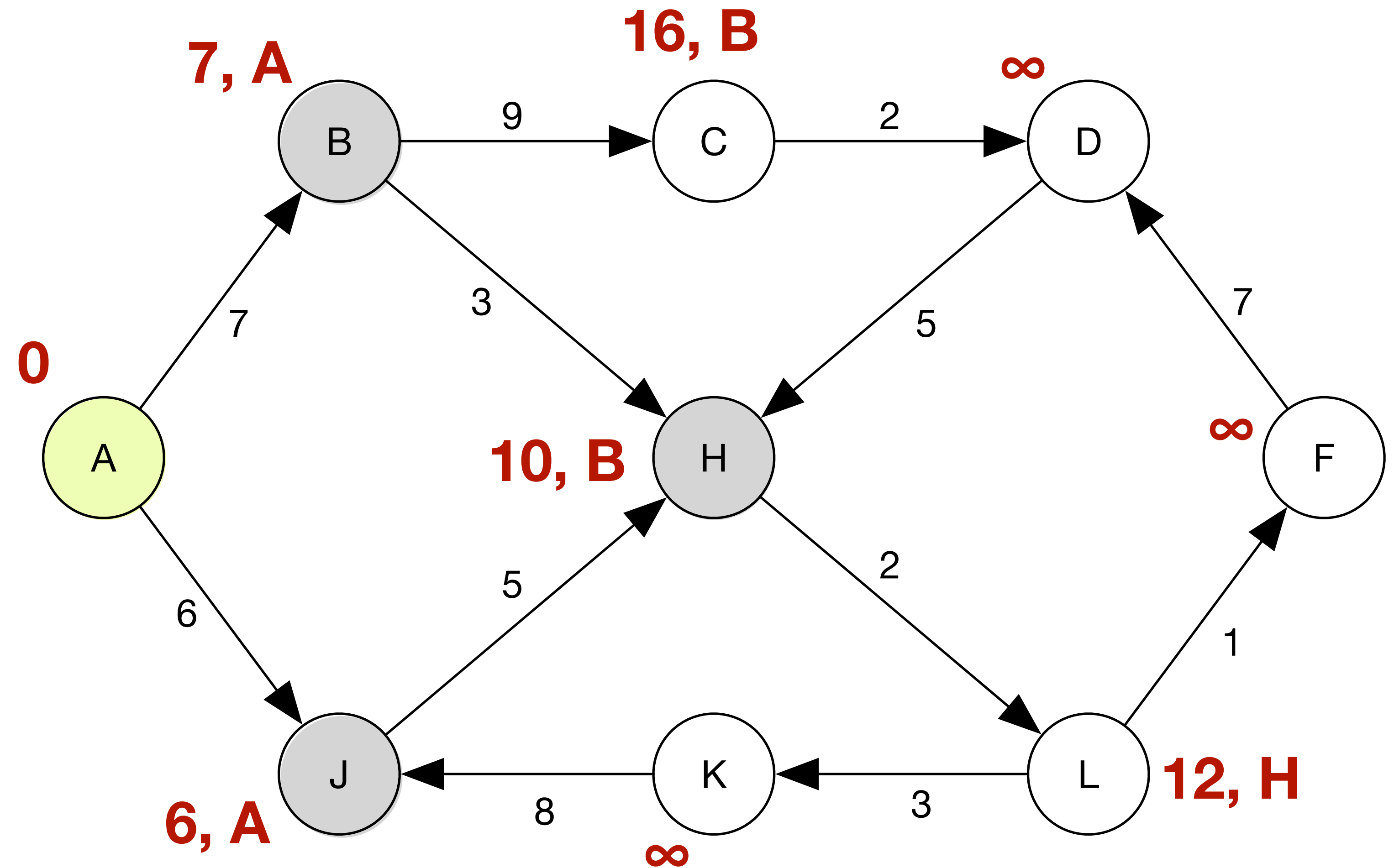


# Dijkstra

Explore from L and calculate distances

Unvisited set

$U = \{C, D, F, K, L\}$

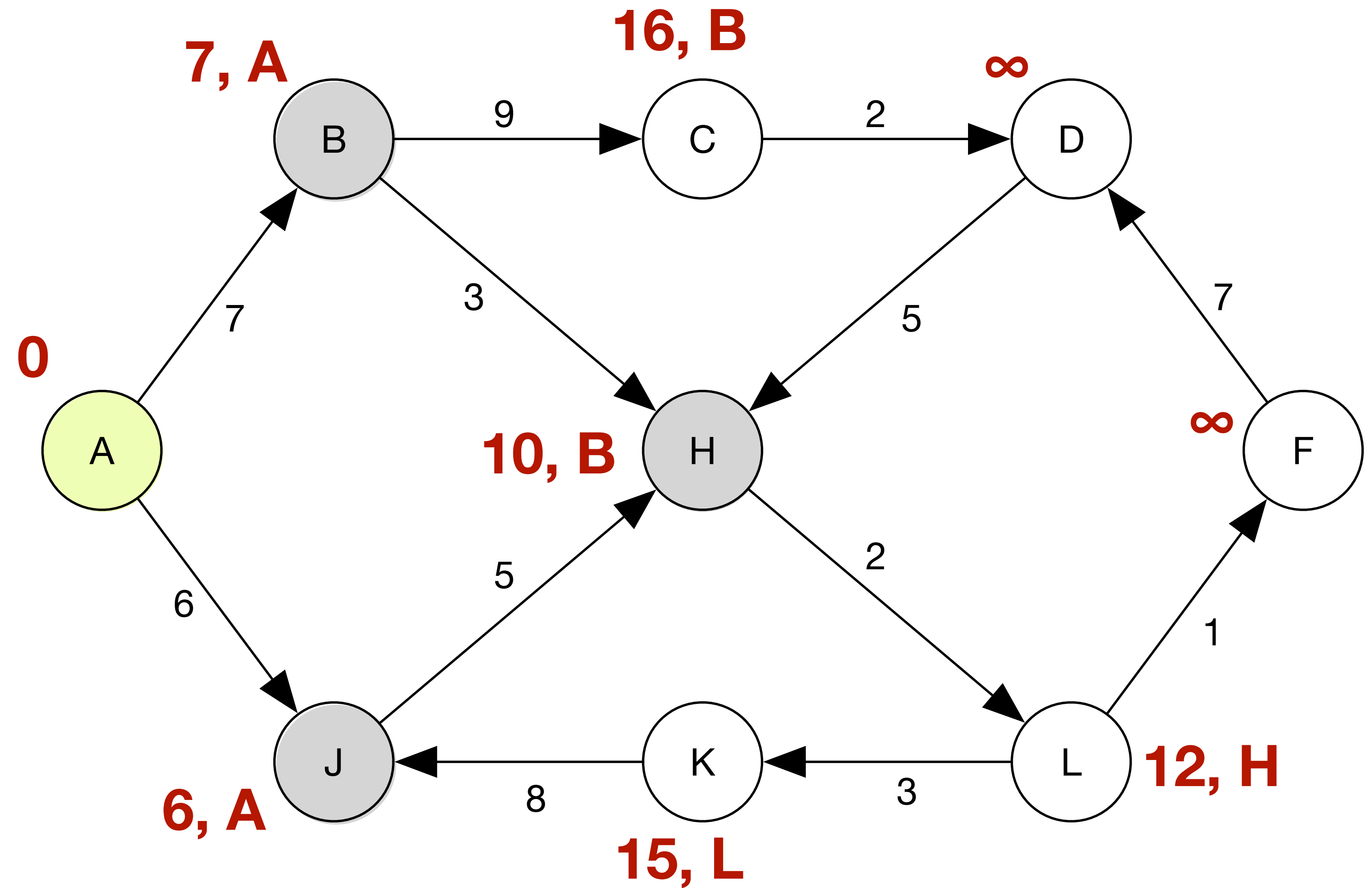


# Dijkstra

Explore from L and calculate distances

Unvisited set

$U = \{C, D, F, K, L\}$

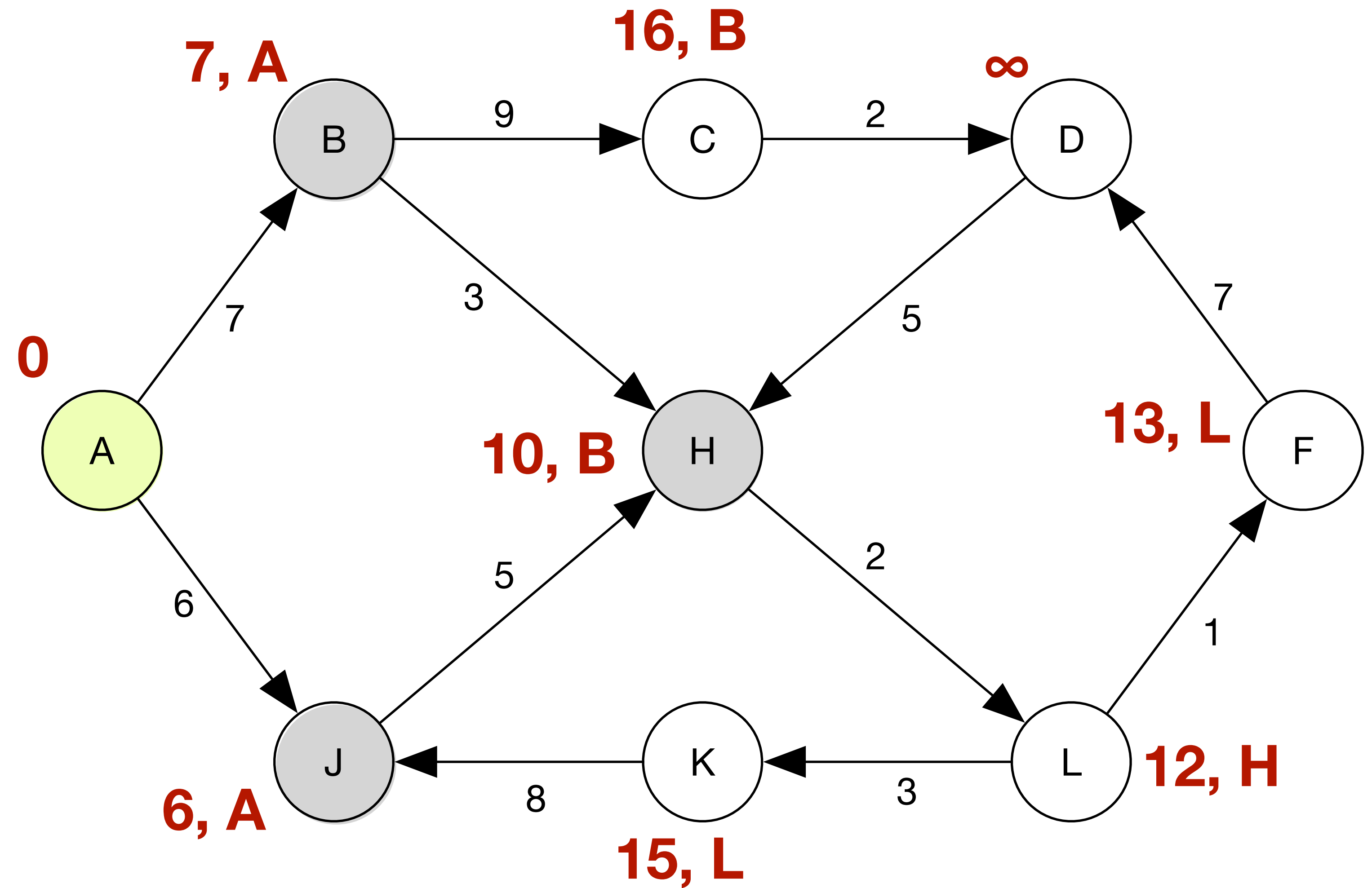


# Dijkstra

Explore from L and calculate distances

Unvisited set

$U = \{C, D, F, K, L\}$

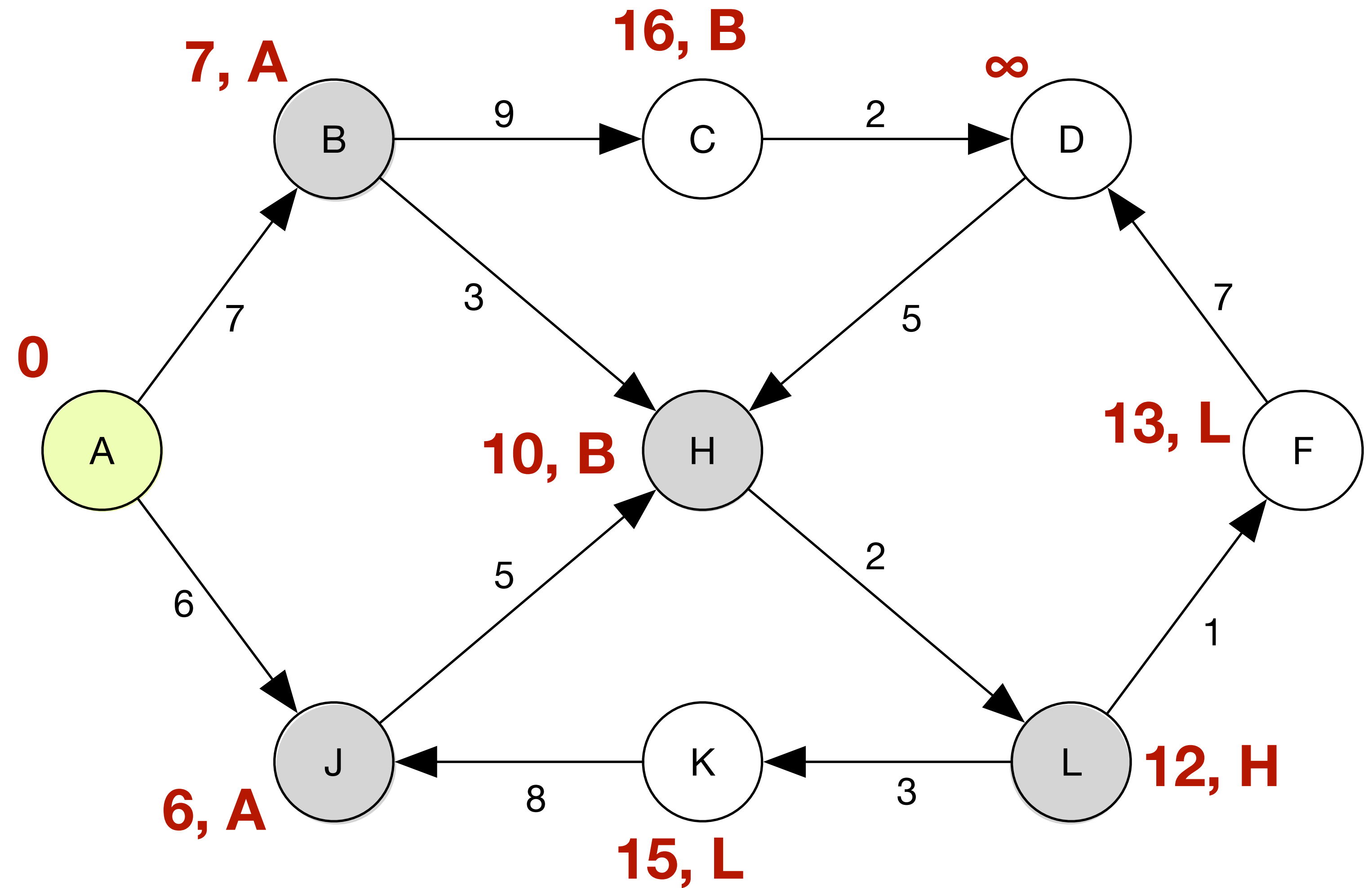


# Dijkstra

Mark L as visited (remove from set U)

Unvisited set

$U = \{C, D, F, K\}$

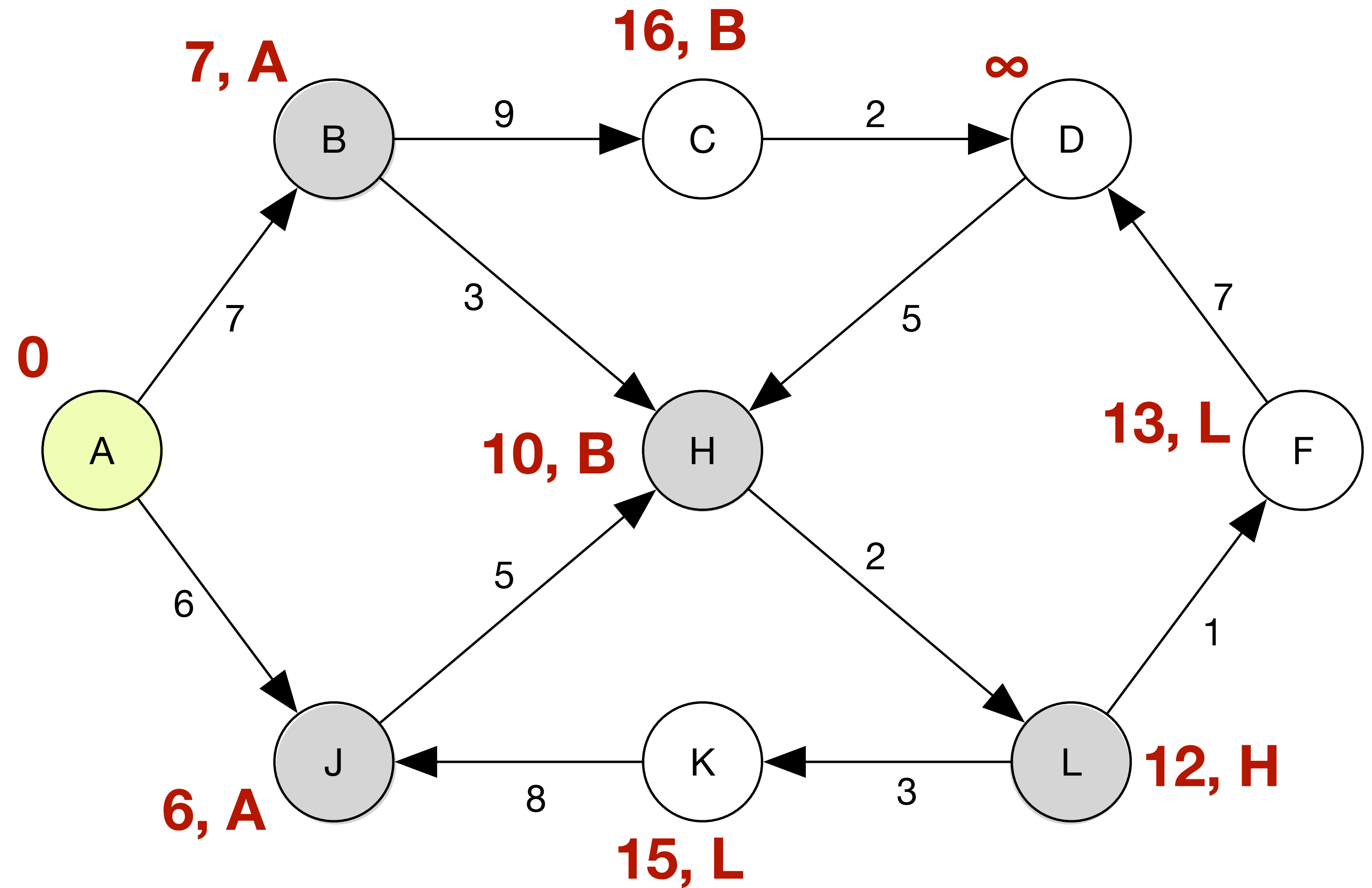


# Dijkstra

Choose next node from which to explore

Unvisited set

$U = \{C, D, F, K\}$

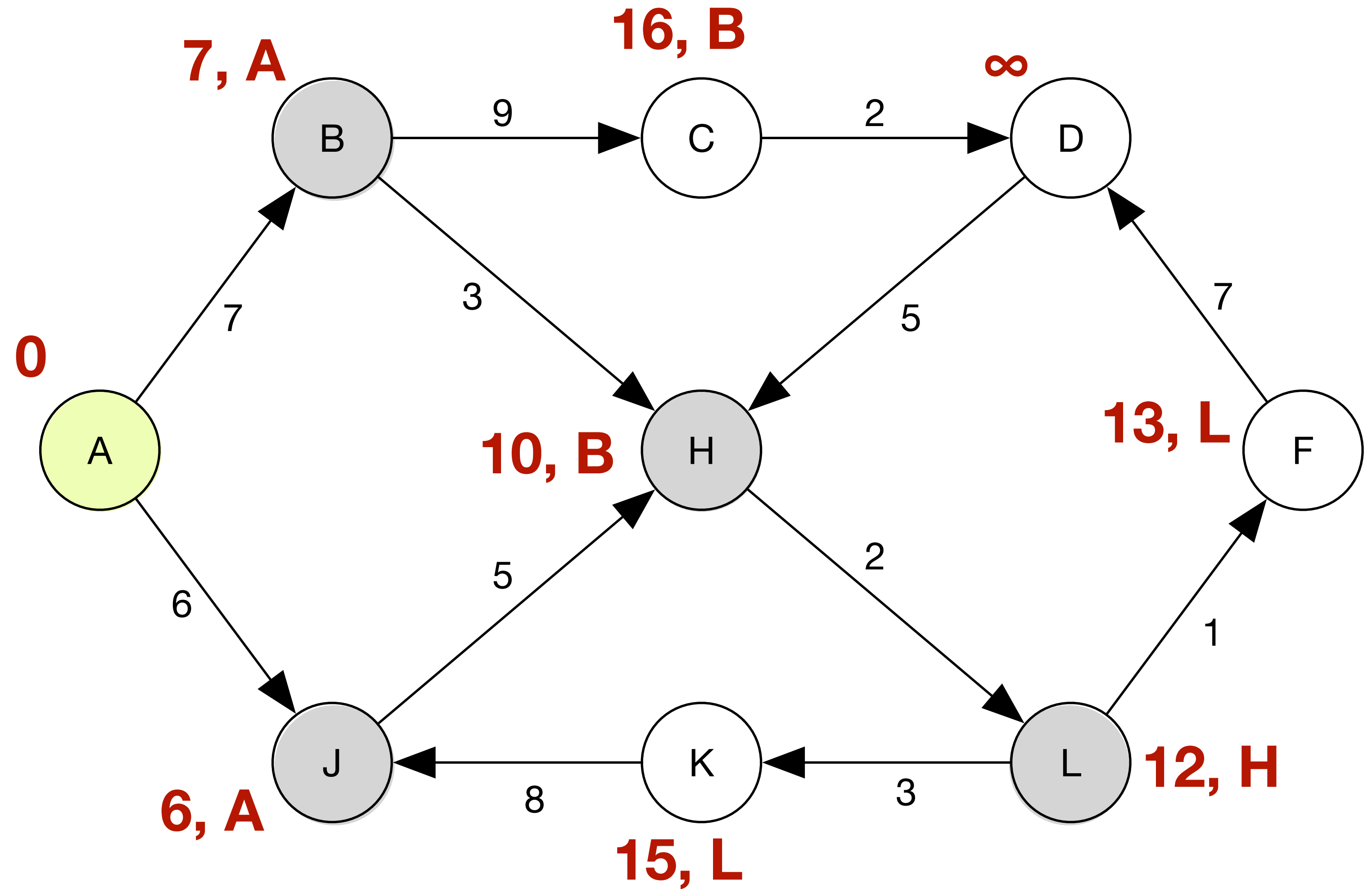


# Dijkstra

Explore from F and calculate distances

Unvisited set

$U = \{C, D, F, K\}$

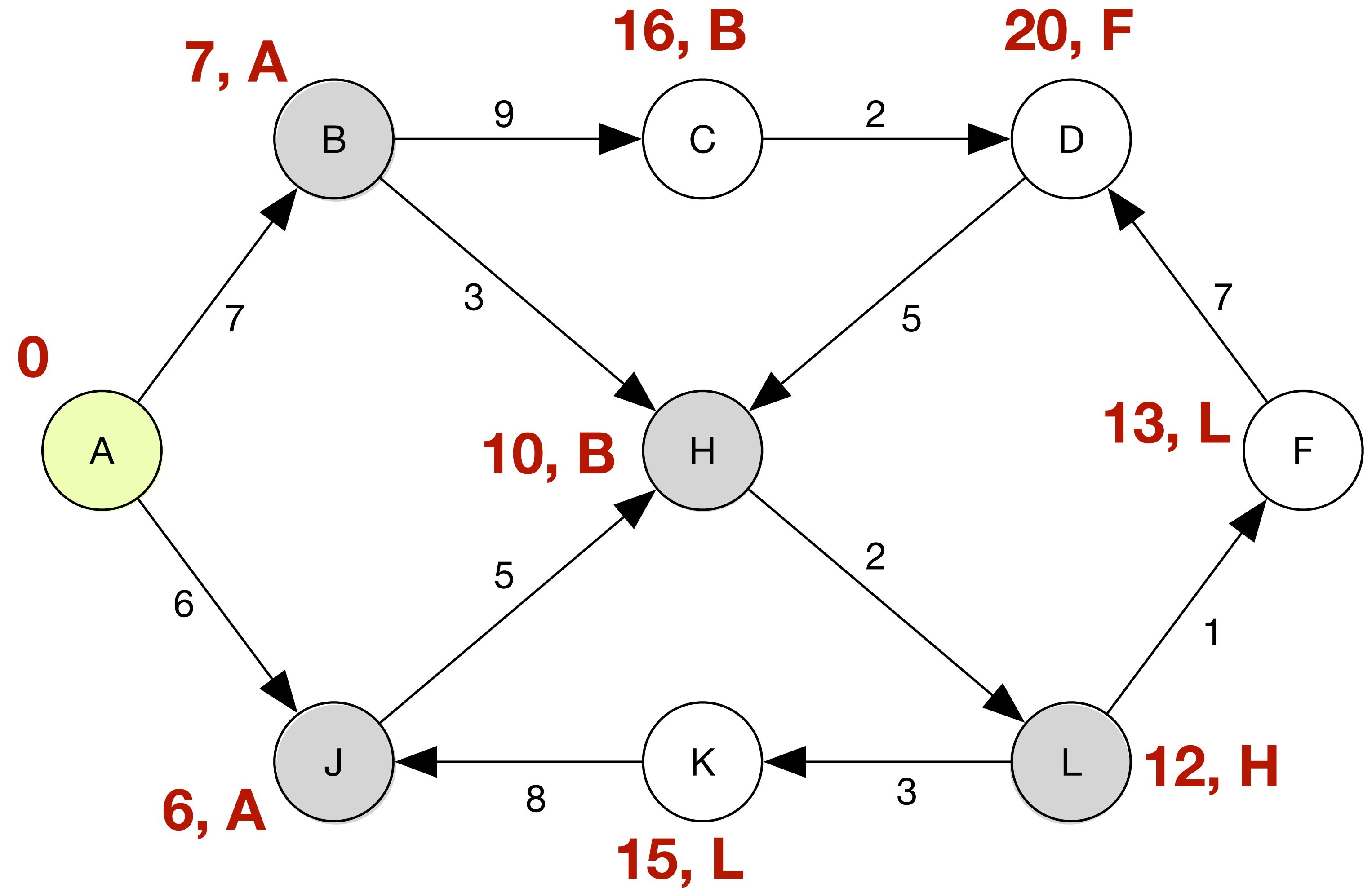


# Dijkstra

Explore from F and calculate distances

Unvisited set

$U = \{C, D, F, K\}$



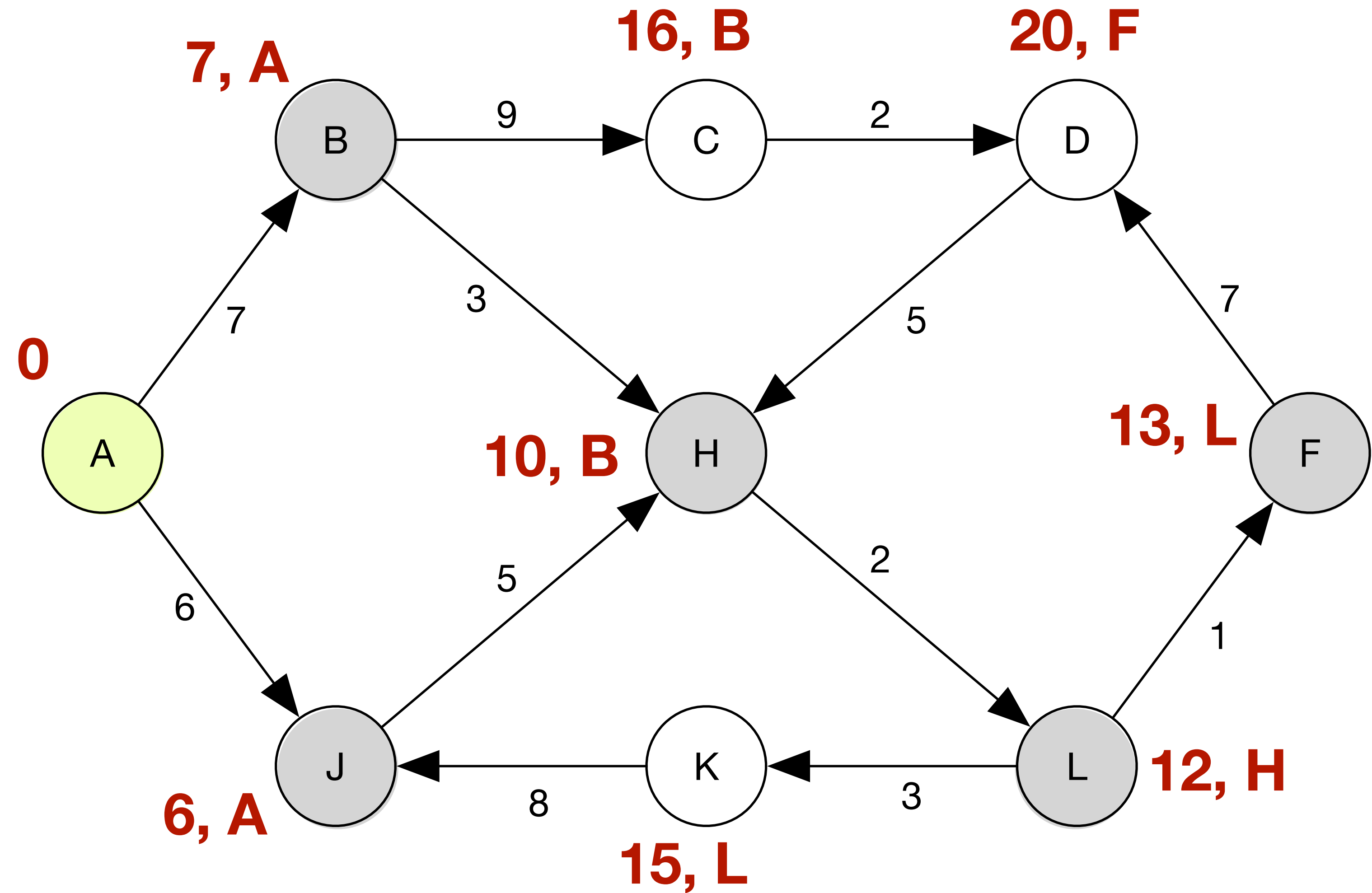


# Dijkstra

Mark F as visited

Unvisited set

$U = \{C, D, K\}$

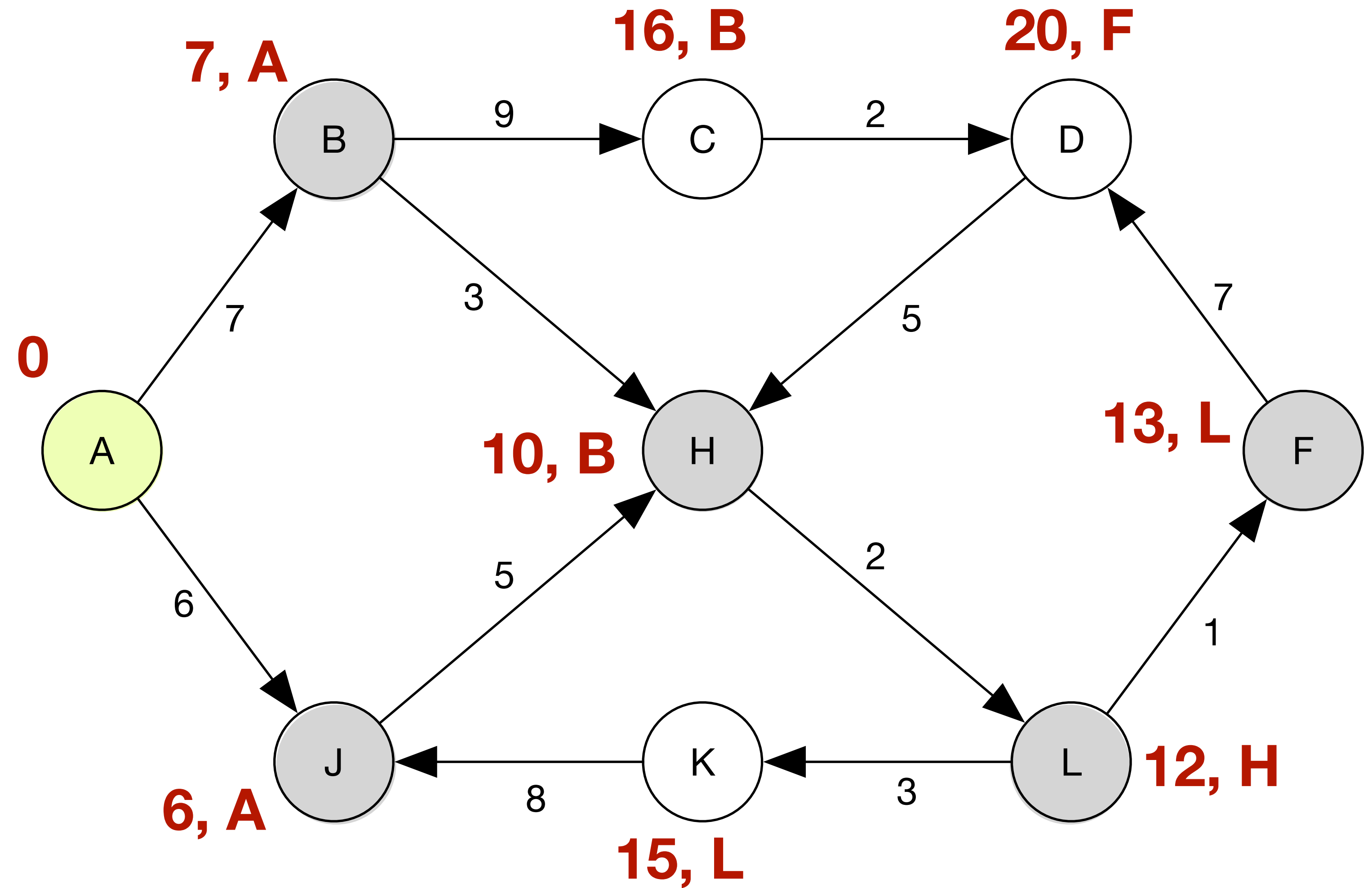


# Dijkstra

Choose next node from which to explore

Unvisited set

$U = \{C, D, K\}$

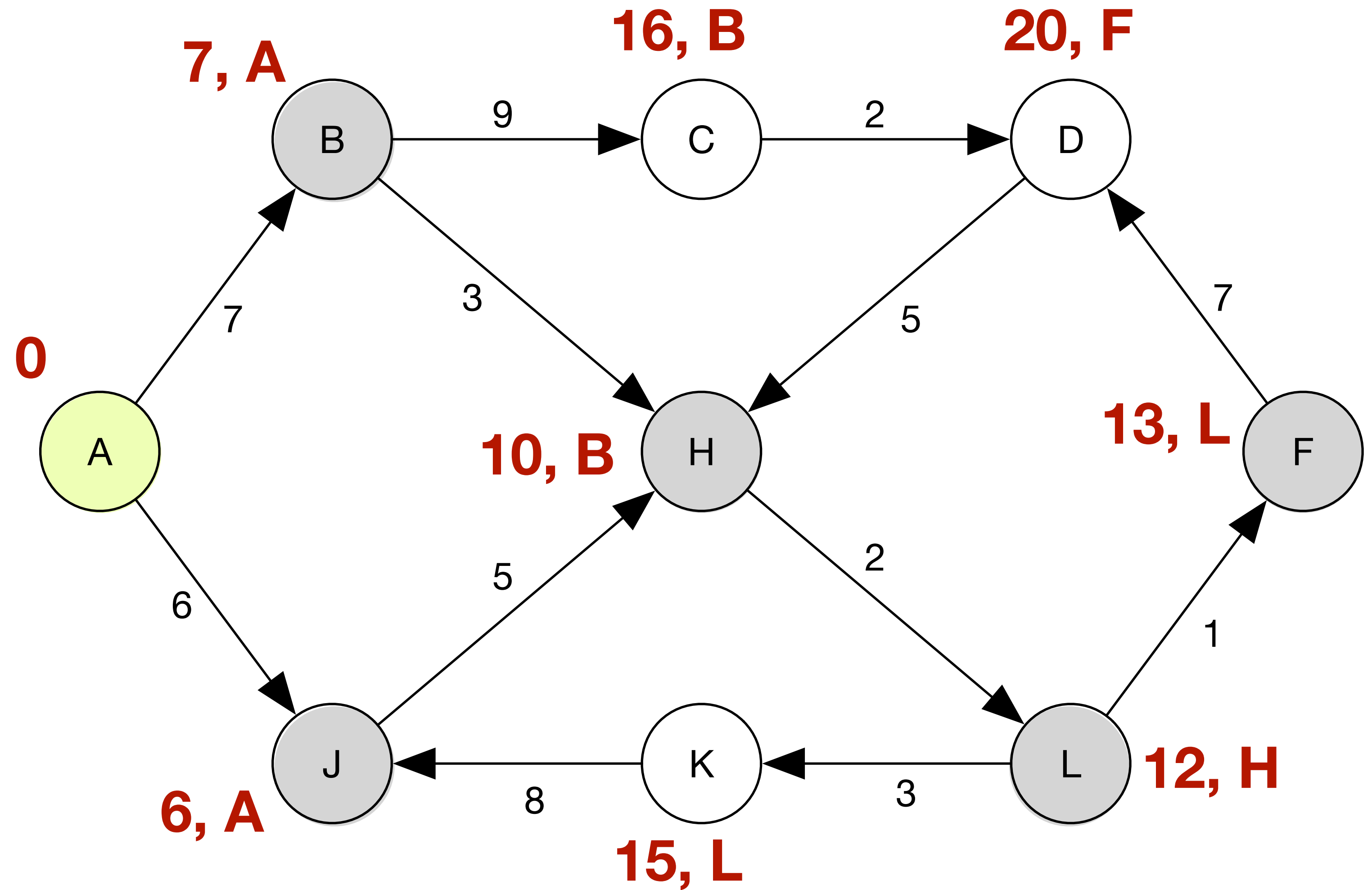


# Dijkstra

Explore from K and calculate distances

Unvisited set

$U = \{C, D, K\}$

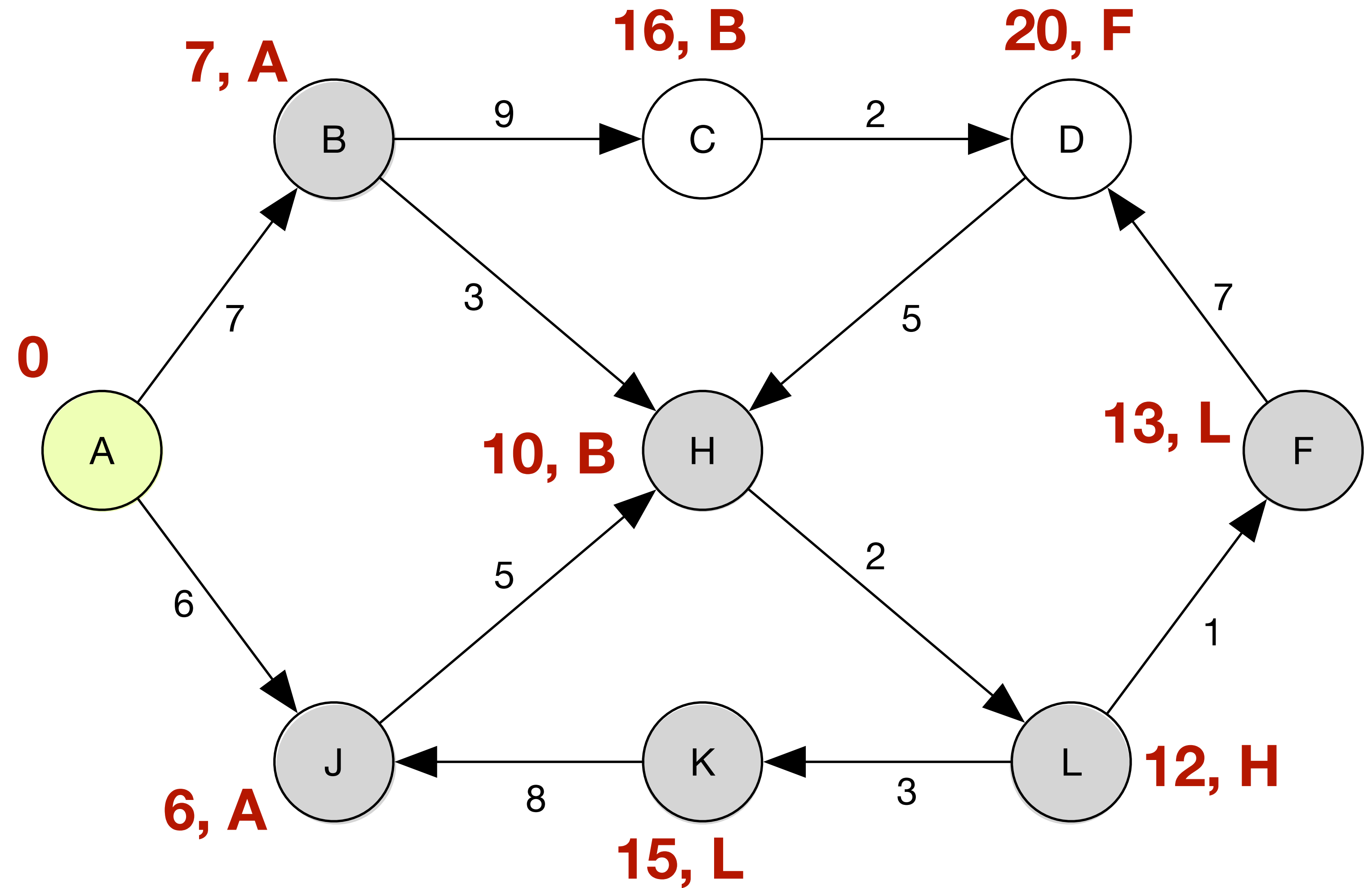


# Dijkstra

Mark K as visited (remove from set U)

Unvisited set

$U = \{C, D\}$

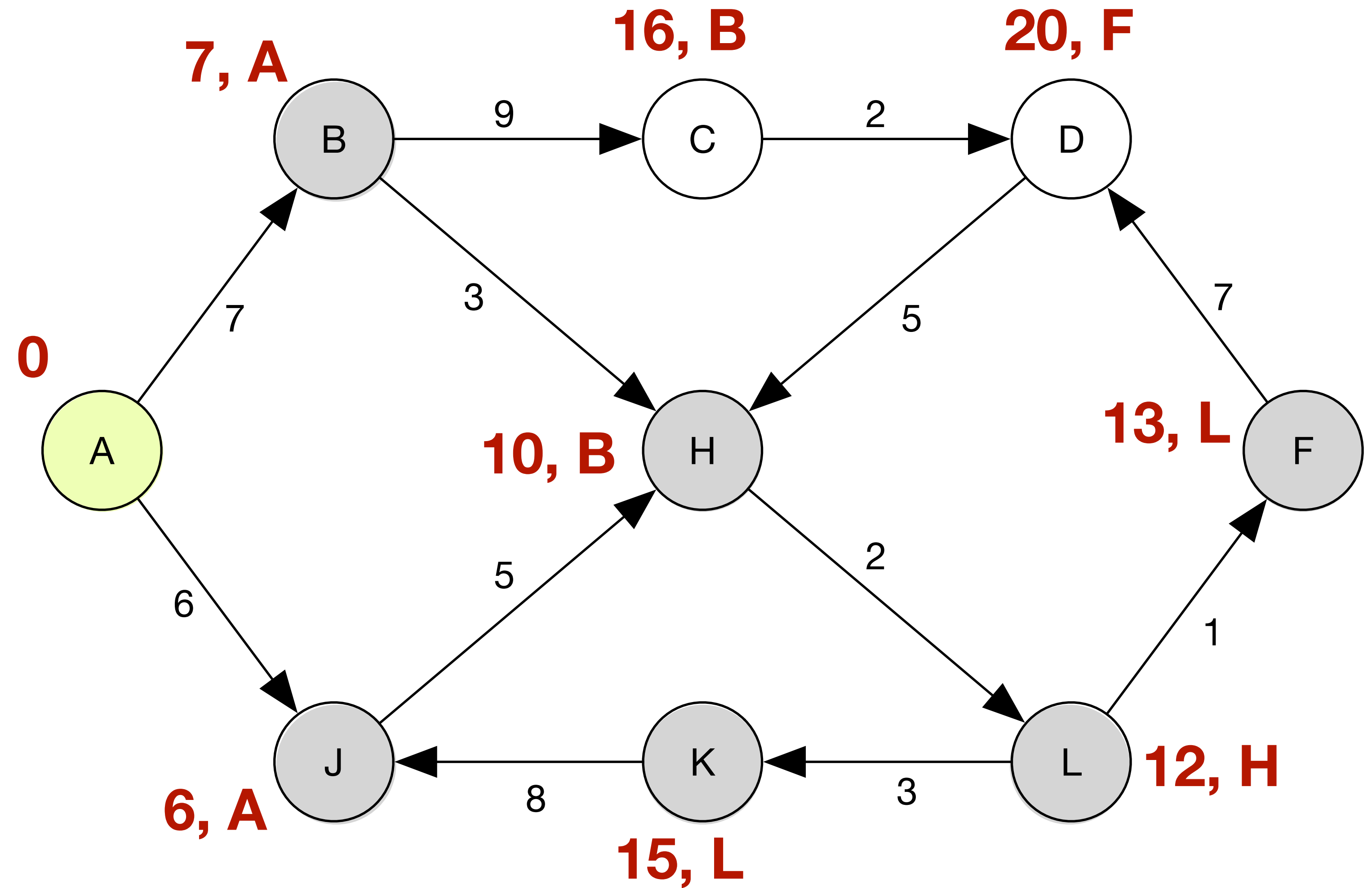


# Dijkstra

Choose next node from which to explore

Unvisited set

$U = \{C, D\}$

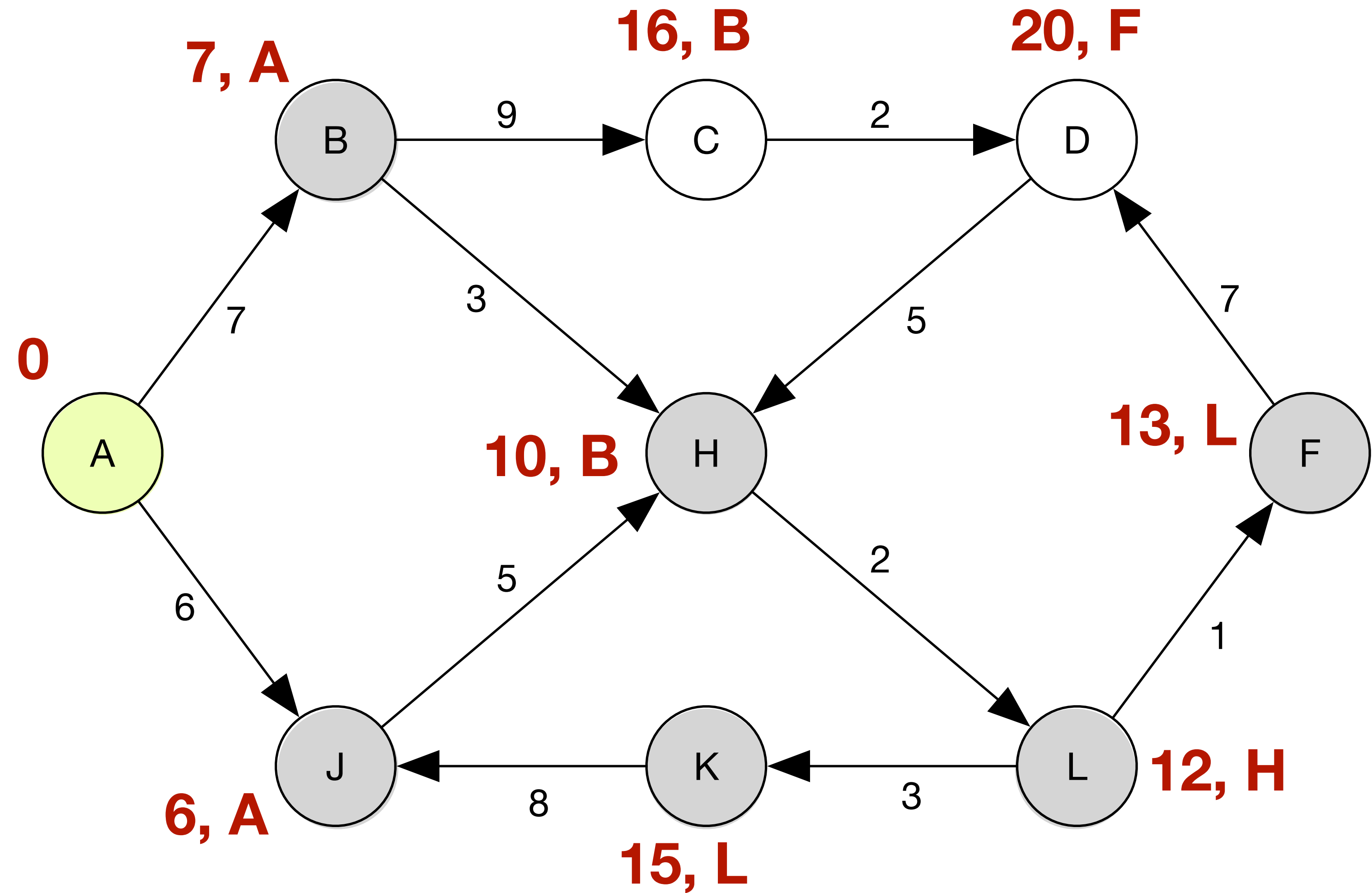


# Dijkstra

Explore from C and calculate distances

Unvisited set

$U = \{C, D\}$

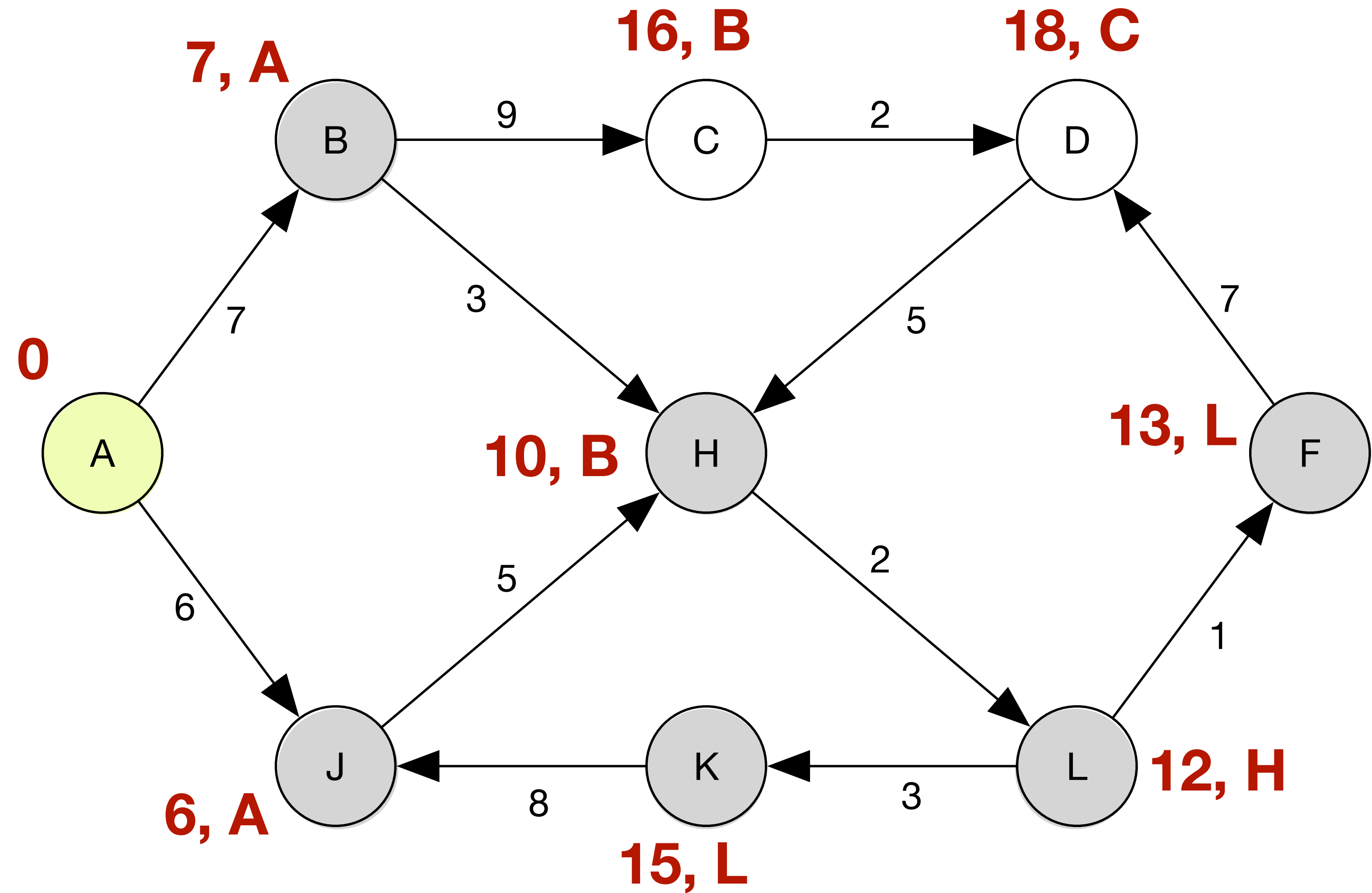


# Dijkstra

Explore from C and calculate distances

Unvisited set

$U = \{C, D\}$

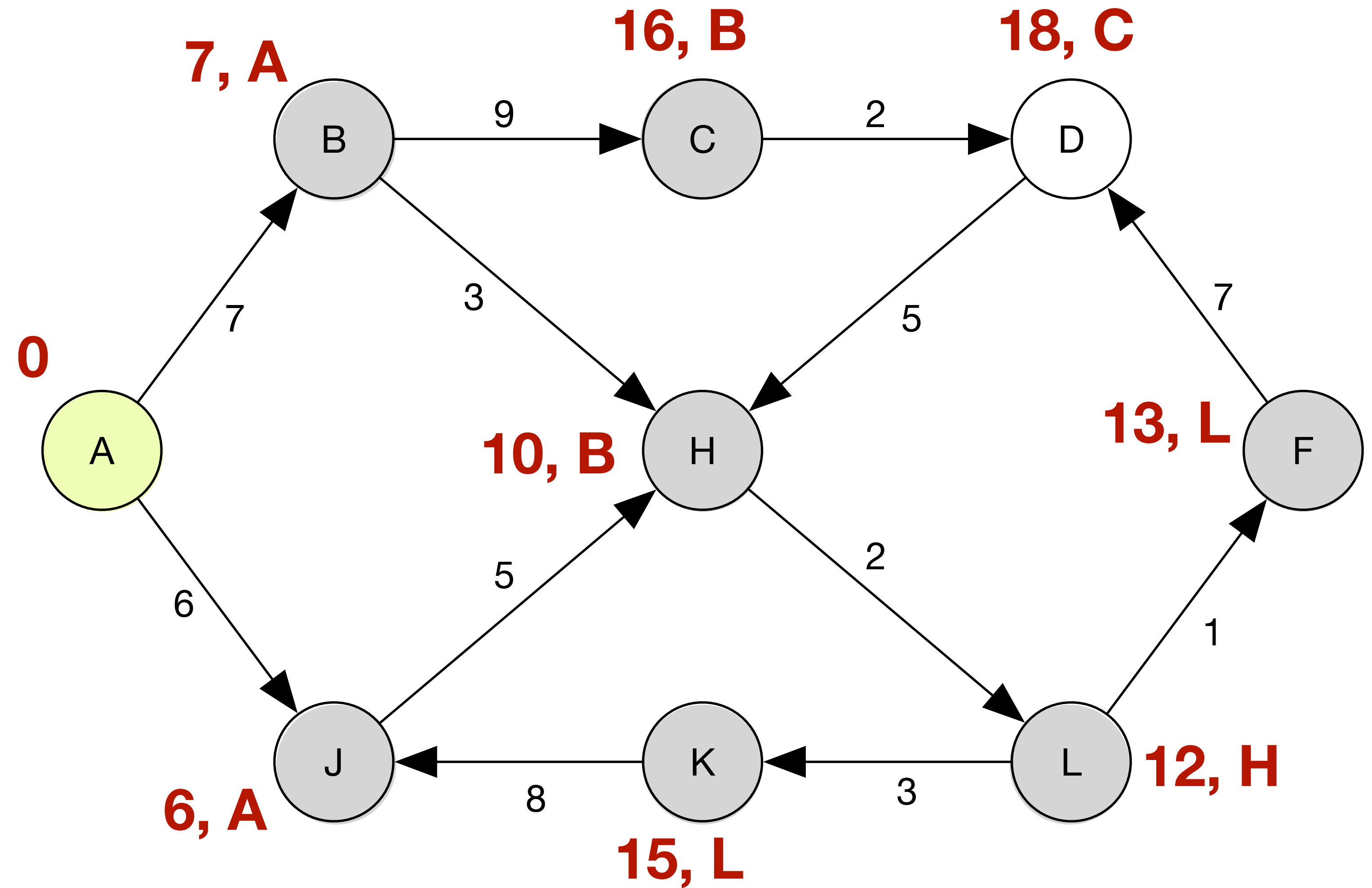


# Dijkstra

Mark C as visited (remove from set U)

Unvisited set

$U = \{D\}$



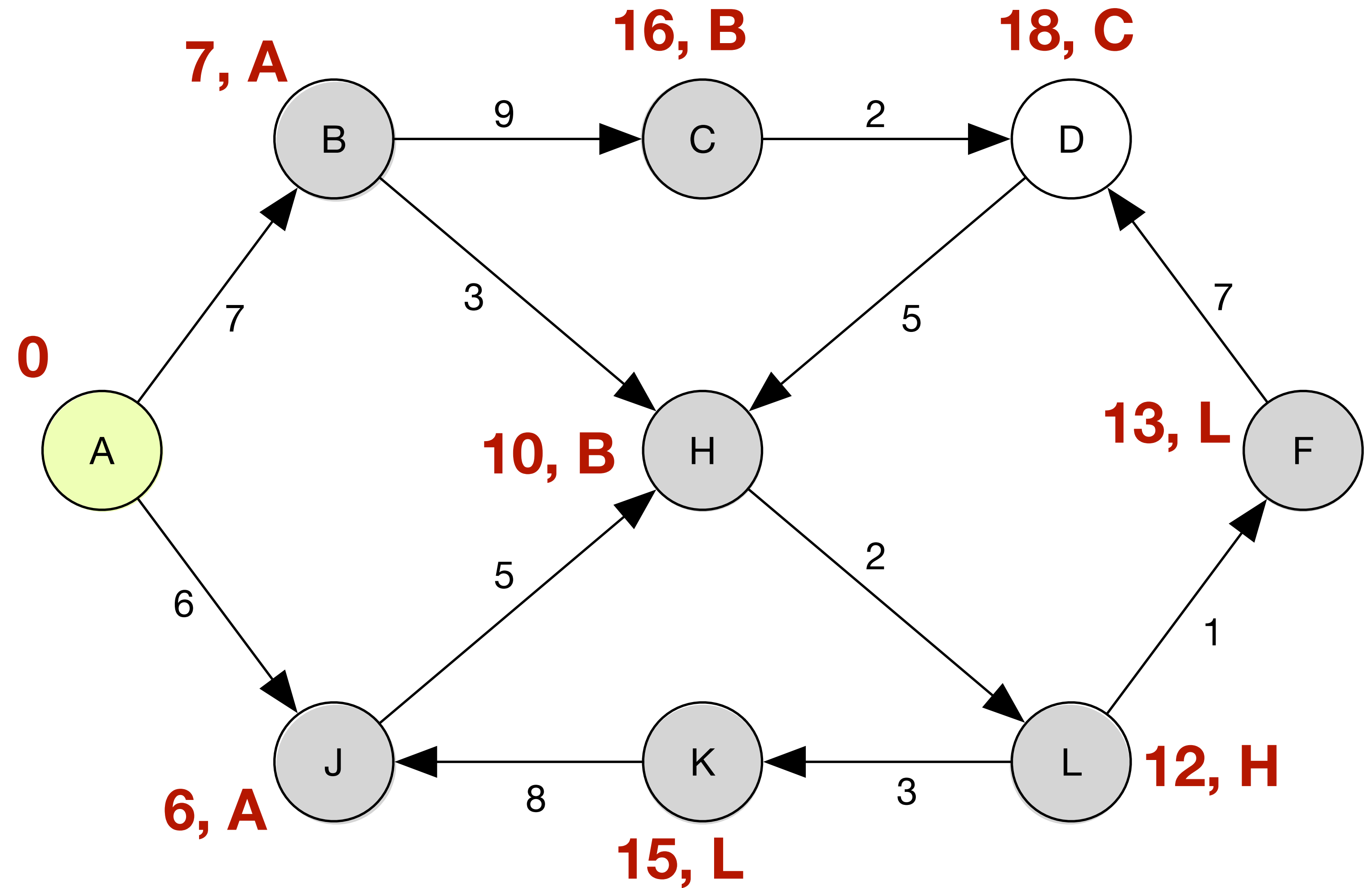


# Dijkstra

Explore from D and calculate distances.

Unvisited set

$U = \{D\}$

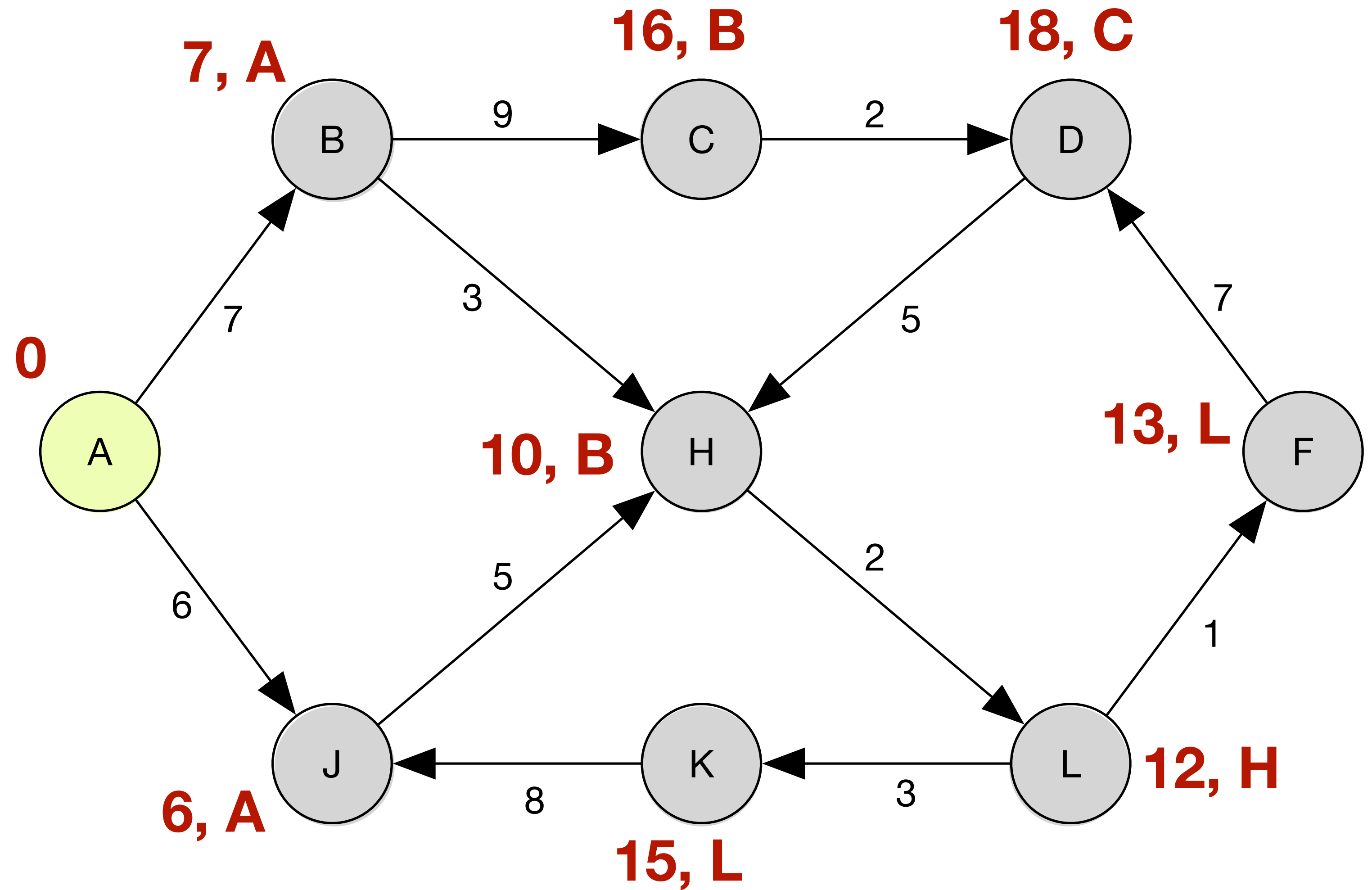


# Dijkstra

Mark D as visited (remove from set U)

Unvisited set

$U = \{\}$

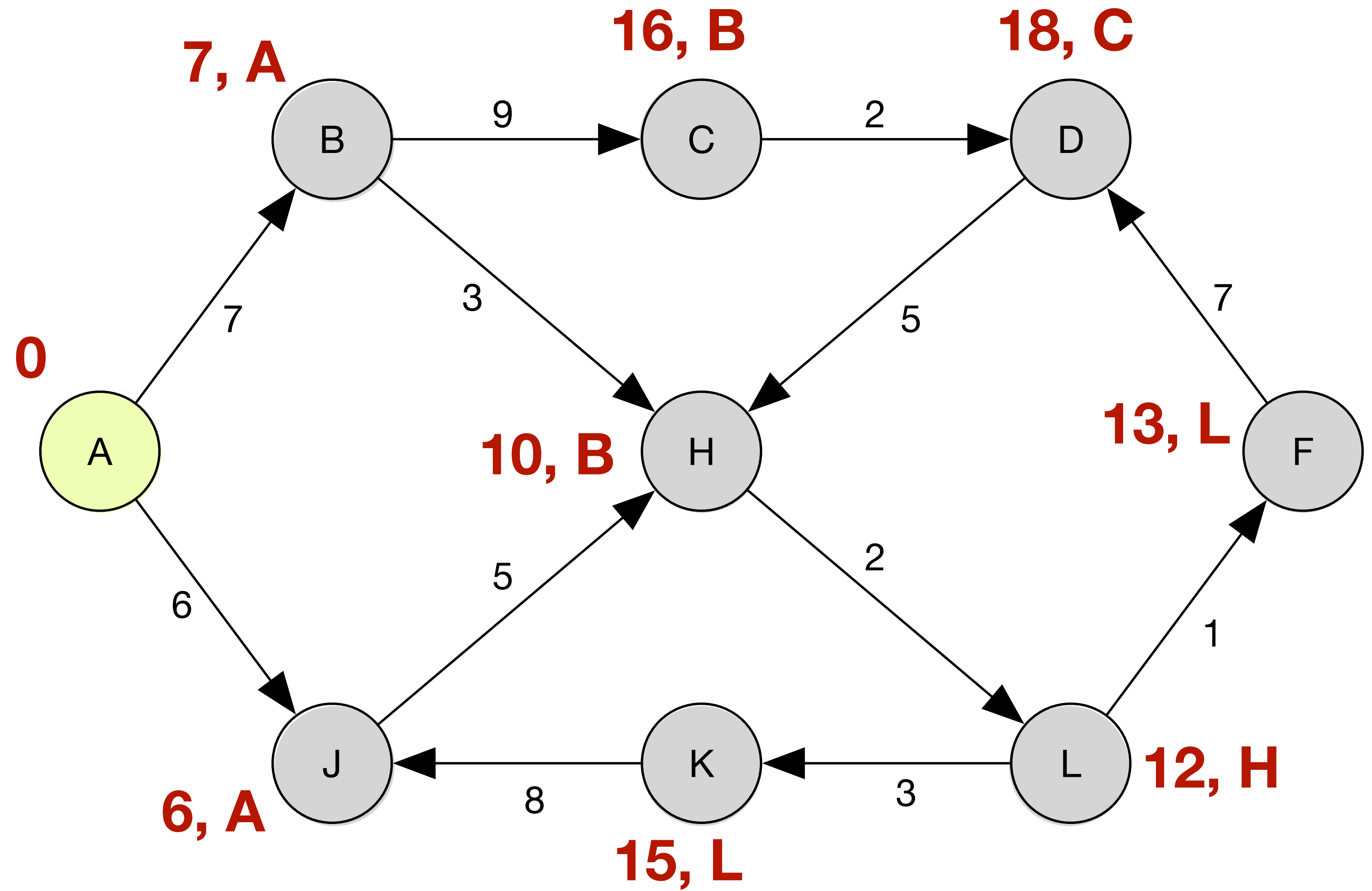


# Dijkstra

Done!

Unvisited set

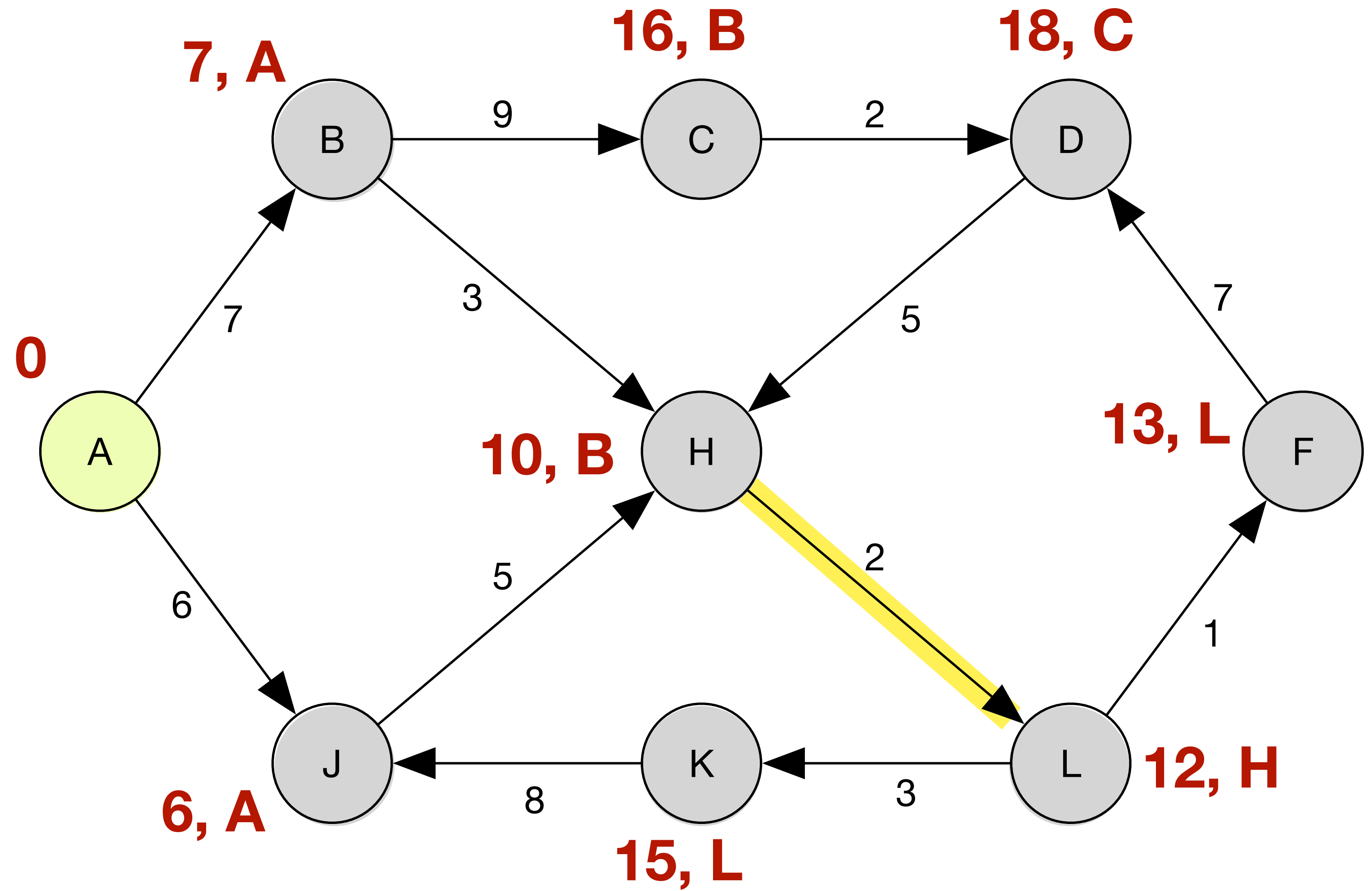
$U = \{\}$



# Dijkstra

Unvisited set

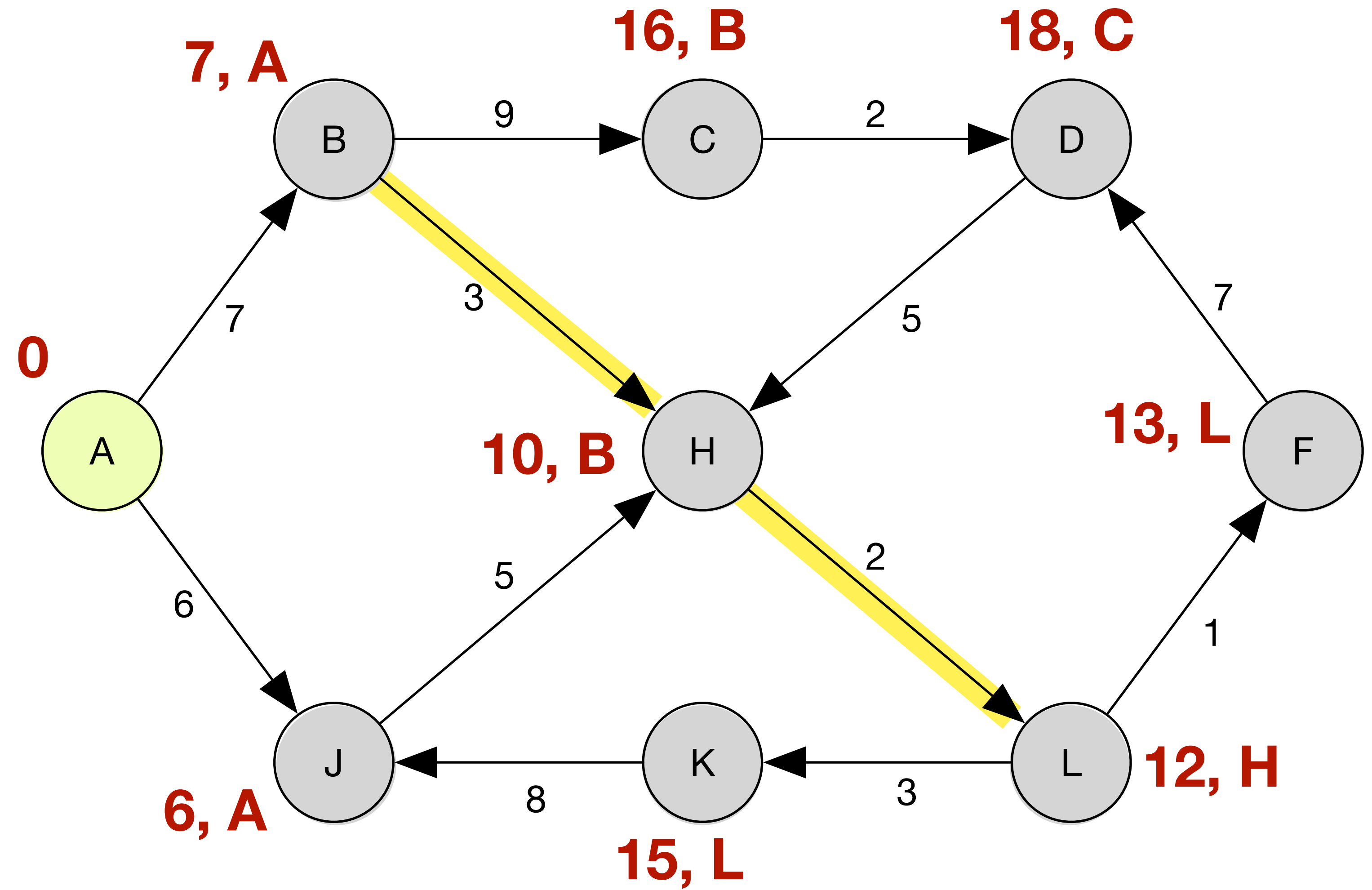
$U = \{\}$



# Dijkstra

Unvisited set

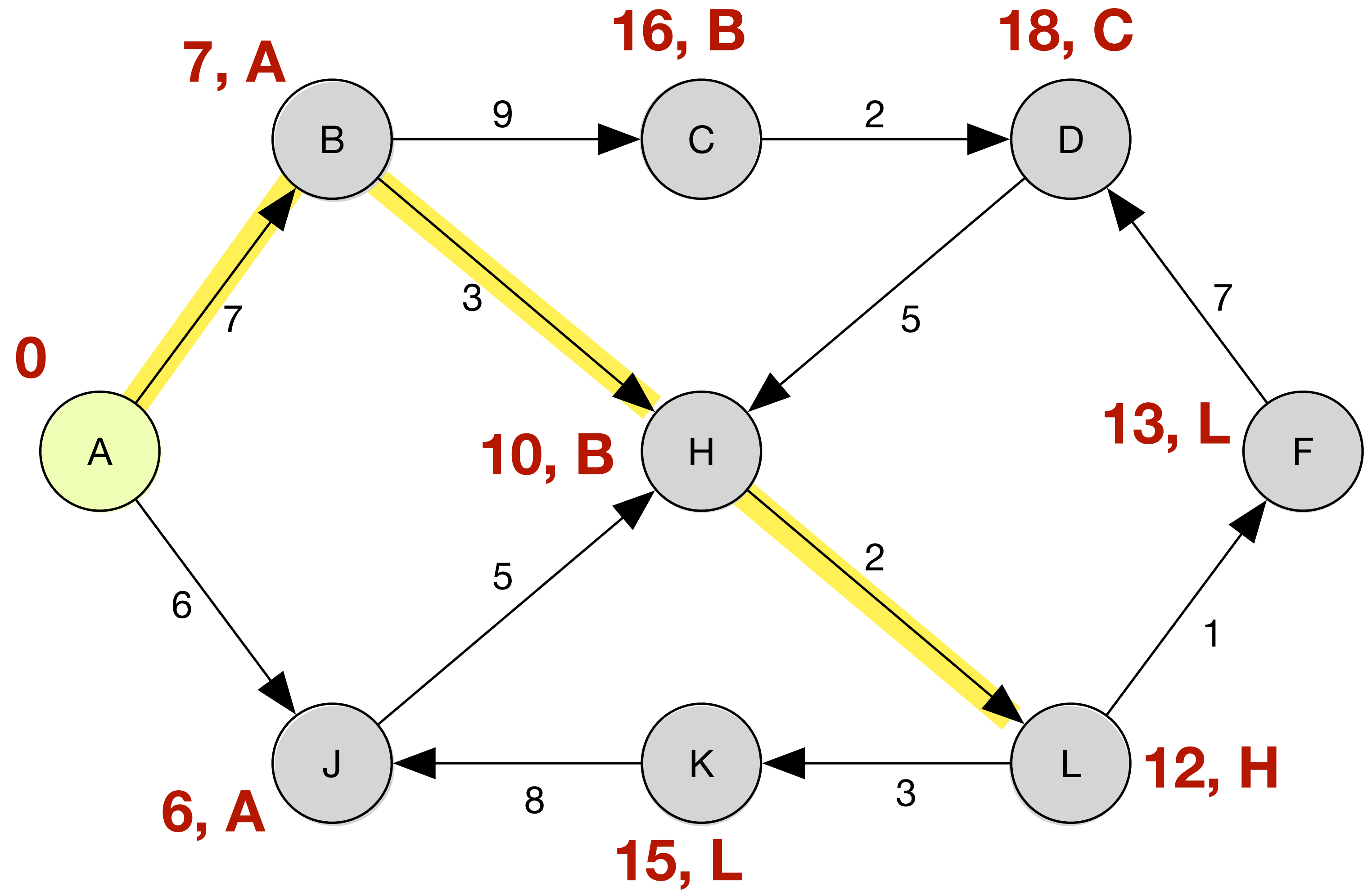
$U = \{\}$



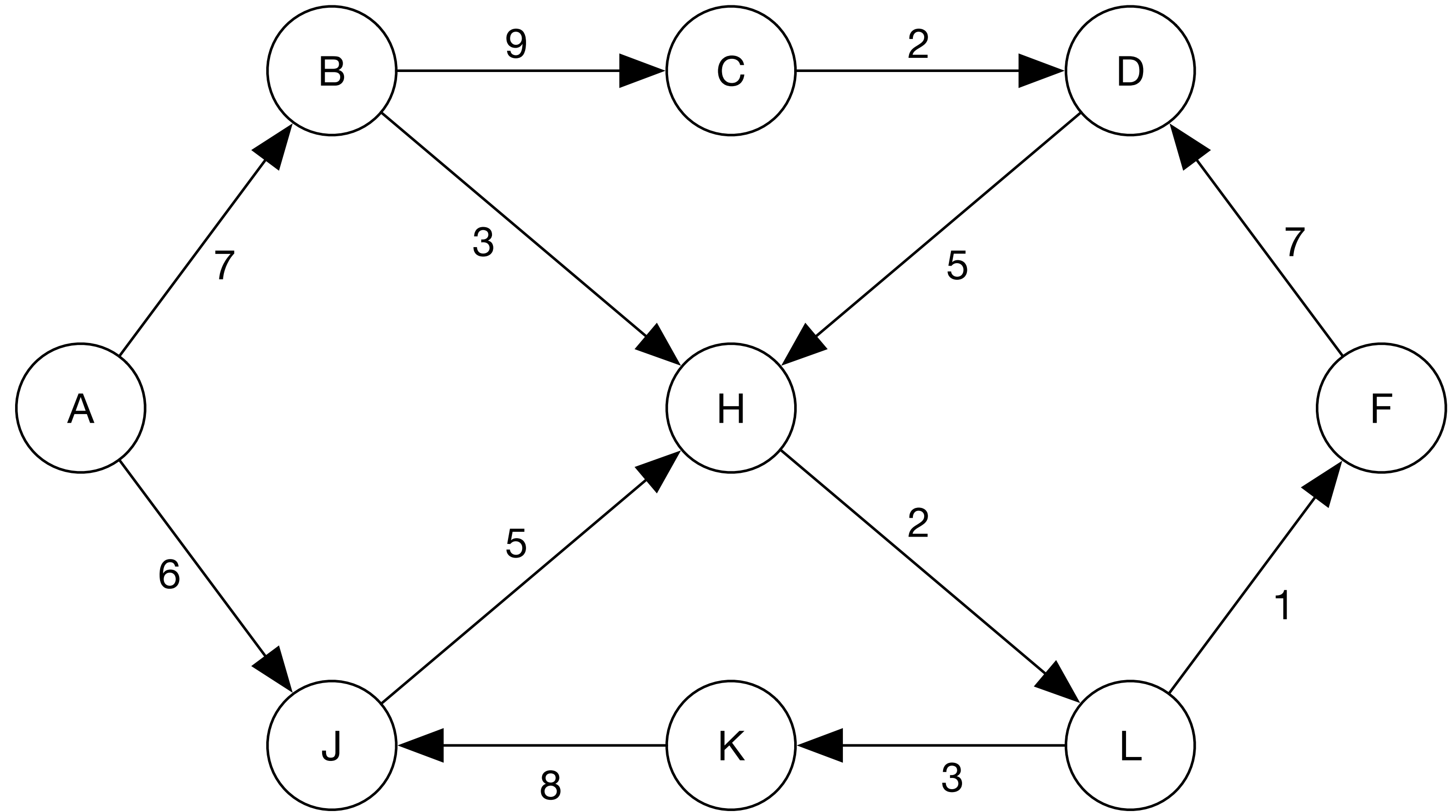
# Dijkstra

Unvisited set

$U = \{\}$



# Dijkstra



# Dijkstra's algorithm

What did you notice about how we chose the nodes to visit?



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We always chose the node with the smallest distance.

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Can you think of a data structure that's handy for always extracting the smallest value?

# Dijkstra's algorithm

What did you notice about how we chose the nodes to visit?

We always chose the node with the smallest distance.

Can you think of a data structure that's handy for always extracting the smallest value?

A minimum priority queue!

# Dijkstra's algorithm: pseudocode

```
function dijkstra(G, S) // G is the graph; S is the starting node
  for each node V in G
    arrived_from[V] = null
    if V = S
      distance[V] = 0
    else
      distance[V] = infinite
    add V to priority queue Q

  while Q is not empty
    V = get min from Q
    for each unvisited neighbor N of V
      distance = distance[V] + distance to N
      if distance < distance[N] // We've found a shorter distance
        distance[N] = distance
        arrived_from[N] = V
```

# Dijkstra's algorithm

Dijkstra's algorithm works for any directed graph so long as all weights are non-negative

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Worst case complexity (using min priority queue)

$$\mathcal{O}((|V| + |E|) \log|V|)$$

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Dijkstra's algorithm works for any directed graph so long as all weights are non-negative

Worst case complexity (using min priority queue)

$$\mathcal{O}((|V| + |E|) \log|V|)$$

Greedy algorithm. Always chooses the best (shortest) distance found so far.

# Dijkstra's algorithm

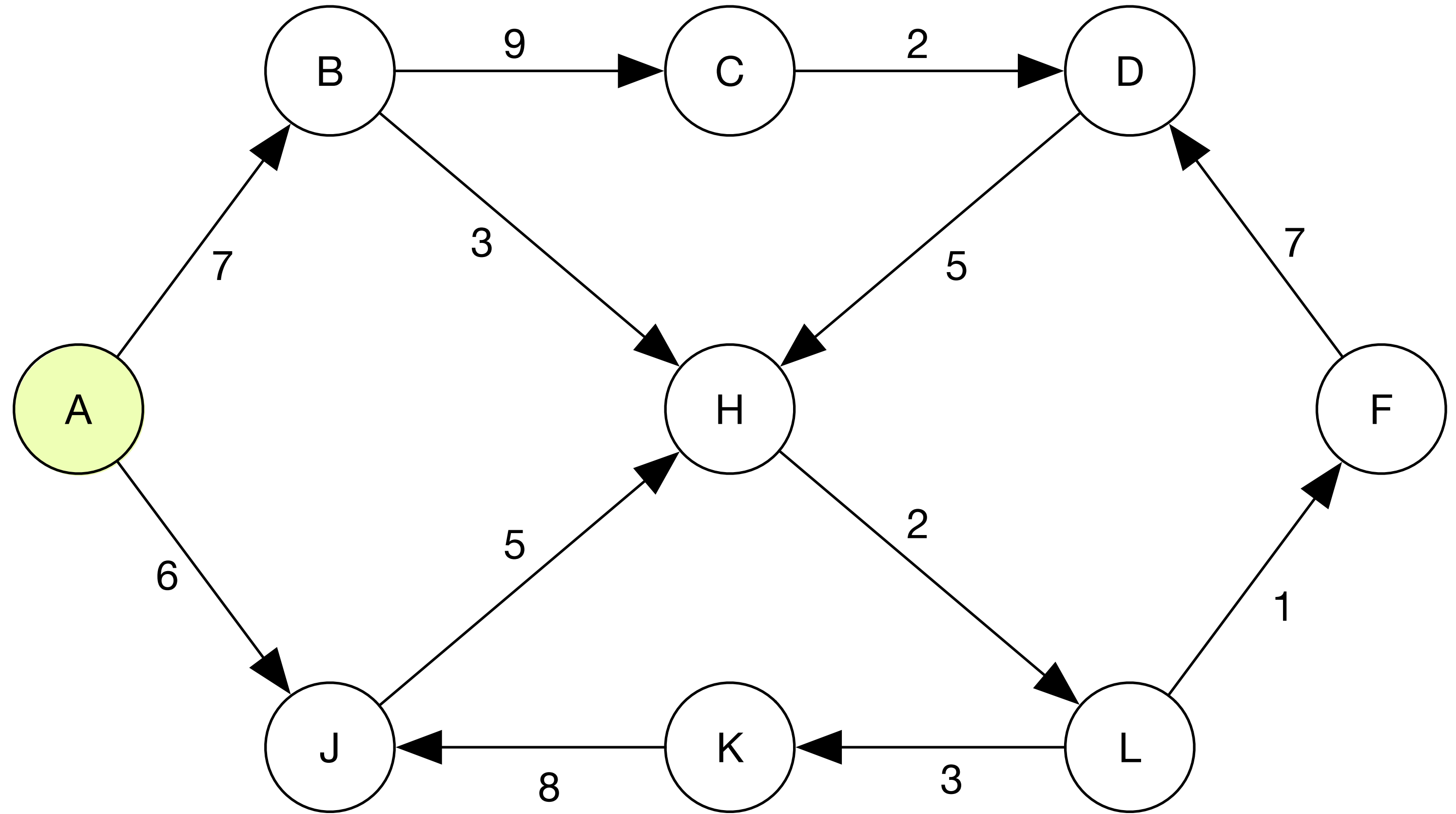
Greedy approach. We always use the best (shortest) distance we've calculated so far, and we never go back -- once a node is marked as visited we never revisit it.



# Dijkstra

Unvisited set

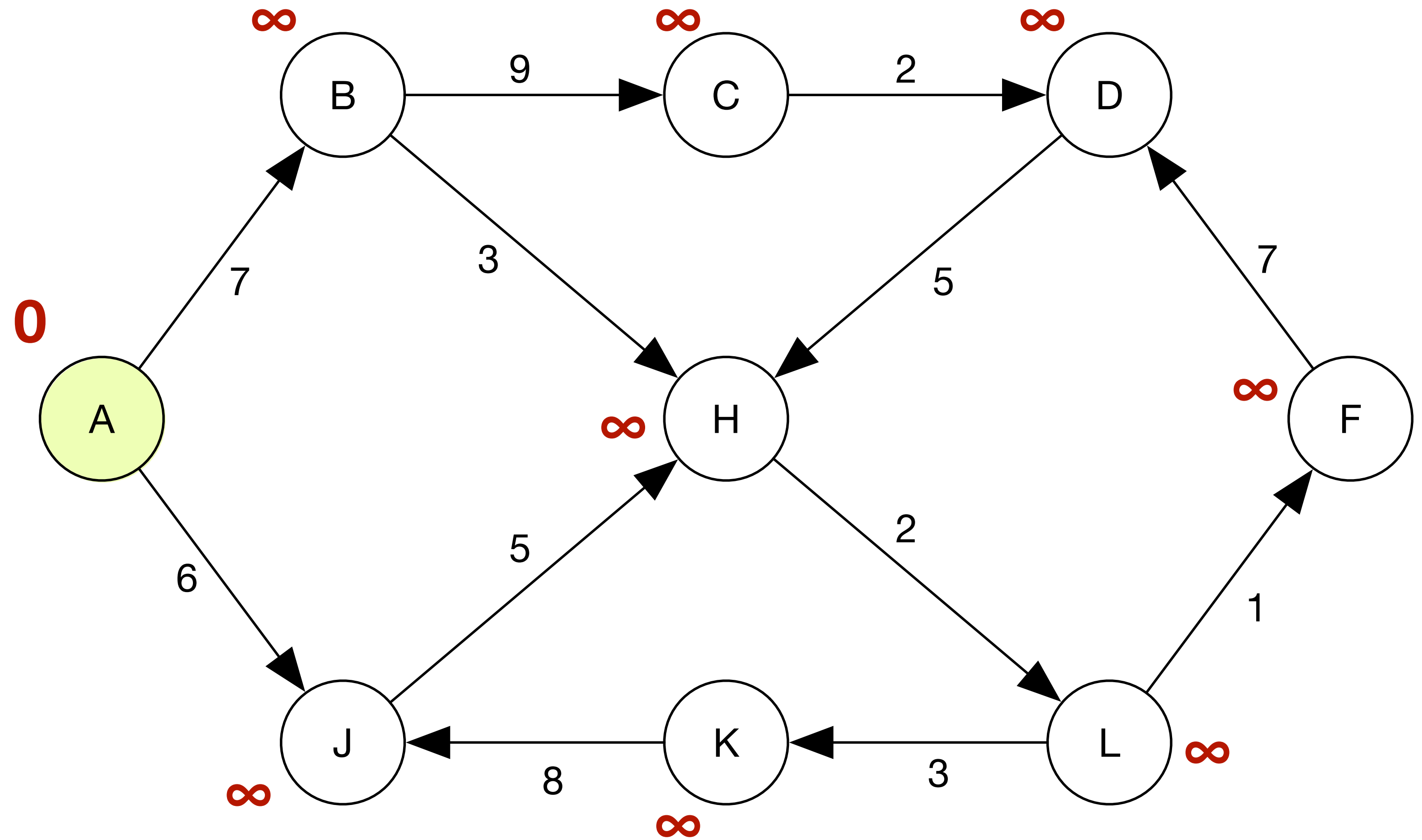
$U = \{A, B, C, D, F, H, J, K, L\}$



# Dijkstra

Unvisited set

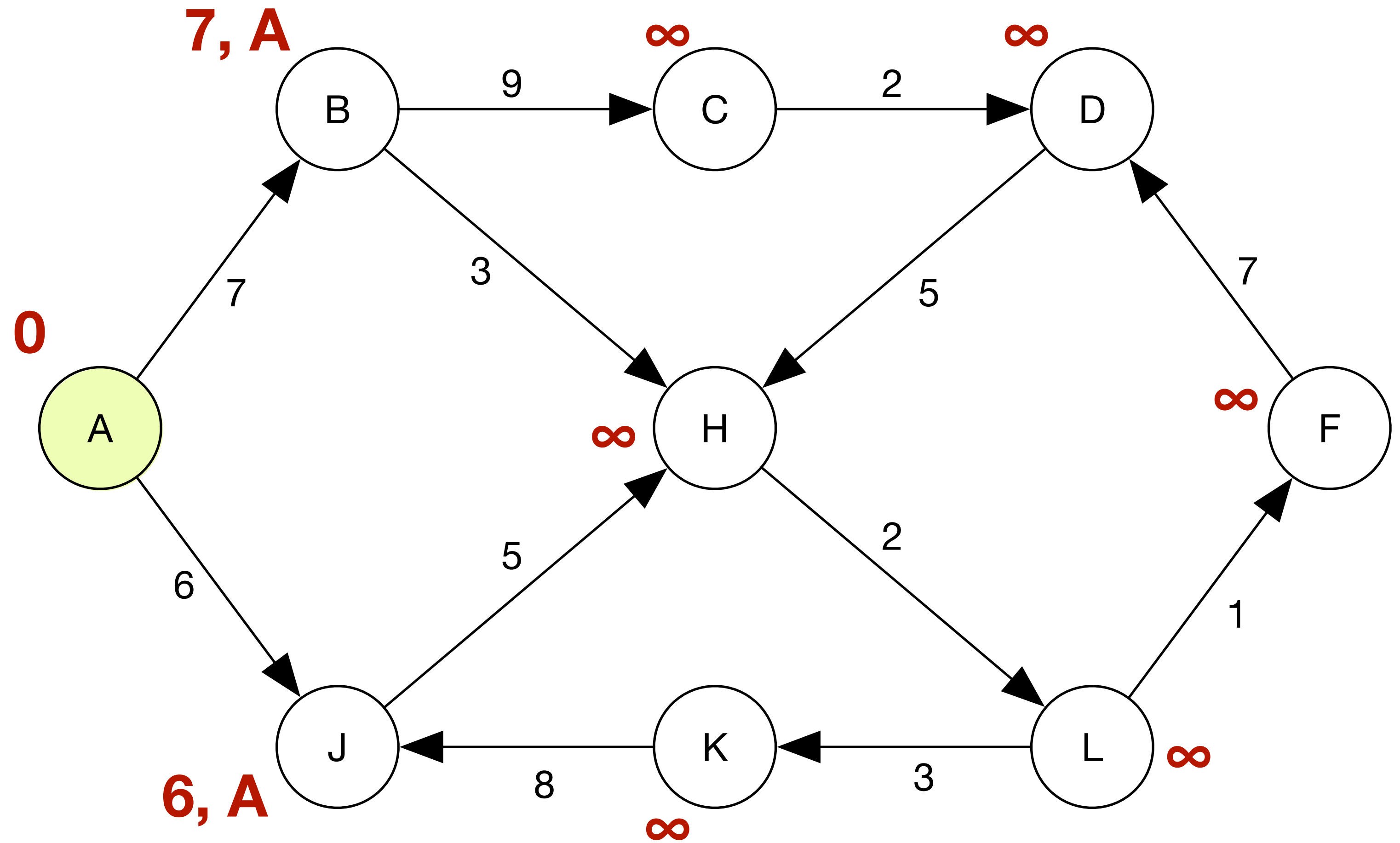
$U = \{A, B, C, D, F, H, J, K, L\}$



# Dijkstra

Unvisited set

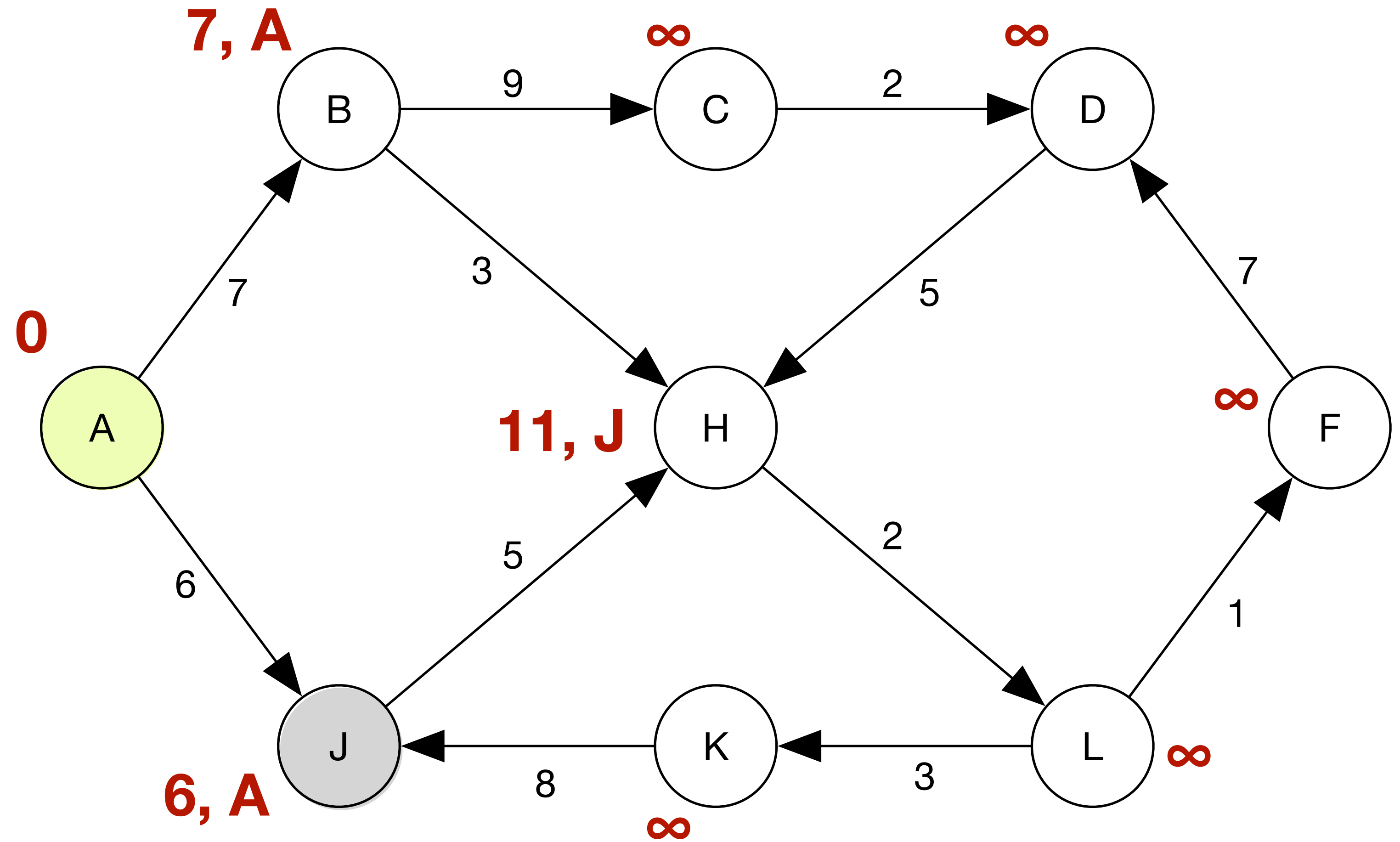
$U = \{A, B, C, D, F, H, J, K, L\}$



# Dijkstra

Unvisited set

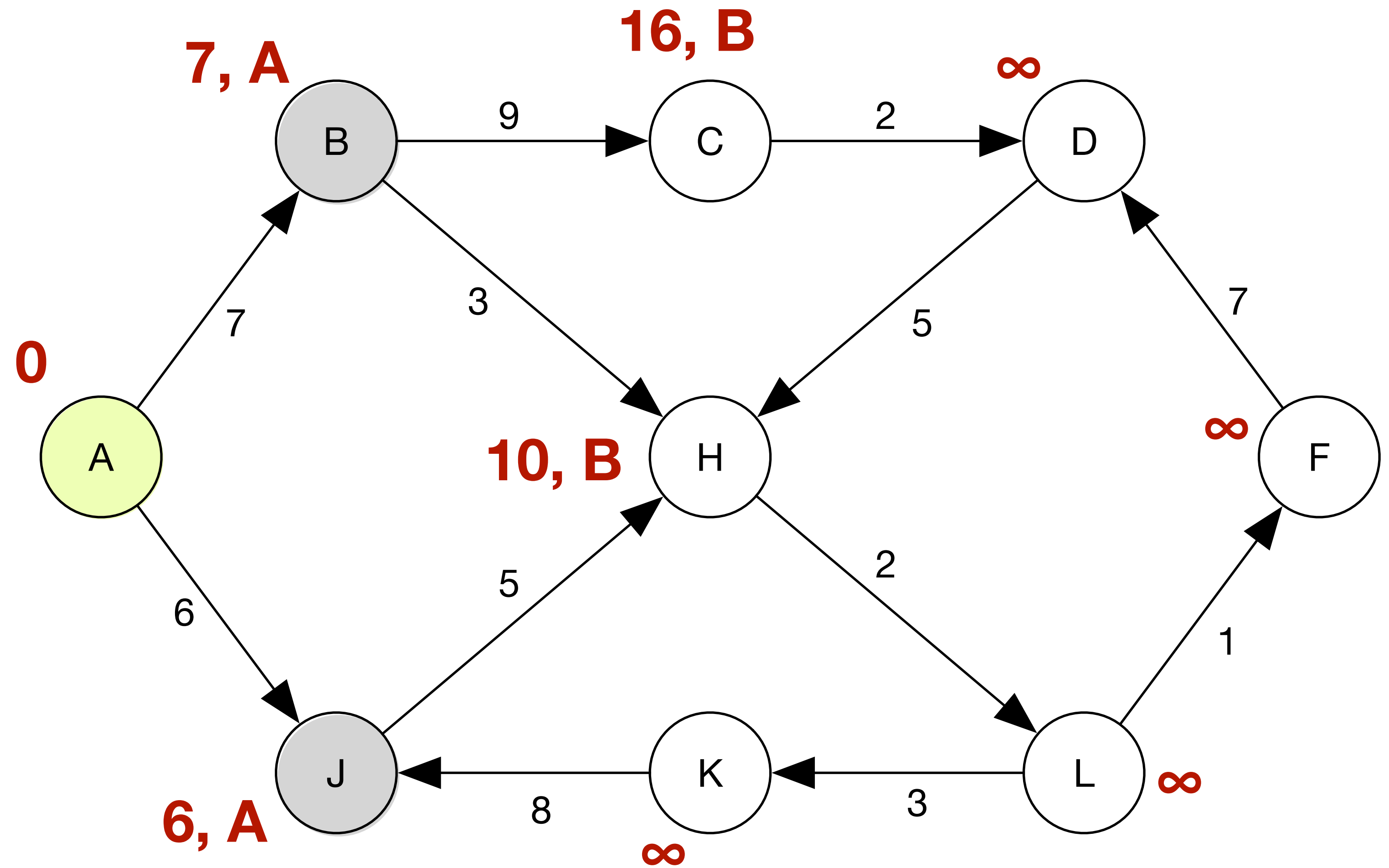
$U = \{B, C, D, F, H, K, L\}$



# Dijkstra

Unvisited set

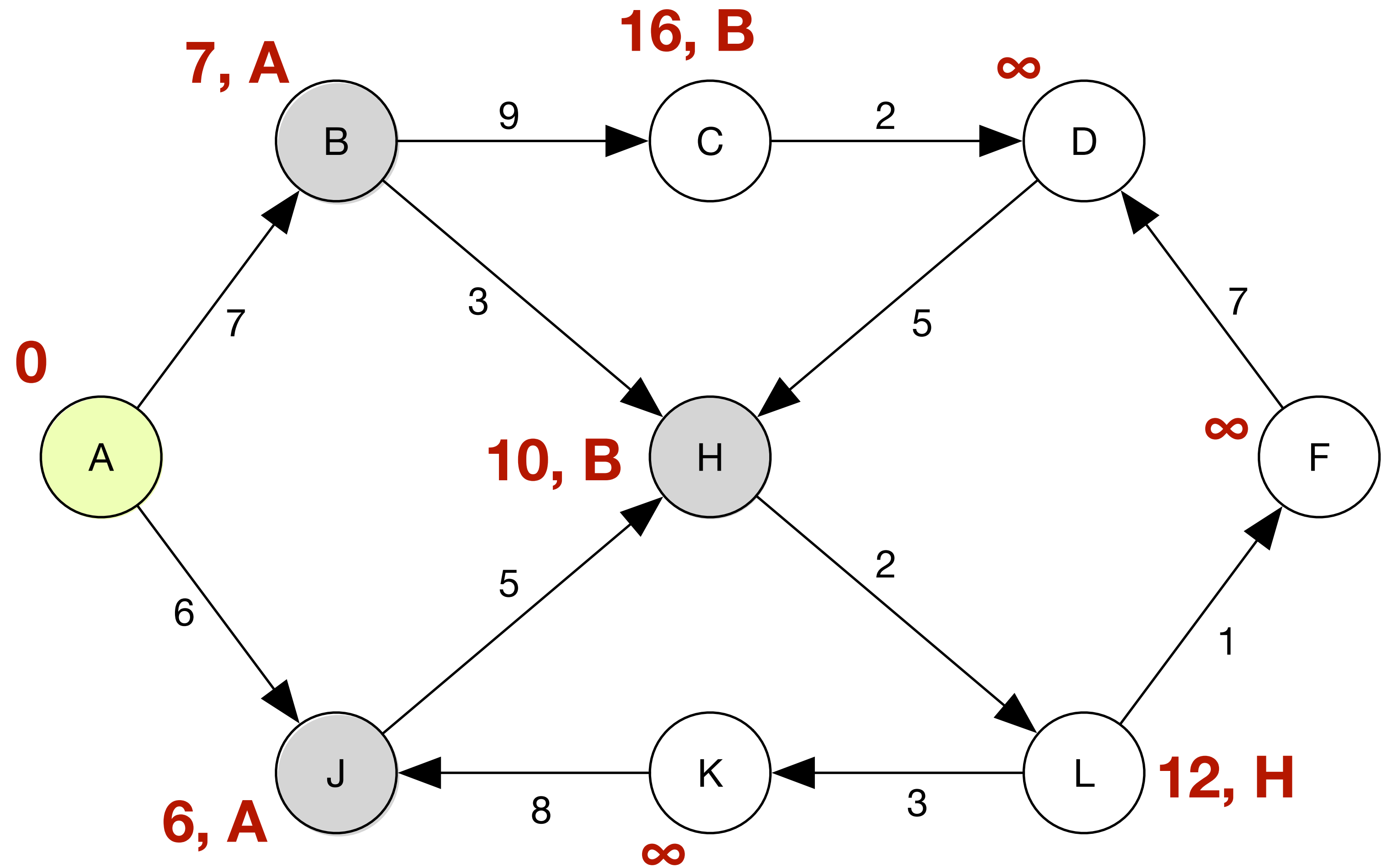
$U = \{C, D, F, H, K, L\}$



# Dijkstra

Unvisited set

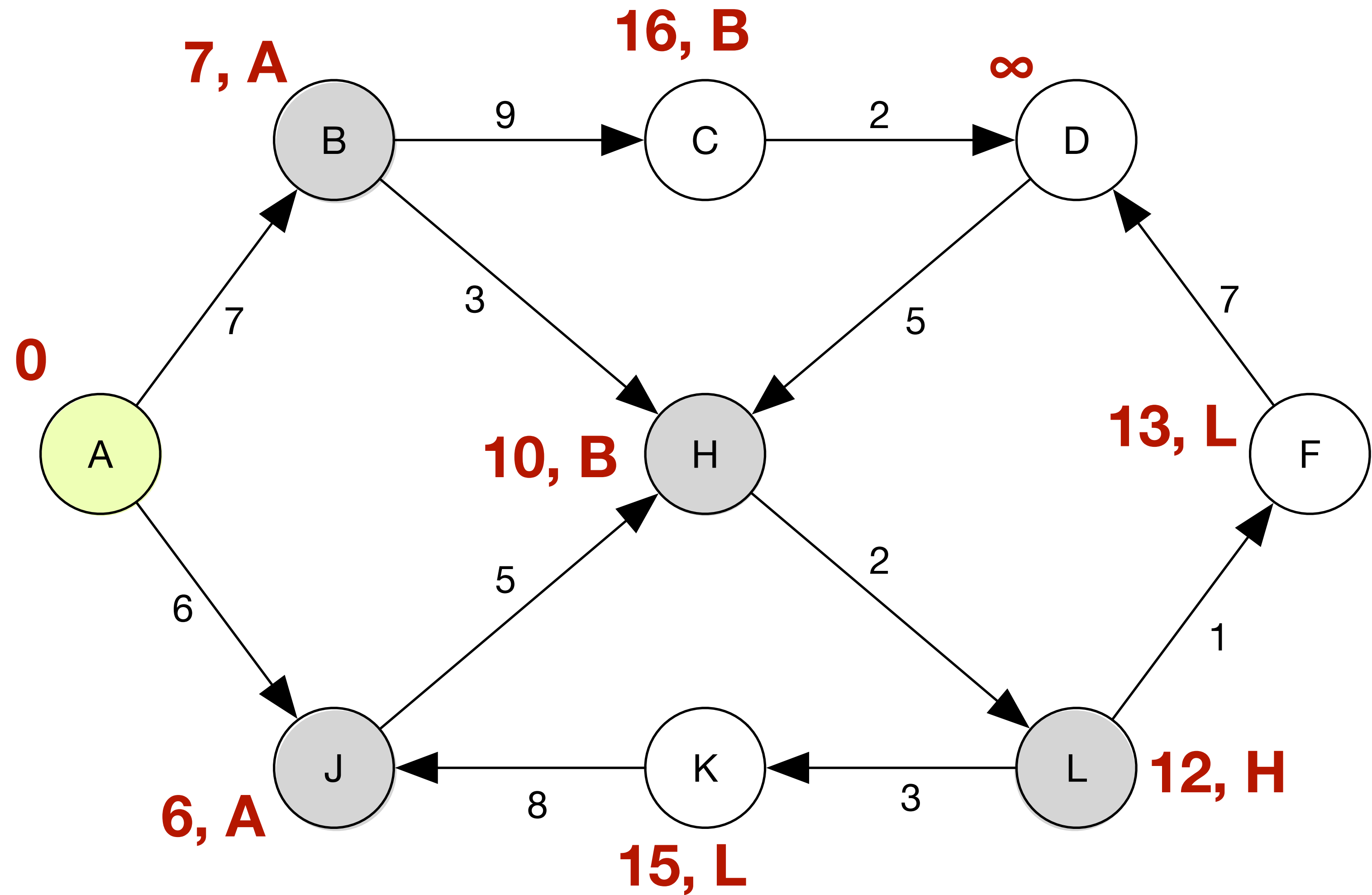
$U = \{C, D, F, K, L\}$



# Dijkstra

Unvisited set

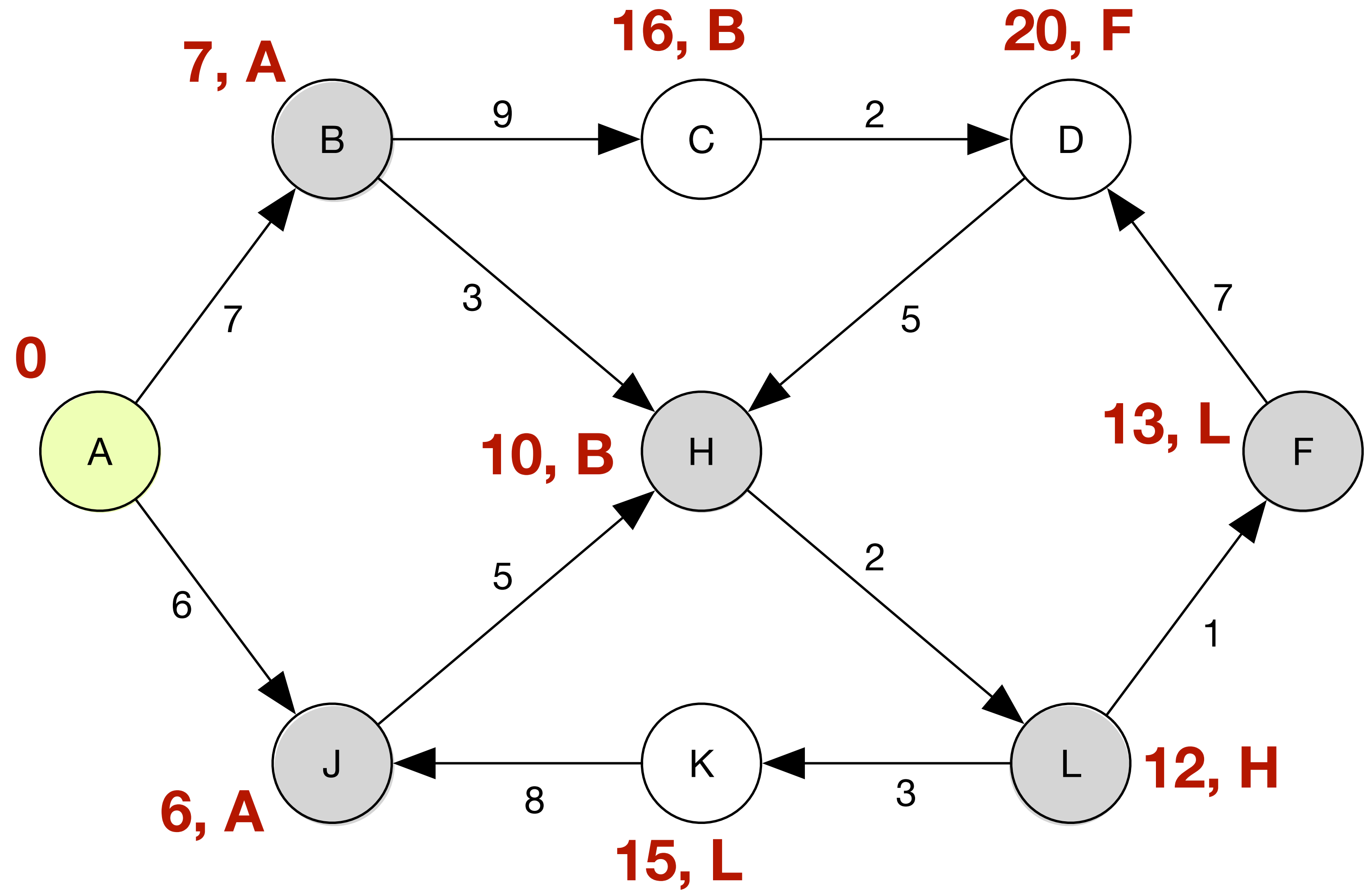
$U = \{C, D, F, K\}$



# Dijkstra

Unvisited set

$U = \{C, D, K\}$

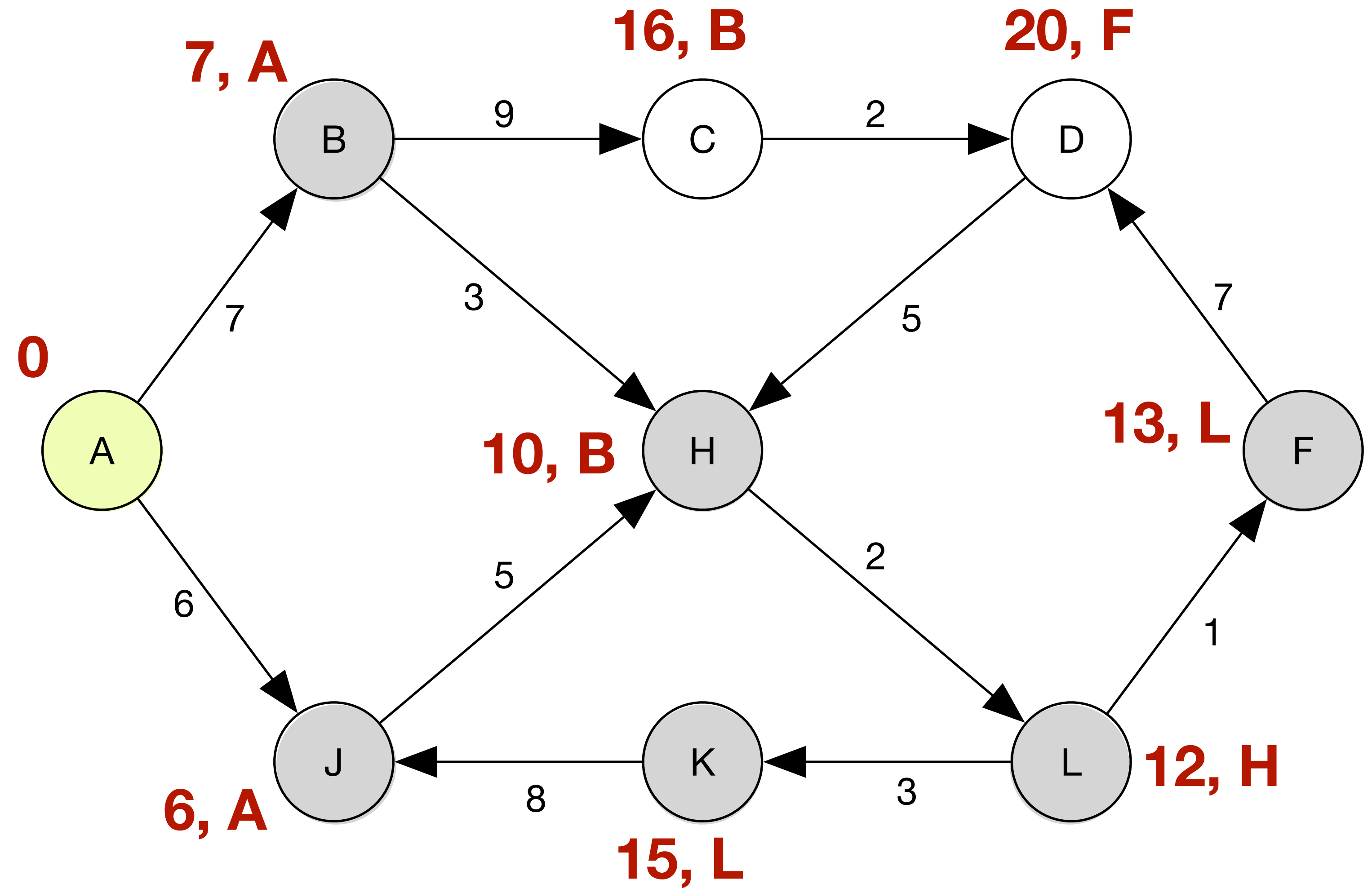




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Unvisited set

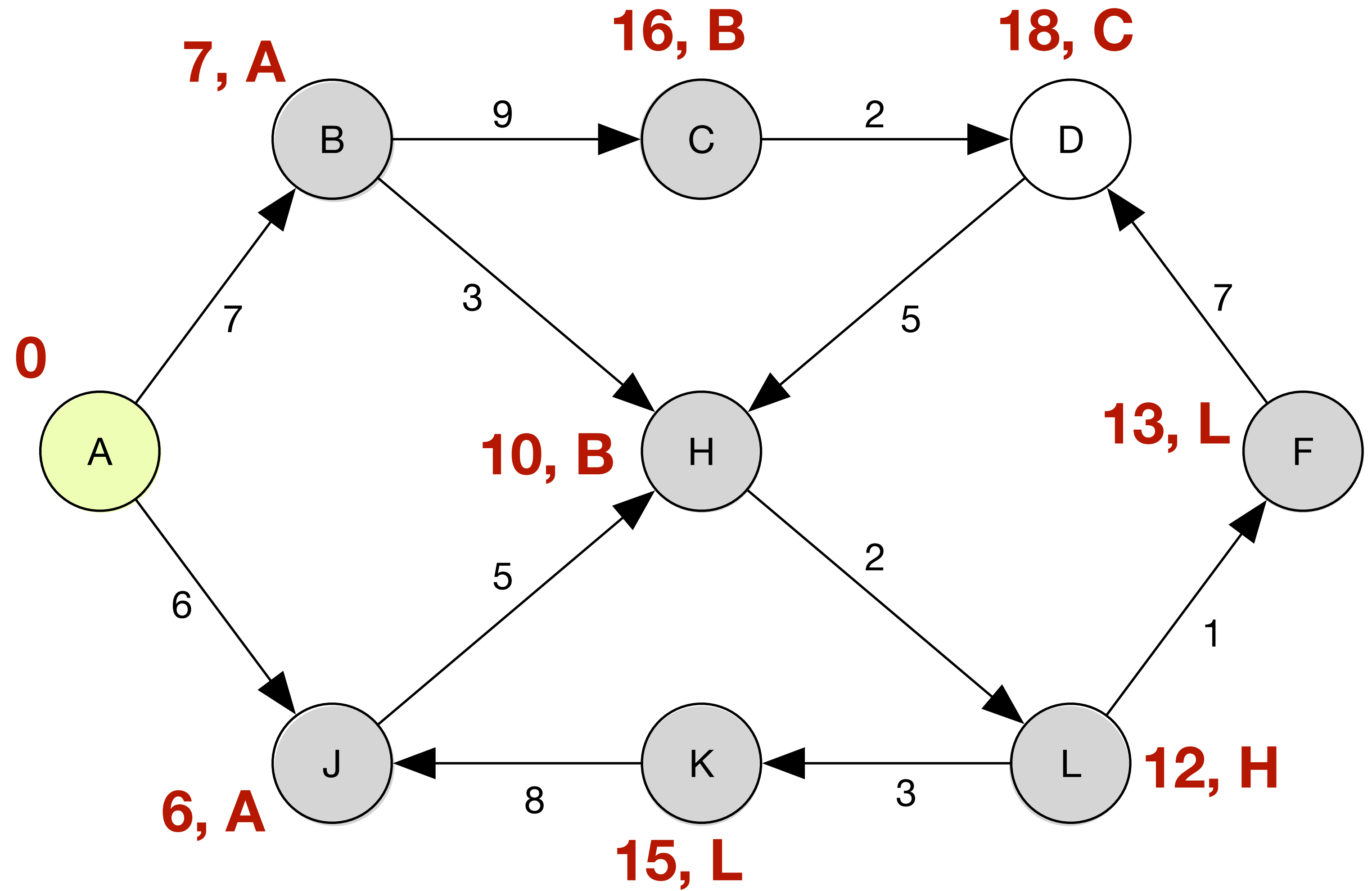
$U = \{C, D\}$



# Dijkstra

Unvisited set

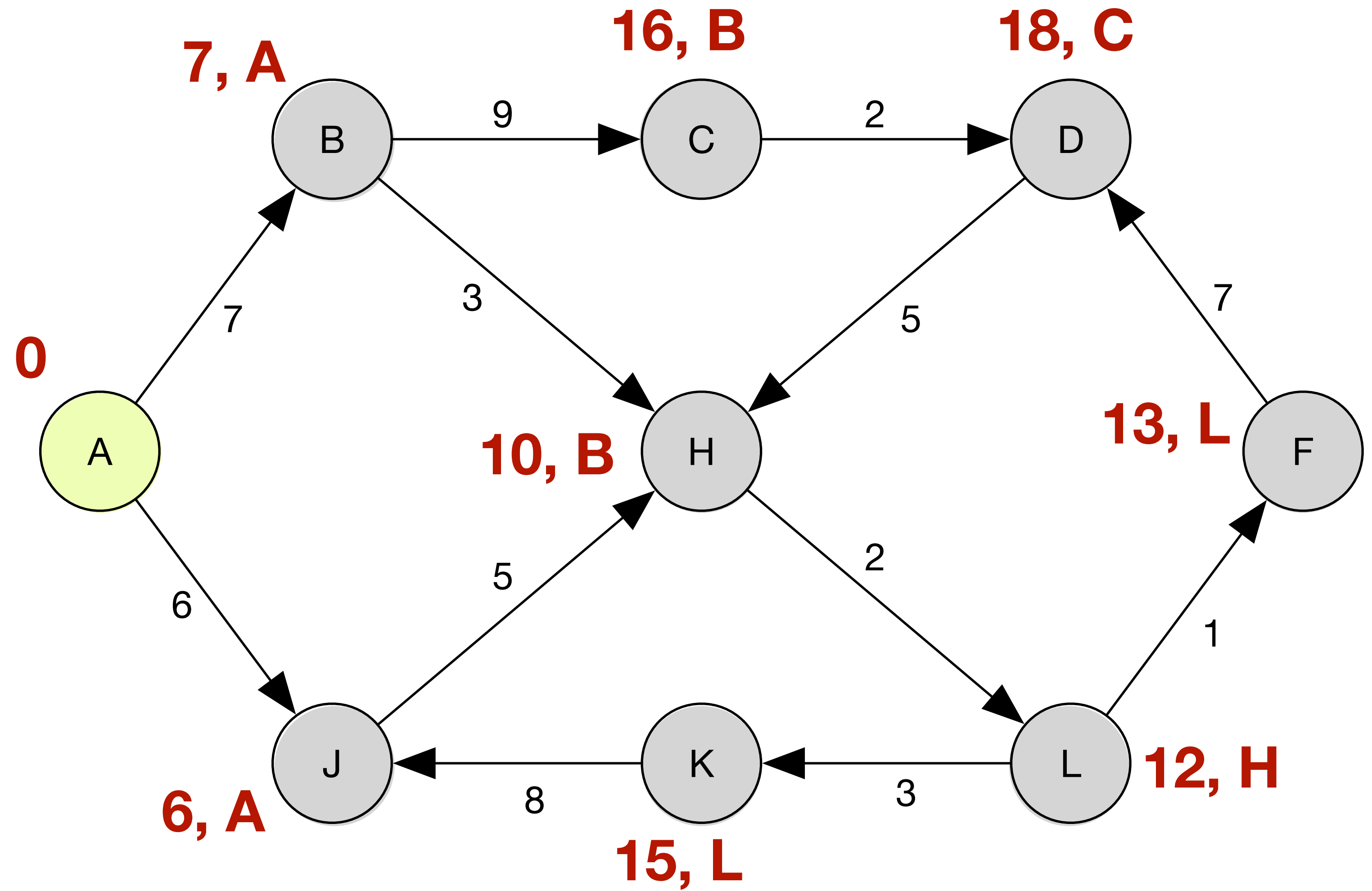
$U = \{D\}$



# Dijkstra

Unvisited set

$U = \{\}$

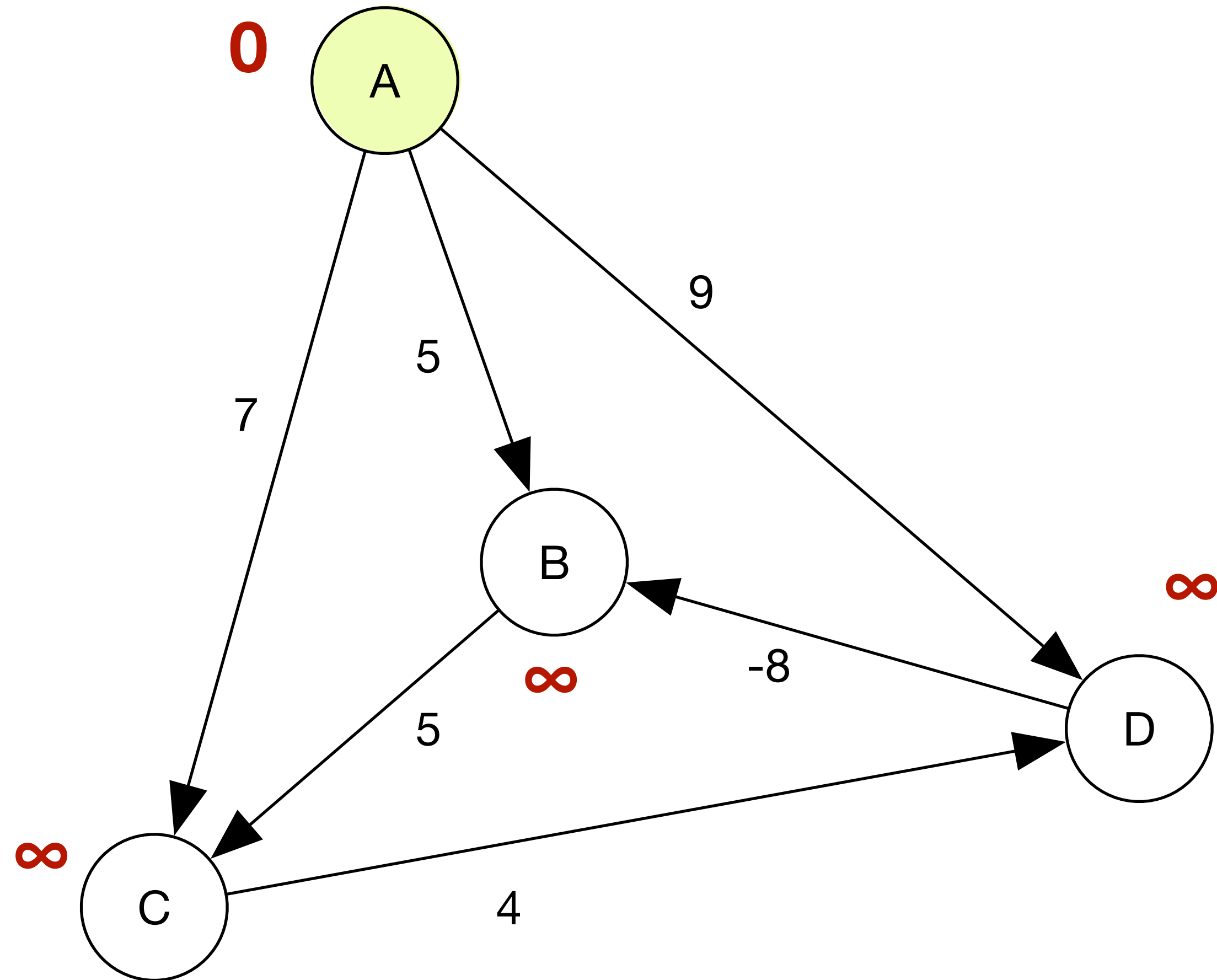


# Dijkstra's algorithm

Why doesn't Dijkstra's algorithm work with negative weights?

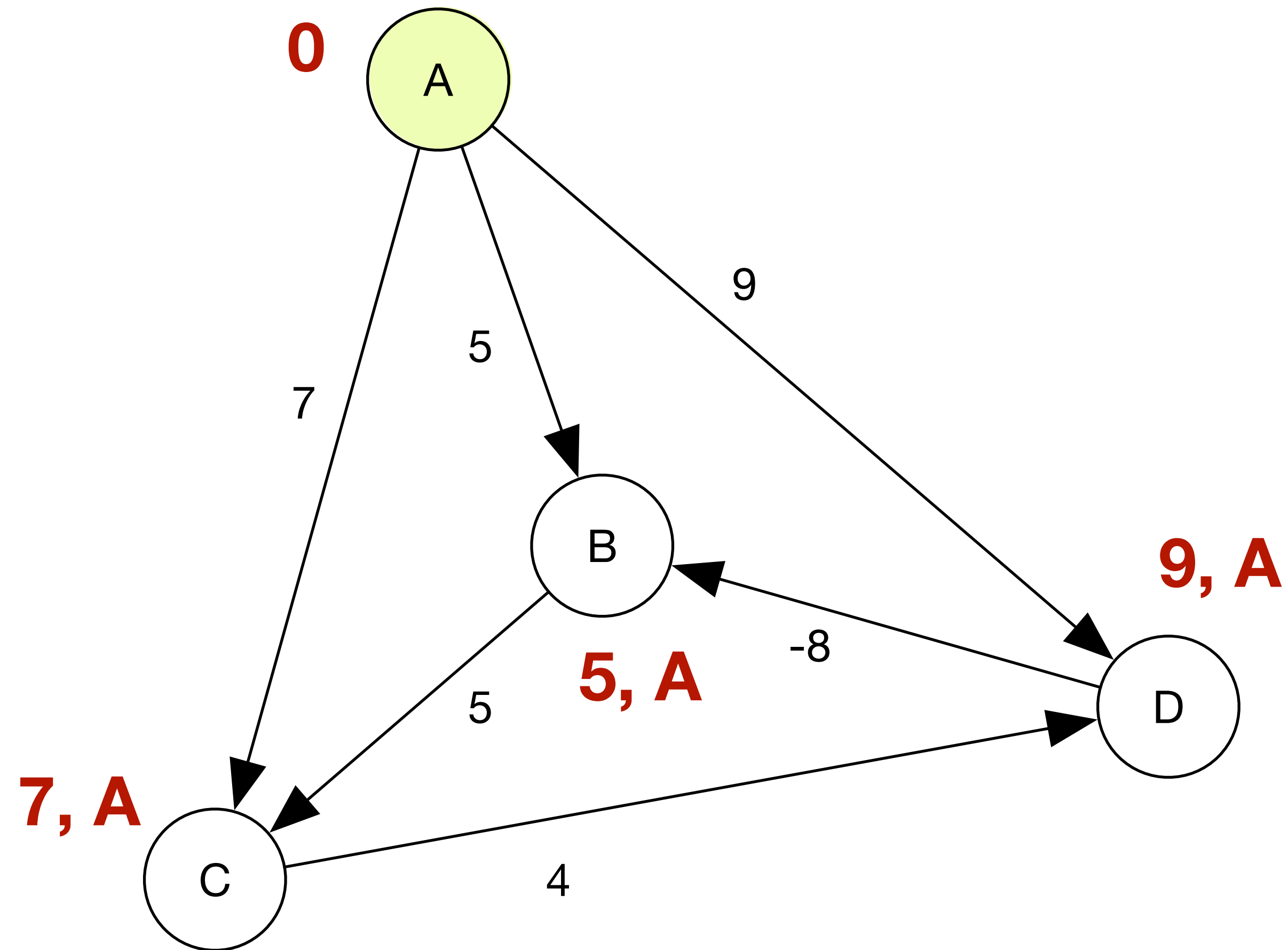
# Dijkstra's algorithm

$U = \{A, B, C, D\}$



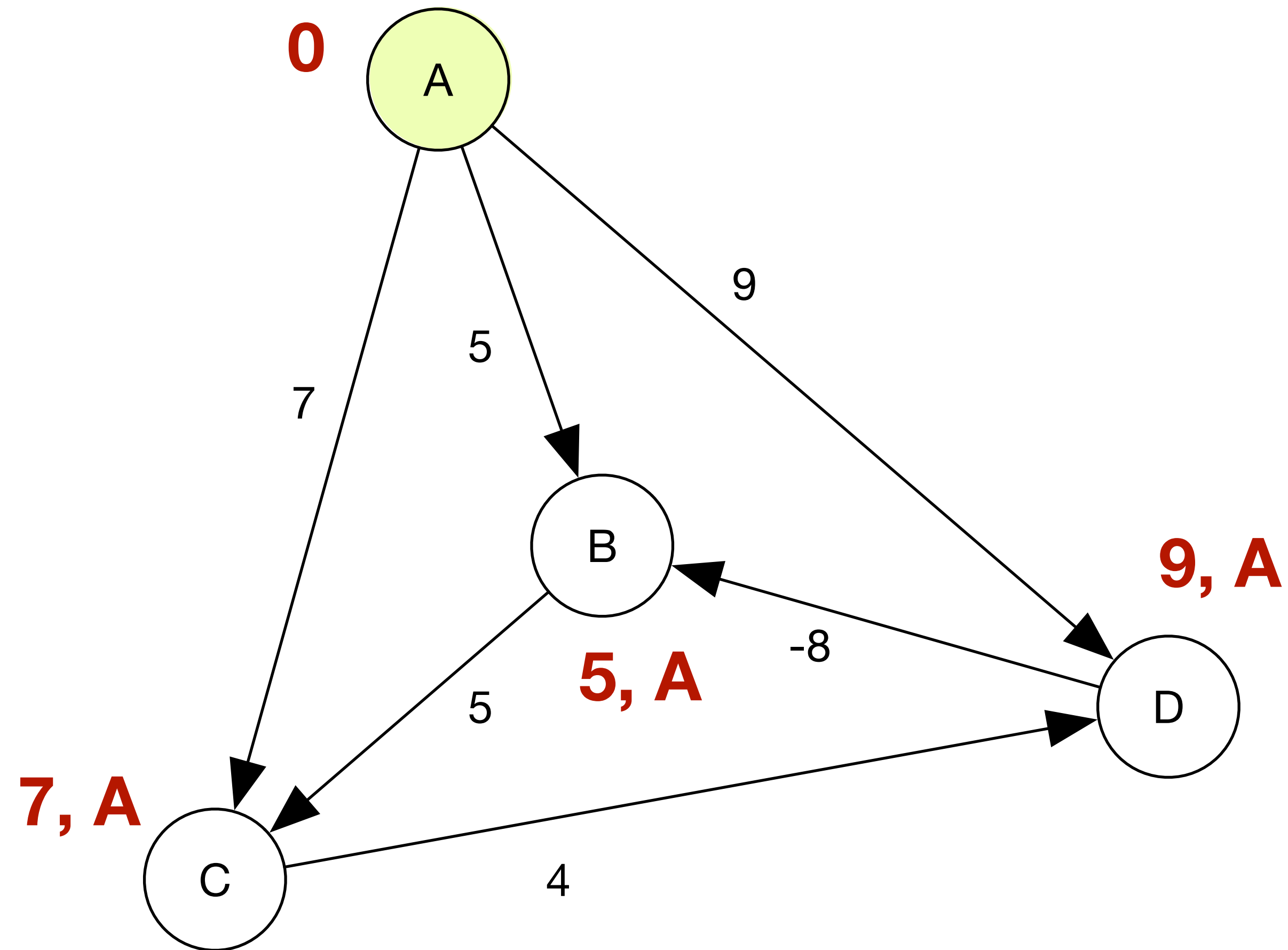
# Dijkstra's algorithm

$U = \{B, C, D\}$



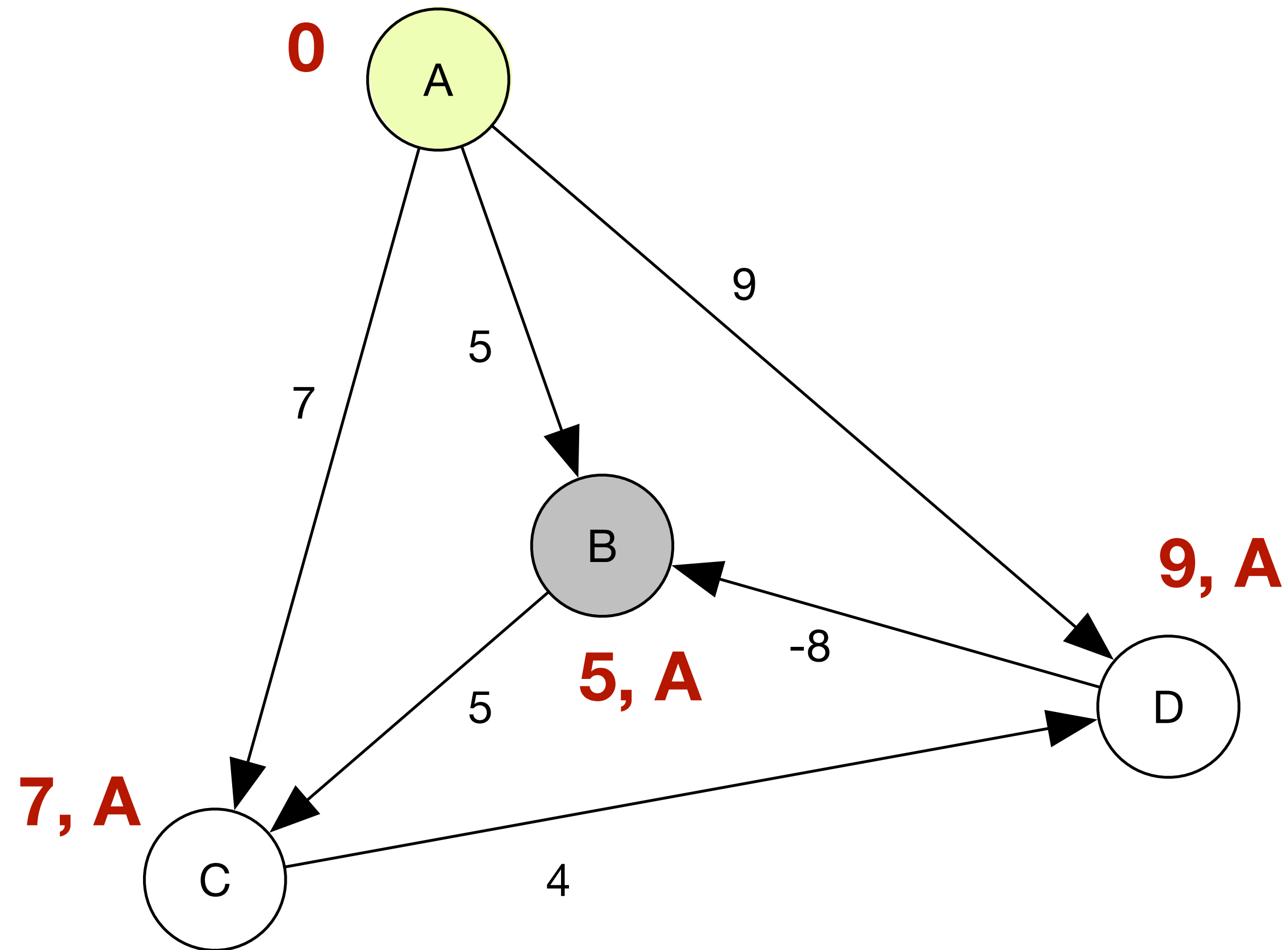
# Dijkstra's algorithm

$U = \{B, C, D\}$



# Dijkstra's algorithm

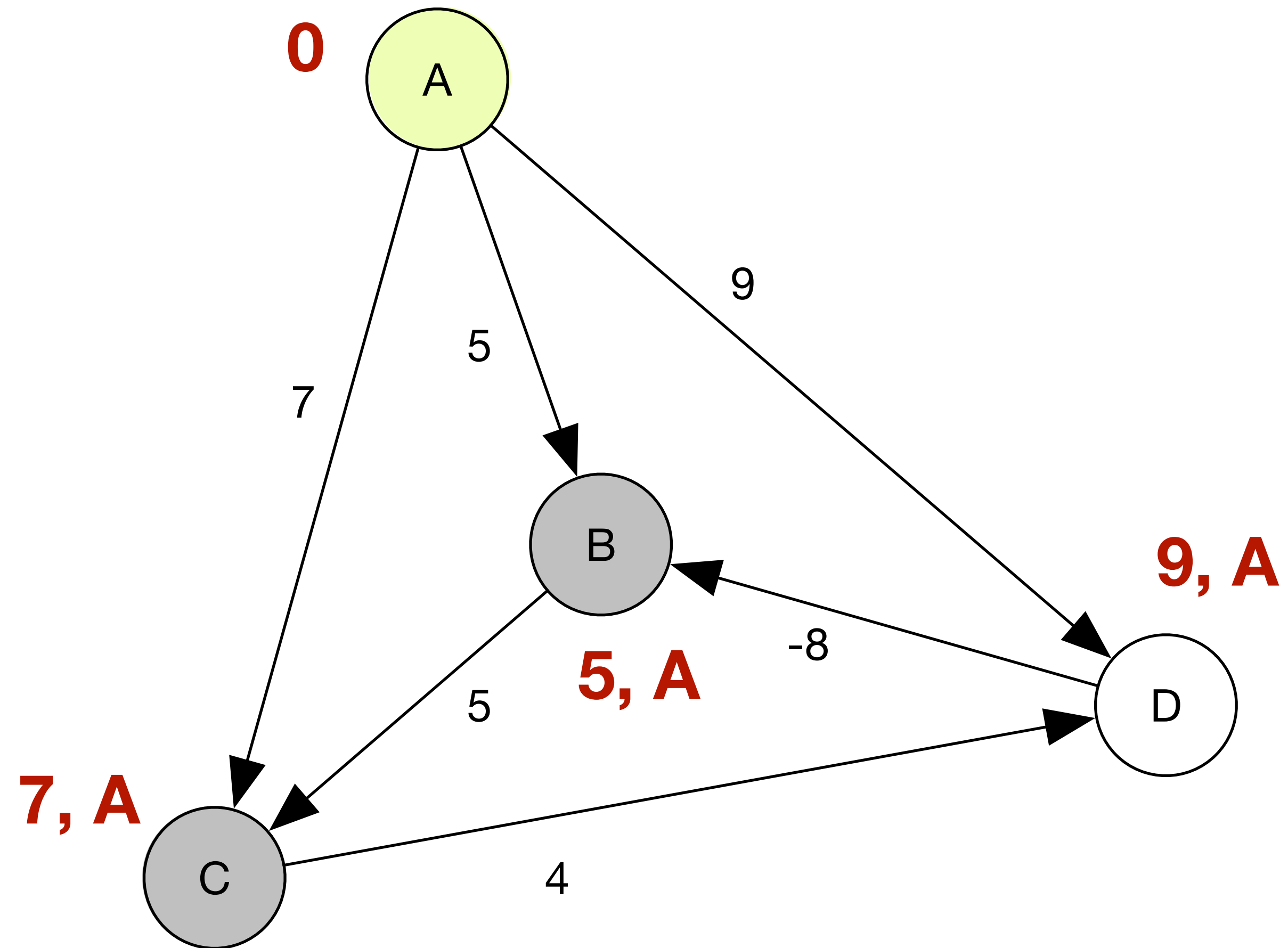
$U = \{C, D\}$





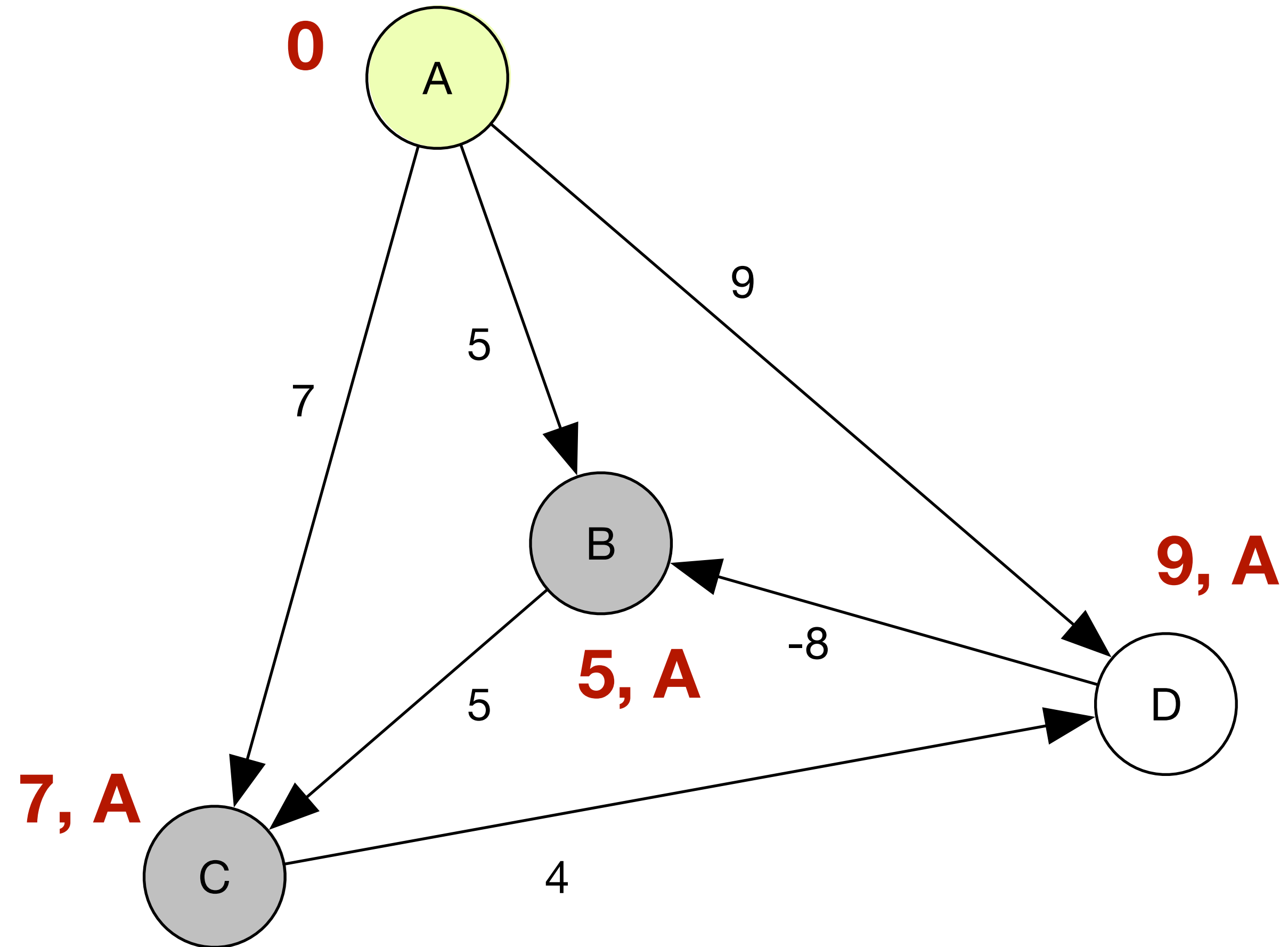
# Dijkstra's algorithm

$U = \{D\}$



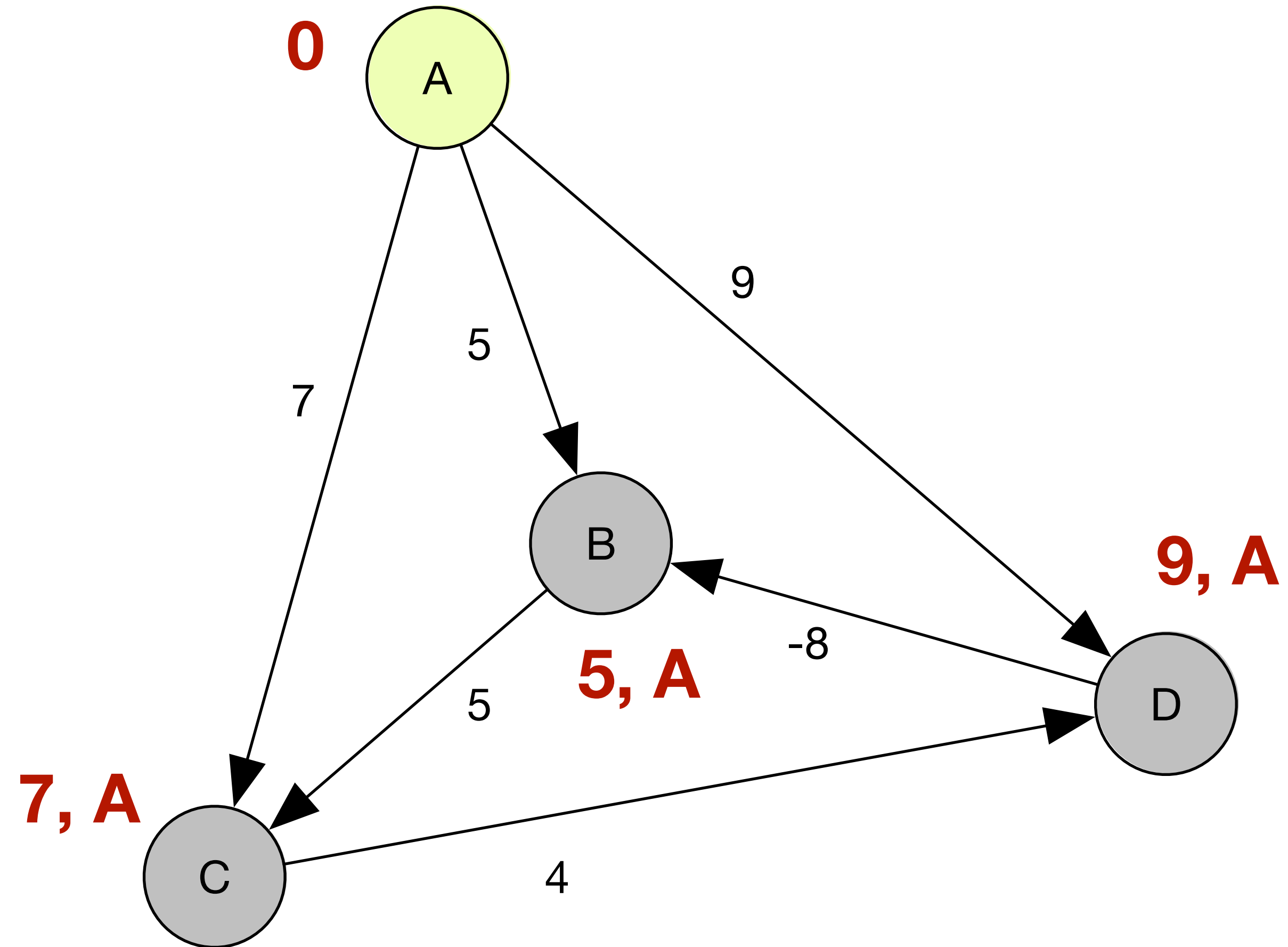
# Dijkstra's algorithm

$U = \{\}$



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$U = \{\}$

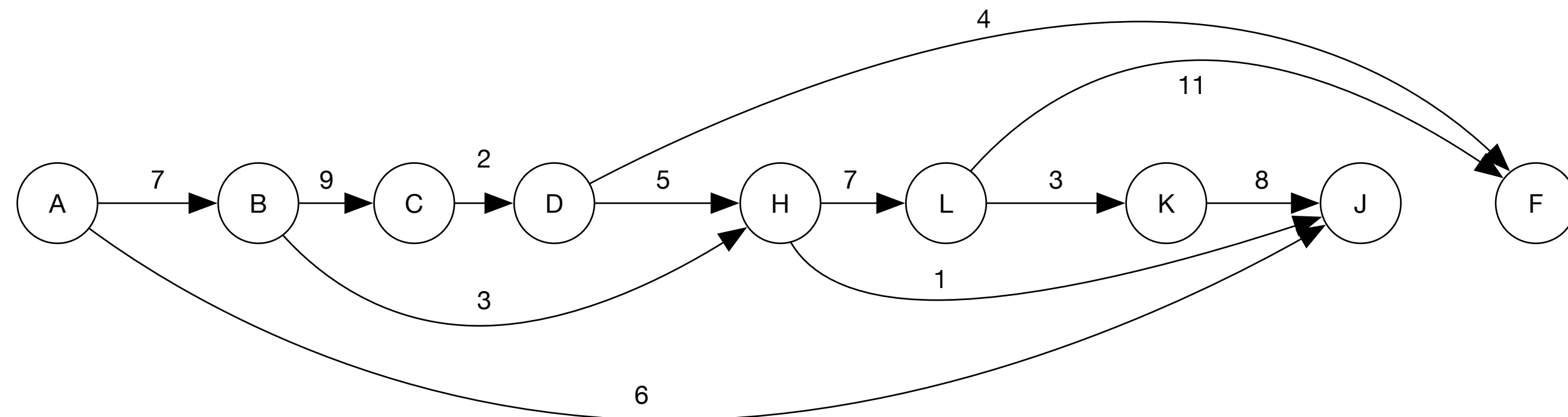
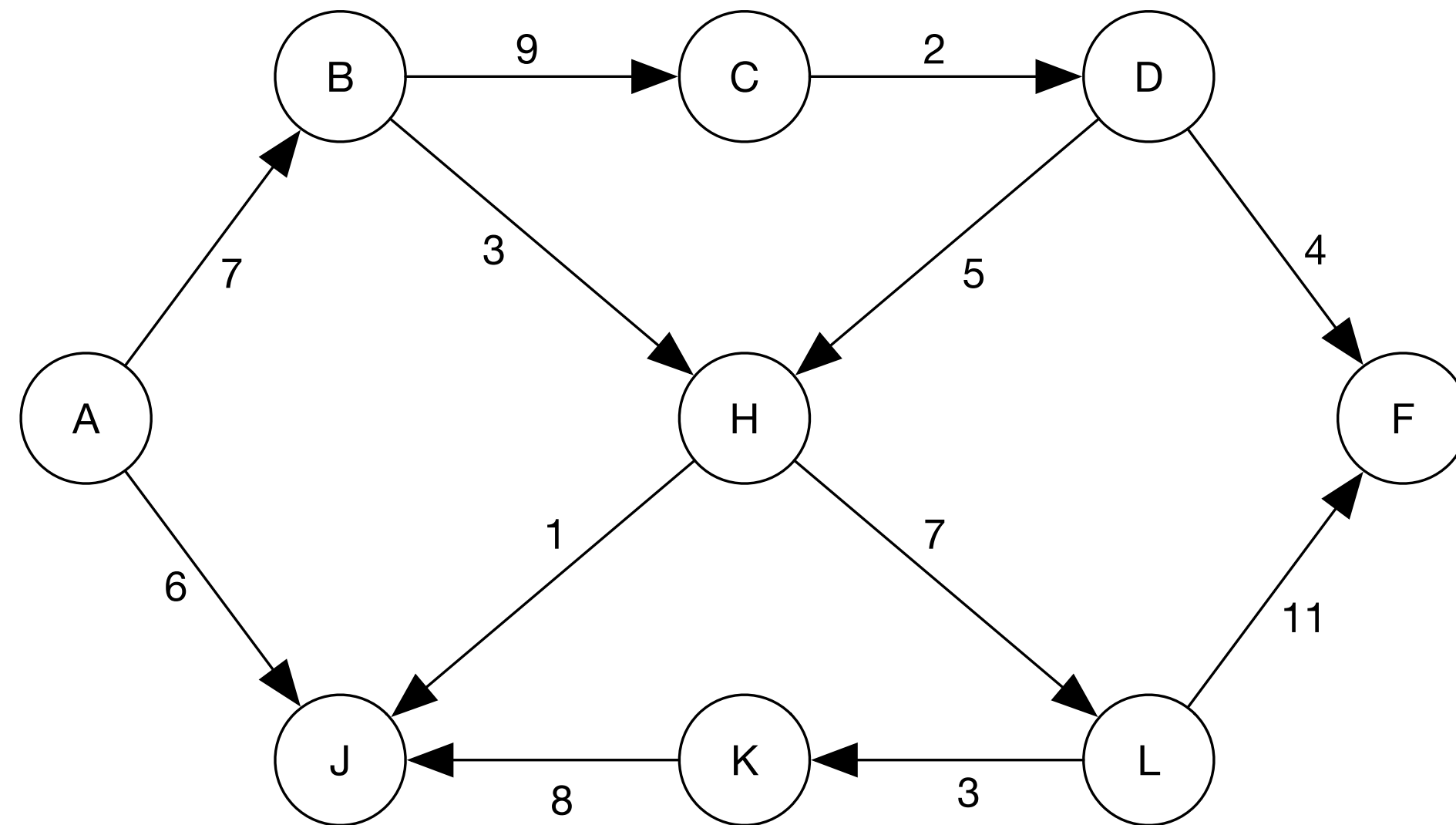


# Dijkstra's algorithm: Can we do better?

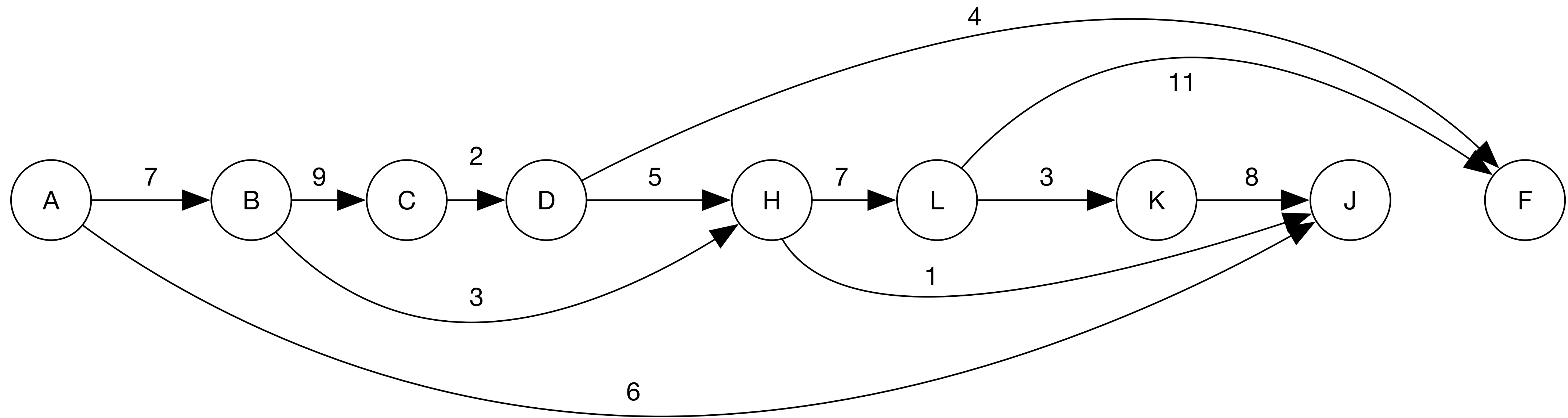
Worst case complexity (using min priority queue)

$$\mathcal{O}((|V| + |E|) \log |V|)$$

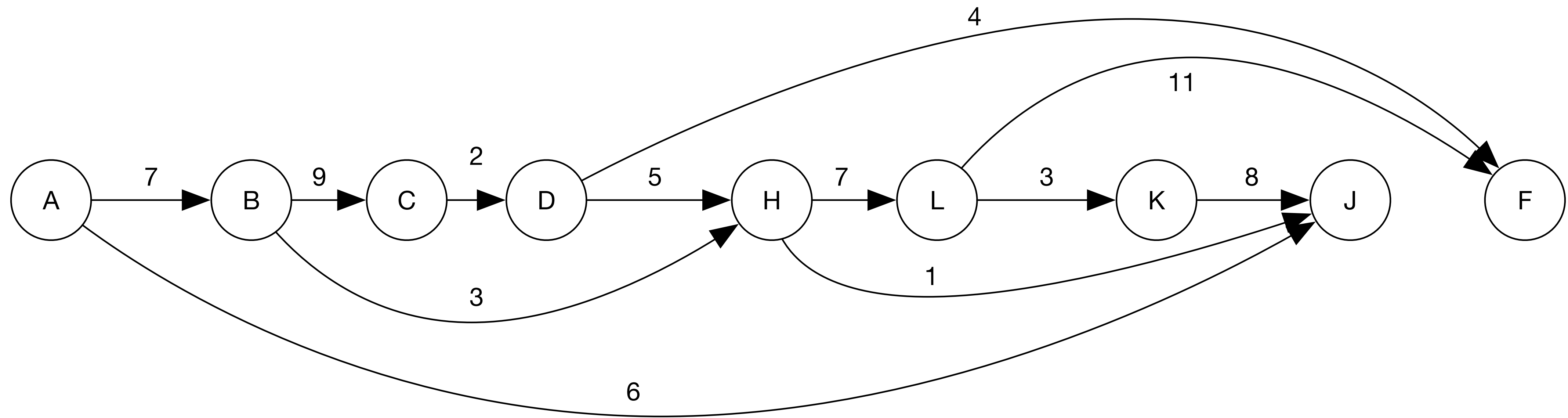
# Dijkstra's algorithm: Can we do better?



# Dijkstra's algorithm: Can we do better?



# Dijkstra's algorithm: Can we do better?



# Dijkstra's algorithm

Worst case complexity directed graph with cycles (using min priority queue)

$$\mathcal{O}((|V| + |E|) \log|V|)$$

Worst case complexity directed acyclic graph (using topological sort)

$$\mathcal{O}(|V| + |E|)$$



# Dijkstra's algorithm

Greedy approach. Grab the best answer so far; never backtrack.

Dynamic programming. Save partial solutions along the way and reconstruct complete solutions from the partial solutions.

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What to do about negative weights?

# Dijkstra's algorithm

Greedy approach. Grab the best answer so far; never backtrack.

Dynamic programming. Save partial solutions along the way and reconstruct complete solutions from the partial solutions.

What to do about negative weights? Bellman-Ford algorithm.